YAŞAR UNIVERSITY
GRADUATE SCHOOL OF NATURAL AND APPLIED SCIENCES

MASTER THESIS

## A STUDY ON UNIFORM PARALLEL

## MACHINE SCHEDULING

## WITH SEQUENCE DEPENDENT SETUP TIMES

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# ABSTRACT <br> A STUDY ON UNIFORM PARALLEL MACHINE SCHEDULING WITH SEQUENCE DEPENDENT SETUP TIMES 

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Scheduling problems are essential for decision-making in many academic disciplines, including operations management, computer science, and information systems. Since many scheduling problems are NP-hard in the strong sense, there is only limited research on exact algorithms and their efficiency. This thesis considers the uniform parallel machine scheduling problem with sequence-dependent setup times to minimize the maximum completion time (makespan). We present an IP formulation, which clearly describes our problem and can be used to obtain optimal solutions for small-sized problems. As our problem is NP-hard, we propose a randomized heuristic with an improvement subroutine. The performance of the proposed heuristic through a computational study was tested with 320 instances. We created these instances using the full factorial design of experiment (DOE) with five different factors. Our computational study indicates that the proposed mathematical model takes 22.88 minutes on average, and the heuristic algorithm achieves these results only in 0.062 minutes. The average solutions obtained with the heuristic have an approximately $4 \%$ Gap value for average CPLEX solutions. Also, the contribution of the improvement subroutine step to the overall performance of the heuristic is $73.34 \%$.
keywords: parallel machine scheduling, sequence-dependent setup time, full factorial design, randomized heuristic, uniform machines, total completion times


# SIRAYA BAĞIMLI KURULUM SÜRELERİ İLE TEK TiP PARALEL makiñ çizelgelemesí Üzerinn bir çalişma 

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Çizelgeleme problemleri; operasyon yönetimi, bilgisayar bilimi ve bilgi sistemleri dahil olmak üzere birçok akademik disiplinde karar vermek için gereklidir. Çoğu çizelgeleme problemi güçlü anlamda NP-zor olduğundan, kesin algoritmalar ve verimliliklerinin nasıl ölçeklendiği konusunda sınırlı araştırma vardır. Bu çalışmada, maksimum tamamlama süresini en aza indirmek için sıraya bağlı kurulum süreleriyle tek tip paralel makine çizelgeleme problemini ele alıyoruz. Problemimizi açık bir şekilde tanımlayan ve küçük boyutlu problemler için en uygun çözümleri elde etmek için kullanılabilecek bir tam sayılı problem formülasyonu sunuyoruz. Sonrasında, problemimiz NP-zor olduğundan, iyileştirme alt rutini ile rastgele bir buluşsal yöntem öneriyoruz. Hesaplamalı bir çalışma yoluyla önerilen sezgisel yöntemin performansı 320 örnekle test edilmiştir. Bu örnekleri, beş farklı faktörlü deneyin tam faktöriyel tasarımını (DOE) kullanarak oluşturduk. Hesaplamalı çalışmamız, önerilen matematiksel modelin ortalama 22.88 dakika sürdüğünü ve sezgisel algoritmanın bu sonuçları yalnızca 0.062 dakikada elde ettiğini göstermektedir. Sezgisel yöntem sonuçları ile matematiksel model sonuçları karşılaştırıldığında, CPLEX yazıımında yapılan sezgisel yöntem ortalama olarak yaklaşık \%4 Gap değerine sahiptir. Ayrıca, iyileştirme adımının sezgisel yöntemin genel performansına katkısı \% 73,34 'tür.

Anahtar Kelimeler: paralel makine çizelgelemesi, sıraya bağlı kurulum süresi, tametkenli tasarım, sezgisel yöntem, tek tip makine, toplam tamamlanma süresi


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Beste Yıldiz
İzmir, 2022


## TEXT OF OATH

I declare and honestly confirm that my study, titled "A STUDY ON UNIFORM PARALLEL MACHINE SCHEDULING WITH SEQUENCE DEPENDENT SETUP TIMES" and presented as a Master's Thesis, has been written without applying to any assistance inconsistent with scientific ethics and traditions. I declare, to the best of my knowledge and belief, that all content and ideas drawn directly or indirectly from external sources are indicated in the text and listed in the list of references.


## TABLE OF CONTENTS

ABSTRACT ..... v
ÖZ. ..... vii
ACKNOWLEDGEMENTS ..... ix
TEXT OF OATH ..... xi
TABLE OF CONTENTS ..... xiii
LIST OF FIGURES ..... xv
LIST OF TABLES ..... xvii
SYMBOLS AND ABBREVIATIONS ..... xix
CHAPTER 1 INTRODUCTION ..... 1
CHAPTER 2 LITERATURE REVIEW ..... 8
2.1. Parallel Machines .....  8
2.1.1. Identical Parallel Machine ..... 9
2.1.2. Unrelated Parallel Machine ..... 13
2.1.3. Uniform Parallel Machine ..... 20
CHAPTER 3 PROBLEM DESCRIPTION \& ANALYSIS ..... 22
CHAPTER 4 COMPUTATIONAL STUDY ..... 31
CHAPTER 5 CONCLUSIONS AND FUTURE RESEARCH ..... 37
REFERENCES ..... 39
APPENDIX 1 - CPLEX Solutions for All Instances ..... 47
APPENDIX 2 - Heuristic Solutions for All Instances with Reputation Times ..... 55
APPENDIX 3 - Comparison for Initial Heuristic and Improved Heuristic Solutions ..... 63


## LIST OF FIGURES

Figure 1.1. A Classification of Scheduling Problems - Part 1 ..... 2
Figure 1.2. A Classification of Scheduling Problems - Part 2 ..... 2
Figure 1.3. The Parallel Machine Environment ..... 3
Figure 1.4. Parallel Machine Scheduling with Setup Time Illustration. ..... 4
Figure 3.1. Schedule in Identical Parallel Machine for Example 1 ..... 23
Figure 3.2. Schedule in Uniform Parallel Machine for Example 1 ..... 24
Figure 3.3. Pseudo-Code of the Randomized Heuristic ..... 27
Figure 3.4. Gannt Charts for Heuristic Example ..... 29
Figure 4.1. Combinations for 3 Machines ..... 31
Figure 4.2. Combinations for 5 Machines ..... 31


## LIST OF TABLES

Table 1.1. Field Indicators for the Problem Identifier Triplet of Scheduling Problems ..... 6
Table 1.2. Abbreviations of The Solution Methods of Scheduling Problems ..... 7
Table 2.1. Literature Review for Identical Parallel Machine ..... 12
Table 2.2. Literature Review for Unrelated Parallel Machine ..... 18
Table 2.3. Literature Review for Uniform Parallel Machine ..... 21
Table 3.1. Processing Times for Example 1 ..... 22
Table 3.2. Setup Time Matrix for Example 1 ..... 23
Table 3.3. Processing Times and Job Index for Heuristic Example ..... 28
Table 3.4. Setup Time Matrix for Heuristic Example ..... 28
Table 4.1. Testbed for the Computational Study ..... 32
Table 4.2. Average CPLEX and Heuristic Solutions ..... 33
Table 4.3. CPLEX - Average Solutions ..... 34
Table 4.4. Heuristic - Average Solutions ..... 34
Table 4.5. Mean of Heuristic \% Gap ..... 35
Table 4.6. Median of Heuristic \% Gap ..... 35
Table 4.7. \% Gap Deviation for All Instances ..... 35


## SYMBOLS AND ABBREVIATIONS

| ABBREVIATIONS: |  |
| :---: | :---: |
| PMSP | Parallel Machine Scheduling Problem |
| UPMSP | Uniform Parallel Machine Scheduling Problem |
| SDSP | Sequence Dependent Setup Time |
| IP | Integer Programming |
| P | Identical Machines |
| $R$ | Unrelated Machines |
| $Q$ | Uniform Machines |
| SYMBOLS: |  |
| $N$ | Number of jobs to be processed. |
| M | Number of uniform parallel machines. |
| $i, j$ | Jobs. |
| $k$ | Machines. |
| $C_{i}$ | Completion time of job $i$. |
| $C_{\text {max }}$ | Minimize the maximum completion time (makespan). |
| $v_{k}$ | Processing speed of mackine $k$. |
| $p_{i}$ | Processing time for job $i$ at the base speed. |
| $p_{i k}$ | Processing time for job $i$ on machine $k$. |
| $s_{i j}$ | Setup time of job $j$ immediately after job $i$ at the base speed |
| $s_{i j k}$ | Setup time of job $j$ immediately after job $i$ on machine $k$. |
| $L$ | A large number. |



## CHAPTER 1

## INTRODUCTION

This thesis investigates the fundamental properties of a class of scheduling models commonly used in industrial engineering. Unlike most studies that develop extensions to known models, approaches, or techniques, the emphasis here is to gain insight and understanding. As a direct result of our aspirations, much research was needed before finally developing the ideas presented here. This work considers a uniform parallel machine scheduling problem with sequence-dependent setup times to minimize the maximum completion times (makespan). Tens of thousands of papers addressing different scheduling problems have appeared in the literature since the first systematic approach to scheduling problems was undertaken in the mid-1950s. In this way, parallel machine scheduling problems have an important place in the literature among machine scheduling problems. On the contrary, work on the uniform parallel machine scheduling problem with sequence-dependent setup time is quite limited. We aim to add value by shedding light on this point.

Pinedo (2012) described scheduling as a decision-making process of assigning jobs to resources in a particular order to meet one or more objectives. Also, Allahverdi (2015) stated that scheduling problems can be classified based on the number of stages for jobs to be processed, the number of machines in each stage, job processing requirements, setup time or cost requirements, and the performance metrics to be optimized. Scheduling means determining which jobs can be processed by which machines in what order within a certain period for purposes set, such as ensuring that products are delivered to customers when promised, more efficient use of production resources, and minimization of the total completion time in a manufacturing environment. Ying and Liao (2004) mentioned that efficient scheduling is one of the most critical issues in manufacturing and services in today's competitive industrial world. In addition to the industrial field, other areas benefited from scheduling, such as education, agriculture, transportation, or health research.

Behnamian (2015) stated that scheduling problems are first divided into two classes according to the nature of the problem. The first of these classes is deterministic problems in which the processing constraints and parameters can be ascertained with certainty. The second class is the uncertain scheduling problems in which some processing conditions or parameters cannot be determined in advance. In this context, the uncertain scheduling problems are divided into three types, considering the method of definition of uncertainty. The first one is a fuzzy scheduling problem in which the processing conditions and parameters are modeled using fuzzy numbers. The second one is the stochastic scheduling problem that the stochastic variable is used to specify the processing constraints and parameters. The third one is robust scheduling. Robust approaches aim to create solutions that can absorb some level of the unexpected event without rescheduling. Also, all scheduling problems are classified into five parts. These parts are single machine, parallel machine, flow shop, job shop, and lastly, open shop. In our thesis, we focus on parallel machine scheduling problems and describe the detailed information and sub-headings on this subject in the following sections. Figure 1.1. and Figure 1.2. show the classification of scheduling problems.


Figure 1.1. A Classification of Scheduling Problems - Part 1


Figure 1.2. A Classification of Scheduling Problems - Part 2

Allahverdi (2015) indicated that in a parallel machine environment, all jobs should be done in a single operation, as in the case of a single machine environment. Also, the operation can be performed by any of $m$ machines, which means that $m$ machines are running in parallel. In other words, arriving jobs in parallel machine scheduling problems can be processed on any available machines. Each job with different characteristics has a single operation that can be performed on any machine, and job schedules can meet certain criteria based on various performance measures.

Let the number of jobs be denoted by $n$, where the index $i$ refers to a job and the number of machines in parallel by $m$, where the index $k$ refers to the machines. Each job $i$ as to be processed at one of the machines $k$ and any machine can do it. Figure 1.3. shows the general representation of this environment.


Figure 1.3. The Parallel Machine Environment

The primary work on the parallel machine scheduling problem (PMSP) is by McNaughton (1959) and dates back to the late 1950s. PMSP can be classified into three main categories: (1) identical machines $(P)$, where the processing times are the same for all machines, (2) uniform machines $(Q)$, where the machines have different speeds but each machine process at a consistent rate, (3) unrelated machines $(R)$ where the processing times are arbitrary and have no unique characteristics.

Allahverdi and Soroush (2008) described that setup time is the time it takes to prepare the necessary resource, such as people and machines, required to perform a task, job, or operation. The setup cost is the cost to set up resources before executing a task. Another necessary definition for this thesis is processing time. Processing time is the time required to process a work item. Therefore, the time taken to manufacture a product or provide a service is called processing time. It can be assigned to activities and the entire process. Steps such as reviewing an order, printing shipping labels and packing items, or delivering shipments to a customer can reduce an order's processing time.

Kopanos et al. (2009) pointed out that setup times occur in a large number of industrial and service applications, while a literature review on scheduling problems shows that more than 90 percent of the literature on scheduling problems ignores setup times. Ignoring setup times may be valid for some applications; however, it negatively affects the solution quality of some other scheduling applications. This is because the setup process is not a value-added factor. Hence, setup times need to be clearly considered when planning decisions for industry-critical topics such as increasing efficiency, eliminating waste and improving resource utilization. For the sake of a real-life example of this topic, Loveland et al. (2007) considered the scheduling problem in Dell Inc. They proposed a methodology to minimize the setup cost in the manufacturing system. As a result of this methodology, the production volume was increased by up to 35 percent, and thereby Dell Inc. has saved over $\$ 1$ million a year.


Figure 1.4. Parallel Machine Scheduling with Setup Time Illustration
Figure 1.4. illustrates a simplified example for parallel machine scheduling with setup times. There are five job types and three parallel machines in the system in the example. Jobs are assigned to machines randomly. In this example, jobs of Type 1 and 3 are processed on Machine 1, jobs of Type 2 and 4 are processed on Machine 2, and finally, the job of Type 5 is processed on Machine 3. In each machine, when job types change, a setup is required, and it is performed by a human operator and setup times are different.

Allahverdi et al. (1999) showed that there are two common types of setup (or changeover) structures in classical scheduling problems: (i) sequence-independent- the
setup times are usually added to the jobs' processing times, and (ii) sequence-dependent- the setup times depend not only on the job currently being scheduled but also on the immediate preceding job. To give a real-life example of sequencedependent setup time, Hsu et al. (2009) observed in one of his studies: In manufacturing clothes, the setup (cleaning) time required to prepare for dyeing a future job may differ depending on the colors of the incoming yarn and the color of the yarn that has just finished dyeing. Because before dyeing the yarn, the machine that processes the yarn to be dyed (dyeing tank) must be cleaned. If the previous job is black and the next job is white, the dyeing tank needs to be cleaned completely. On the other hand, if the previous job is white and the next one is black, the dyeing tank needs to be cleaned roughly. Because it is much easier in the system to switch from a light color to dark color; therefore, it requires less setup (cleaning) time when the tank is changed from white to black versus black to white. For this reason, if company owners want to reduce the completion time in the textile industry, these color changes are an important constraint for them. They should care about setup times in their production system.

Ahmarofi et al. (2017) stated that completion time in the manufacturing sector is needed to produce a product through production processes in sequence. Oyetunji (2009) showed that several performance measures are used to evaluate the quality of a schedule. Minimization of the maximum completion time (makespan), minimization of tardiness/earliness, and minimization of the total completion time (TCT) are the most common criteria for scheduling problems. Garey and Johnson (1979) pointed out that the PMSP with minimizing the makespan with two identical machines is known to be NP-hard; likewise, Tahar et al. (2006) mentioned a more complex problem with $m$ identical parallel machines and sequence-dependent setup times is also NP-hard. Therefore, heuristics algorithms providing near-optimal solutions in a reasonable runtime are advantageous. We refer the reader to Allahverdi (2015), Allahverdi et al. (1999), Allahverdi et al. (2008), and Gedik et al. (2016) for a comprehensive review of literature on solution methods for different types of PMSP.

Graham et al. (1979) presented that a triplet of notations, $\alpha / \beta / \gamma$, commonly describes a scheduling problem. The first field $(\alpha)$ relates to the machine setting. The second field $(\beta)$ describes the setup information and details of the processing characteristics, containing multiple entries. The third field $(\gamma)$ defines the performance measure.

Table 1.1. Field Indicators for the Problem Identifier Triplet of Scheduling Problems

| $\alpha$ |  | $\gamma$ |  |
| :---: | :---: | :---: | :---: |
| Notation | Description | Notation | Description |
| 1 | Single machine | $C_{\text {max }}$ | Makespan |
| $P$ | Parallel machines(identical) | $E_{\text {max }}$ | Maximum earliness |
| Q | Parallel machines(uniform) | $L_{\text {max }}$ | Maximum lateness |
| $R$ | Parallel machines(unrelated) | $T_{\text {max }}$ | Maximum tardiness |
| $F_{m}$ | m -stage flowshop | $D_{\text {max }}$ | Maximum delivery time |
| J | Job shop | TSC | Total setup/changeover cost |
| FJ | Flexible job shop | TST | Total setup/changeover time |
| 0 | Open shop | TNS | Total number of setups |
|  | $\beta$ | TEC | Total energy consumption |
| Notation | Description | $\Sigma F_{j}$ | Total flow time |
| $S T_{s i}$ | Sequence-independent setup time | $\Sigma C_{j}$ | Total completion time |
| $S C_{s d}$ | Sequence-dependent setup cost | $\Sigma E_{j}$ | Total earliness |
| $S T_{s d}$ | Sequence-dependent setup time | $\Sigma T_{j}$ | Total tardiness |
| $S T_{s i, f}$ | Sequence-independent family setup time | $\Sigma U_{j}$ | Number of tardy(late)jobs |
| $S D_{s i, f}$ | Sequence-dependent family setup time | $\Sigma w_{j} C_{j}$ | Total weighted completion time |
| $S C_{s d, f}$ | Sequence-dependent family setup cost | $\Sigma w_{j} F_{j}$ | Total weighted flow time |
| $S T_{p s d}$ | Past-sequence-dependent setup time | $\Sigma w_{j} U_{j}$ | Weighted number of tardy jobs |
| Prec | Precedence constraints | $\Sigma w_{j} E_{j}$ | Total weighted earliness |
| $r_{j}$ | Non-zero release date (ready times) | $\Sigma w_{j} T_{j}$ | Total weighted tardiness |
| $d_{j}$ | Due date | $\Sigma w_{j} T N S$ | Total weighted setup times |
| split | Job splitting | $\Sigma w_{j} W_{j}$ | Total weighted waiting time |
| $M_{j}$ | Machine eligibility | $\Sigma h\left(E_{j}\right)$ | Total earliness penalties |
| $S$ | Single Server | $\Sigma h\left(T_{j}\right)$ | Total tardiness penalties |
| $h_{j}$ | Maintenance activities | TADC | Total absolute differences |
| res | Resource constraints |  | incompletion times |

In Table 1.1., we present the values for each field of this triplet we use in the rest of this paper. For example, a single machine scheduling problem to minimize makespan with sequence-dependent setup times will be noted as $1 / S T_{s d} / C_{\max }$. Also, many different solution methods have been proposed in the literature to solve scheduling problems. Table 1.2. gives the abbreviations of the solution methods used in the literature reviewed in this thesis. The first column of the table provides the short encodings of the solution methods. In the second column, the expansions of these succinct encodings are given. For example, the solution method of the abbreviation
given with SA is the Simulated Annealing solution method for scheduling problems in the literature.

Table 1.2. Abbreviations of The Solution Methods of Scheduling Problems

| Description of Abbreviations |  |  |  |
| :---: | :---: | :---: | :---: |
| ABC | Artificial Bee Colony | ICA | Imperialist Competitive Alg. |
| ACO | Ant Colony Optimization | $I G$ | Iterated Greedy Algorithm |
| AIS | Artificial Immune System | ILS | Iterated Local Search |
| ALNS | Adaptive Large Neighborhood Search | MA | Memetic Algorithm |
| ATCS | Apparent Tardiness Cost with Setups | MILP | Mixed Integer Linear Programming |
| ATCSR | Apparent Tardiness Cost with Setups and Ready Times | MIP | Mixed Integer Programming |
| $B \& B$ | Branch-and-Bound | PSO | Particle Swarm Optimization |
| $B \& P$ | Branch-and-Price | RKGA | Random Key Genetic Alg. |
| BRKGA | Parallel Biased Random-Key Genetic Algorithm | $R N G$ | Random Number Generation |
| CP | Constraint Programming | RSA | Restricted Simulated Annealing |
| DE | Differential Evolution | SA | Simulated Annealing |
| EDA | Estimation of Distribution Algorithm | SEA | Self-Evolution Algorithm |
| EMA | Electromagnetism-like Alg. | SOS | Symbiotic Organisms Search |
| FA | Firefly Algorithm | TS | Tabu Search |
| GA | Genetic Algorithm | VND | Variable Neighborhood Descent |
| GRASP | Greedy Randomized Search Procedure | VNS | Variable Neighborhood Search |
| IA | Immune Algorithm |  |  |

In this study, we address the problem of scheduling $n$ jobs on $m$ uniform parallel machines with sequence-dependent setup times to minimize the maximum completion time (makespan). To the best of our knowledge, there are few studies in the literature for this problem. In this context, we provide an IP formulation and propose a randomized heuristic with an improvement subroutine to solve the problem. We evaluate the performance of the proposed algorithm through a computational study.

The rest of this thesis is organized as follows: Chapter 2 gives the literature review for the scheduling problems; Chapter 3 defines the problem, introduces the formulation of the mathematical model, and presents the developed randomized heuristic. Results of computational experiments and comparisons are provided in Chapter 4. Chapter 5 gives the conclusion and direction for further research in related fields.

## CHAPTER 2

## LITERATURE REVIEW

The parallel machines scheduling problem is one of the most challenging classes of the scheduling problem. Many studies have been conducted on various commercial, industrial and academic fields. Cheng and $\operatorname{Sin}(1990)$ considered that parallel machine scheduling problems could be roughly classified into three categories: (1) identical parallel machines, (2) unrelated parallel machines, and (3) uniform parallel machines. In our literature review, we first considered general parallel machine scheduling definitions, divided them into these three main classes, and examined them separately.

### 2.1. Parallel Machines

In this section, we review papers related to our problem. In a parallel machine environment, all the jobs are required to have a single operation, as in the case of a single machine environment. However, the operation can be performed by any $m$ machines, i.e., the $m$ machines are working in parallel. In other words, arriving jobs in parallel machine scheduling problems can be processed on any available machines. PMSP can be classified into three main categories mentioned in the introduction chapter. The $m$ machines may have the same speed, i.e., identical $(P)$; or have different speeds, i.e., uniform $(Q)$; or completely unrelated $(R)$. A summary of the scheduling literature in parallel machine environments is presented in Table 2.1, Table 2.2 and Table 2.3, where the identical, uniform, or unrelated machines are indicated by the letter $P, Q$, or $R$ in the second column first indices. To summarize the table structure, the first column shows who wrote the paper and its published year. The second column classifies the problem following Graham et al.'s (1979) 's triple taxonomy, which we mentioned in the previous chapter. The paper examined in this column indicates what kind of machine setting, the performance measure, and the setup information and details of the processing characteristics. Finally, the last column gives the solution methodologies of these papers.

### 2.1.1. Identical Parallel Machine

First, numerous papers address identical parallel machines. Turker and Sel (2011) studied the $P 2 / S T_{s d} / C_{\max }$ problem. GA algorithm is developed using random data sets and setup operations performed by a single server. The optimum results are obtained using a string-based permutation algorithm.

The problem of $P / S T_{s d} / C_{\max }$ is addressed by many researchers. Behnamian et al. (2009) presented the hybridization of an ACO, SA with VNS; combining the advantages of these three individual components is the key innovative aspect of the approach. This proposed algorithm stressed the balance between global exploration and local exploitation. Báez et al. (2019) proposed a hybrid algorithm that combines GRASP and VNS as the improvement procedure. The designed algorithm consists of two phases: construction and improvement, performed using a general VNS. Xu et al. (2013) developed a robust (min-max regret) scheduling model for identifying a robust schedule with minimal maximal deviation from the corresponding optimal schedule across all possible job-processing times. These scenarios are specified as closed intervals. Soares and Carvalho (2020) and Beezão et al. (2017) addressed the problem of $P / S T_{s d} / C_{\max }$ with tooling constraint in a flexible manufacturing system (FMS). As main contributions, Soares and Carvalho (2020) studied using a parallel biased random-key genetic algorithm (BRKGA) hybridized with local search procedures organized using VND and they published the results for single benchmark instances available in the literature, which will contribute consistently to the future of the study of the problem. Beezão et al. (2017) proposed two mathematical formulations of the problem and an ALNS metaheuristic. The destroy and repair operators exploit the structures of two well-known and related combinatorial optimization problems, namely the PMSP and the job sequencing and tool switching problem on a single machine.

Hamzadayi and Yildiz (2007) considered the $P / S T_{s d}, S / C_{\max }$ problem. Motivated by a real-life problem from the textile industry, Hamzadayi and Yildiz (2007) developed a new MILP model. Also, they considered SA and GA-based metaheuristics. After, they compared the performance of the proposed metaheuristic algorithm solution with basic dispatching rules. This is the first time dealing with the static $m$ identical PMSP with a common server and sequence-dependent setup times.

Arbaoui and Yalaoui (2016) and Tahar et al. (2006) presented the problem of $P / S T_{s d}, s p l i t / C_{\text {max }}$. Arbaoui and Yalaoui (2016) suggested new approach based on the Benders Decomposition, which can optimally solve the examples discussed in the literature.The problem is divided into two parts. The master problem and the subproblems that using a Traveling Salesman Problem (TSP) exact algorithm. Tahar et al. (2006) studied a new method based on LP techniques. They introduced a lower bound to evaluate the performance of their new approach on a large number of randomly generated instances.

Expósito-Izquierdo et al. (2019) considered the $P / S T_{s d} / \sum C_{j}$ problem. They firstly proposed a VNS metaheuristic algorithm aimed at finding high-quality and diverse solutions ignoring the learning/tiredness. Then, they studied the effects of learning or tiredness on the obtained solutions in a real-world scenario using a multi-agent simulation approach.

Driessel and Mönch, $(2009,2011)$ presented the problem of $P / S T_{s d}, r_{j}, p r e c / \sum w_{j} T_{j}$. Driessel and Mönch (2009) suggested a VNS approach that can outperform schedules obtained by a list-based scheduling approach using the ATCSR dispatching rule. Driessel and Mönch (2011) is a considerably extended version of the previous paper, containing more results of computational experiments for various VNS schemes.

Kim et al. (2020) developed a MIP model for the problem of $P / S T_{s d}$, split $/ \sum T_{j}$. They also proposed a novel mathematical model to offer metaheuristic approaches with new solution representation schemes, solution encoding schemes, and decoding methods by utilizing metaheuristics such as the SA and the GA.

Joo and $\operatorname{Kim}$ (2012) considered the problem of $P / S T_{s d}, r_{j} / \sum w_{j} T N S, T_{j}, U_{j}$. First, they presented the MIP model. Since this mathematical model is not tractable for large problems, GA and SEA metaheuristics are applied to improve the solution efficiency. This is the first time that SEA is a new population-based evolutionary metaheuristic.

Ying and Cheng (2010) and Lee et al. (2010) addressed the problem of $P / S T_{s d}, r_{j} / L_{\text {max }}$. Ying and Cheng (2010) presented IG algorithm. Extensive computational experiments reveal that the proposed heuristic is more effective than state-of-the-art algorithms on the same benchmark problem data set. Lee et al. (2010) proposed SA and RSA algorithms that incorporate a restricted search strategy to eliminate non-effect job moves to find the best neighborhood schedule.

Park et al. (2012) analyzed the problem of $P / S T_{s d}, s p l i t, t_{j}, b_{j} / \sum T_{j}$. This paper presented heuristic algorithms that consider job splitting and sequence-dependent major/minor setup times. The performance of the proposed heuristics is compared with the split algorithm, which is embedded into the three heuristics as a slack-based heuristic, dynamic scheduling window-based heuristic, and the latest starting timebased heuristic.

Queiroz and Mundim (2019) solved the $P / S T_{s d} / C_{\max }, \sum C_{j}$ problem with a heuristic that was based on the multiobjective VND and can satisfactorily construct the Pareto front. They recommended neighborhood structures with swap, remove and insertion moves. To the best of our knowledge, there is no application of such a heuristic to solving this problem.

Bosman et al. (2019) addressed the problem of $P / S T_{s d} / w_{j} C_{j}$. The twist is that the jobs assigned to the machine must obey the order of the input sequence, as is the case in multi-server queuing systems. They establish a constant-factor approximation algorithm. Their approach is very different from what has been used for similar scheduling problems without the fixed-order assumption. They also give a quasipolynomial time approximation scheme (QPTAS) for the particular case of unit processing times.

Ozer and Sarac (2019) proposed the problem of $P / S T_{s d}, M_{j} / w_{j} C_{j}$. In this study, an identical parallel machine scheduling problem with sequence-dependent setup times, machine eligibility restrictions, and multiple copies of shared resources (IPMSP-SMS) are considered. MIP models and a model-based GA matheuristic are proposed.

Ying (2012) studied the wafer sorting scheduling problem (WSSP), with minimization of total setup time as the primary criterion and minimization of the number of testers used as the secondary criterion with due dates and maximum machine capacity constraints. Given the strongly NP-hard nature of this problem, a simple and effective IG heuristic is presented. Behnamian et al. (2011) considered a min-max multiobjective procedure for a dual-objective; $C_{\max }$ and $\sum E_{j}+T_{j}$ in due window problems. Several hybrid metaheuristics were proposed for the addressed problem with three unique features: its population-based evolutionary searching ability belonging to ACO, its ability to balance exploration and exploitation belonging to SA, and its local improvement ability belonging to VNS.

Table 2.1. Literature Review for Identical Parallel Machine

| References | Problem | Approach |
| :---: | :---: | :---: |
| Turker and Sel (2011) | $\begin{gathered} P 2 / S T_{\text {sd }} / C_{\text {max }}(\text { Identical } \\ 2 \text { Machines) } \\ \hline \end{gathered}$ | GA, String based permutation algorithm |
| Expósito-Izquierdo et al.(2019) | $P / S T_{s d} / \Sigma C_{j}$ with learning or tiredness effect | VNS algorithm |
| Arbaoui and Yalaoui <br> (2016) | $P / S T_{\text {sd }}$, split $/ C_{\text {max }}$ | Bender's decomposition and TSP exact algorithm |
| Behnamian et al.(2009) | $P / S T_{s d} / C_{\text {max }}$ | Hybridization of an ACO, SA with VNS algorithms |
| Ying and Cheng (2010) | $P / S T_{s d}, r_{j} / L_{\text {max }}$ | IG algorithm |
| Hamzadayi and Yildiz (2007) | $P / S T_{s d}, S / C_{\text {max }}$ | MILP model - SA and GA metaheuristics |
| Driessel and Mönch (2009) | $P / S T_{s d}, r_{j}, \operatorname{prec} / \Sigma w_{j} T_{j}$ | VNS algorithm and ATCSR dispatching rule |
| Kim et al.(2020) | $P / S T_{\text {sd }}$, split $/ \Sigma T_{j}$ | MIP model - SA and GA metaheuristics |
| Driessel and Mönch (2011) | $P / S T_{s d}, r_{j}, \operatorname{prec} / \Sigma w_{j} T_{j}$ | VNS algorithm |
| Park et al.(2012) | $P / S T_{s d}$, split $, t_{j}, b_{j} / \Sigma T_{j}$ | Slack-based heuristic, dynamic scheduling windowbased heuristic and latest starting time-based heuristic |
| Lee et al.(2010) | $P / S T_{s d}, r_{j} / L_{\text {max }}$ | SA and RSA algorithms |
| Joo and Kim (2012) | $\begin{array}{r} P / S T_{s d}, r_{j} \\ / \Sigma w_{j}, T N S, T_{j}, U_{j} \end{array}$ | MIP model - SA and SEA metaheuristics |
| Tahar et al.(2006) | P/ST ${ }_{\text {sd }}$, split $/ C_{\text {max }}$ | LP techniques and lower bound |
| Xu et al. (2013) | $P / S T_{s d} / C_{\text {max }}$ | Robust min-max regret scheduling model |
| $\begin{array}{\|l} \text { Soares and Carvalho } \\ (2020) \end{array}$ | $P / S T_{s d} / C_{\max }$ with tooling constraint | BRKGA hybridized with local search procedures using VND |
| Queiroz and Mundim (2019) | $P / S T_{s d} / C_{\text {max }}, \Sigma C_{j}$ | Multiobjective VND and Pareto front neighborhood structure |
| Báez et al. (2019) | $P / S T_{s d} / C_{\text {max }}$ | GRASP and VNS algorithm |
| Bosman et al. (2019) | $P / S T_{s d} / w_{j} C_{j}$ | Quening systems and quasipolynomial time approximation scheme (QPTAS) |
| Beezão et al. (2017) | $P / S T_{s d} / C_{\text {max }}$ with tooling constraint | Two mathematical formula and ALNS metaheuristic |
| Ozer and Sarac (2019) | $P / S T_{s d}, M_{j} / w_{j} C_{j}$ | MIP model - GA matheuristic |

### 2.1.2. Unrelated Parallel Machine

For unrelated parallel machine scheduling, many researchers addressed the problem of $R / S T_{s d} / C_{\max }$ in the literature. Wang et al. (2016) developed a Hybrid Estimation of Distribution Algorithm with Iterated Greedy Search (EDA-IG). This is the first study in the literature dealing with the Estimation of Distribution Algorithm (EDA) applied to the UPMSP-SDST. Abreu and Prata (2019) presented a hybrid meta-heuristic based on GA, SA, VND, and path relinking. The proposed algorithm showed competitive results with an innovative hybridization of GA and neighborhood search algorithms, tested in diverse instances of literature. Furthermore, they presented a granite industry case study to solve real-world problems. Ezugwu et al. (2018) improved the SOS algorithm. They used the ILS strategy to combine variable numbers of insertion and swap moves and LPT rules to enhance the solution quality, performance, and speed. This work is the first to apply an SOS metaheuristic algorithm to solve the UPMSPSDST. Ezugwu and Akutsah (2018) applied Firefly Algorithm (FA), refined with a robust local search solution improvement mechanism. GA, Invasive Weed Optimization (IWO) and ACO metaheuristic algorithms were developed in parallel to verify and measure the effectiveness of the proposed algorithm. Silva et al. (2019) implemented five algorithms to find solutions for UPMSP-SDST. (1) An exact method (2) VNS, which consists of a metaheuristic that uses the concept of neighborhood structures to find better solutions and escape the local optimum. (3) GA, an optimization method based on the natural evolution process. (4), (5) Two heuristics based on the mathematical modeling called Relax-and-Fix (R\&F) and Fix-andOptimize (F\&O) were developed. Ezugwu (2019) proposed three different approaches to solve the problem, including An Enhanced Symbiotic Organisms Search (ESOS) algorithm, a Hybrid Symbiotic Organisms Search with Simulated Annealing (HSOSSA) algorithm and an Enhanced Simulated Annealing (ESA) algorithm.

Tozzo et al. (2018) used GA and VNS to solve the problem due to the difference among their characteristics: the GA is classified as a metaheuristic inspired by nature and based on population, whereas the metaheuristic VNS is not inspired by nature and performs a punctual search through several neighboring structures. These peculiarities allow a complete diversification of the resolution method for the same problem. Diana et al. (2015) proposed an immune-inspired algorithm. The initial population was generated through the construction phase of the GRASP. An evaluation function was
applied to help the algorithm escape from local optima. VND local search heuristic developed as a somatic hypermutation operator to accelerate the algorithm's convergence. Lin and Ying (2014) presented a Hybrid Artificial Bee Colony (HABC) algorithm to solve the problem. The performance of the proposed algorithm was evaluated by comparing its solutions to state-of-the-art metaheuristic algorithms and a high-performing ABC-based algorithm. Avalos-Rosales et al. (2015) considered a new makespan linearization and several MIP formulations. These formulations outperform the previously published formulations regarding the size of instances and computational time to reach optimal solutions. A metaheuristic algorithm based on a multi-start algorithm and VND was analyzed. Müller et al. (2015) developed a new MIP-based heuristic combining atomic moves such as insertion, rejection, and closure to generate sequences of such atomic movements minimizing the makespan. This heuristic employed a commercial solver to search the neighborhood in a multi-start algorithm. Vallada and Ruiz (2011) addressed the Genetic Algorithm (GA) for the unrelated parallel machine scheduling problem with sequence-dependent setup times with the objective to minimize the makespan. The proposed GA involved a new crossover operator, which includes a limited local search procedure which was very fast. Two versions of the algorithm were obtained after extensive calibrations using the Design of Experiments (DOE) approach. They reviewed, evaluated and compared the proposed algorithm against the best methods known from the literature. FanjulPeyro et al. (2019) suggested a new MILP and a mathematical programming-based algorithm. These new models and algorithms are tested and compared in an extensive and comprehensive computational campaign with the existing ones. The performance of two commercial solvers was also compared in the experiments. Gedik et al. (2018) suggested a novel CP model with two customized branching strategies that utilize CP's global constraints, interval decision variables, and domain filtering algorithms. The performance of the model was evaluated with the state-of-art algorithms. Cheng et al. (2020) studied Random Forest (RF) and Random-Forest-based Hybrid Artificial Bee Colony (RF-HABC) metaheuristics. The main objective of this study was to minimize the makespan in an unrelated PMSP with uncertain machine-dependent and job sequence-dependent setup times (MDJSDSTs).

Arbaoui and Yalaoui (2018) and Fanjul-Peyro et al. (2017) addressed the problem of $R / S T_{s d}, r e s / C_{m a x}$. Arbaoui and Yalaoui (2018) formulated the problem using a CP
model and solved it using the state-of-the-art solver. They compared this model's results against the existing literature approaches on two sets of small and medium instances. Fanjul-Peyro et al. (2017) modeled two integer linear programming models. The first one was previously proposed in the literature, which was the adaptation of an existing formulation (named UPMR-S). The second one was based on the resemblance to strip packing problems. It was an original contribution of this paper and a novel reformulation of the problem inspired by the strip packing model (named UPMR-P).

Hu et al. (2016) considered the $R / S T_{s d}, r_{j} / C_{\max }$ problem. This paper identified a robust schedule by the min-max regret criterion. To the best of our knowledge, PMSP with uncertain processing time, ready time, and mold change consideration have not been studied in the literature. MILP formulation and an exact algorithm were proposed. Also, they developed a modified ABC algorithm to solve large-sized problems. AlHarkan and Qamhan (2019) studied the problem of $R / S T_{s d}, r_{j}, r e s / C_{\max }$. In order to find an optimal solution for this problem, a new MILP was presented. Moreover, a two-stage hybrid metaheuristic based on VNS Hybrid and SA (TVNS_SA) was proposed.

Angel Bello et al. (2018) analyzed the $R / S T_{s d}, h_{j} / C_{\max }$ problem. They presented a mathematical formulation for this problem and derived valid inequalities to improve its performance, allowing the model to obtain optimal solutions for small, medium instances. In addition, they designed an efficient metaheuristic algorithm based on the multi-start strategy for solving larger instances.

Afzalirad and Rezaeian (2016) considered the problem of $R / S T_{s d}, r_{j}, M_{j}$, Prec, res/ $C_{\text {max }}$. They created a new pure integer mathematical modeling formula. They developed two new metaheuristic algorithms, including GA and AIS, to detect optimal or near-optimal solutions. They also set the parameters of these algorithms using the Taguchi method.

Caniyilmaz et al. (2015) examined the problem of of $R / S T_{s d}, M_{j} / C_{\max }+\sum T_{j}$. This paper used the new neighborhood approach that gives the different machine assignments for every candidate-job sequence. They took advantage of ABC and GA metaheuristics and this integration benefits to evaluate performances of the algorithms with the real-life problem about quilting work center.

Rauchecker and Schryen (2019) solved the of $R / S T_{s d}, M_{j} / \sum w_{j} C_{j}$ problem. This study
adapted an exact $\mathrm{B} \& \mathrm{P}$ algorithm to UPMSP-SDST, parallelized the concerted algorithm by implementing a distributed-memory parallelization with a master/worker approach, and conducted prevalent computational experiments modern high performance computing cluster.

Zeidi et al. (2017) addressed the problem of $R / S T_{s d}, r_{j}, M_{j} /\left(\sum \alpha_{j} E_{j}+\beta_{j} T_{j}, \sum C_{j}\right)$. This study introduced the MIP model to formulate the considered multi-criteria problem. They proposed the namely Controlled Elitism Non-Dominated Sorting Genetic Algorithm (CENSGA) solve the model for real-sized applications. Also, to validate its performance, the algorithm was examined under six metric performance measures and compared with a Pareto-Based Algorithm, namely NSGA-II.

Naderi-Beni et al. (2014) developed the problem of $R / S T_{s d}, M_{j}, r_{j} / \sum M L_{\max }-$ $\left.M L_{j}\right), \sum T_{j}$.In this paper, a Fuzzy Bi-objective Mixed Integer Linear Programming (FBOMILP) model was presented. The proposed model was solved by two metaheuristic algorithms, namely Fuzzy Multi-Objective Particle Swarm Optimization (FMOPSO) and Fuzzy Non-dominated Sorting Genetic Algorithm (FNSGA-II) for solving large-scale instances.

Lopes and Carvalho (2007) studied the $R / S T_{s d}, M_{j}, r_{j} / \sum w_{j} T_{j}$ problem. They developed a new $\mathrm{B} \& \mathrm{P}$ optimization algorithm for the general class of PMSP. A new column generation accelerating method termed 'primal box', Dantzig-Wolfe decomposition, and a specific branching variable selection rule that significantly reduces the number of explored nodes were proposed.

Tavakkoli-Moghaddam et al. (2009) solved the $R / S T_{s d}, r_{j}, \operatorname{Prec} / \sum U_{j}, C_{\max }$ problem. They studied a two-level MIP model to minimize bi-objectives. Since solving the large-sized problem in a reasonable computational time or optimization tools was extremely difficult, this paper presented an efficient GA model to solve the biobjective PMSP.

Safaei et al. (2015) analyzed the problem of $R / S T_{s d}, r_{j}, \operatorname{Prec} / \sum U_{j}+C_{\max }$. They proposed two Multiobjective Genetic Algorithms (MOGA). Random test problems were produced in medium and large-sized to evaluate the proposed algorithms with tight due dates large-sized with tight due dates. The performances of algorithms were evaluated using the concept of Data Envelopment Analysis (DEA), distance method, and some non-dominated solutions.

Bektur and Sarac (2019) used the $R / S T_{s d}, S, M_{j} / \sum w_{j} T_{j}$ problem. A MILP model was developed, and due to the NP-hardness of the problem, TS and SA algorithms were presented. A modified ATCS dispatching rule obtained the initial solutions of the algorithms.

Cota et al. (2019) addressed the problem of $R / S T_{s d} / C_{\text {max }}, T E C$. They considered multiobjective extensions of the Adaptive Large Neighborhood Search (ALNS) metaheuristic with Learning Automata (LA). They solved the large-sized test instances by improving the search process. Moreover, They developed two new algorithms: the Mono-Objective ALNS with Learning Automata (MO-ALNS) and the MO-ALNS/D. Kongsri and Buddhakulsomsiri (2020) considered the $R / S T_{s d} / C_{\max }+\sum T_{j}$ problem. This paper formulated a MIP model for the UPMSP-SDST that total tardiness. A compromise solution was found with a proper weight between the two measures.

Rocha et al. (2008) analyzed the $R / S T_{s d} / C_{\max }+\sum w_{j} T_{j}$ problem. They used Branch and Bound methods and they ensured the solution by using the GRASP metaheuristic as an upper bound. They suggested some test instances and the metaheuristic results for this type of problem compared with two MIP models.

Zeidi and Hosseini (2015) presented the problem of $R / S T_{s d} / \sum e_{j} * E_{j}+t_{j} * T_{j}$. A new mathematical model was provided for the considered problem, and due to the complexity of the problem, an integrated meta-heuristic algorithm is designed to solve the problem. The proposed algorithm consisted of GA as the basic algorithm and SA method as the local search procedure.

Chen (2009) solved the $R / S T_{s d} / \sum T_{j}$ problem. An effective heuristic based on a modified ATCS dispatching rule, the SA method and designed improvement procedures were proposed to minimize the total tardiness of this scheduling problem.

Ekici et al. (2019) examined the problem of $R / S T_{s d} / \sum T_{j}+E_{j}$ and machine-job compatibility restrictions and workload balance requirements. They studied a wide range of heuristics, including (i) a sequential algorithm, (ii) a TS algorithm, (iii) a random set partitioning approach, and (iv) a novel matheuristic approach utilizing the local intensification and global diversification powers of a TS algorithm. This study was motivated by the production scheduling operations at a television manufacturer, Vestel Electronics.

Paula et al. (2010) addressed the problem of $R / S T_{s d} / \sum w_{j} T_{j}$. This work presented a non-delayed relax and cut algorithm based on a Lagrangean Relaxation of a timeindexed formulation of the problem. Also, Lagrangean pure VNS heuristics were developed to obtain approximate solutions.

Chen and Chen (2009) considered the $R / S T_{s d} / \sum w_{j} U_{j}$ problem. They studied several hybrid metaheuristics. These metaheuristics began with effective initial solution generators to generate initial feasible solutions; then, they improved the initial solutions by an approach that integrates the VND and TS principles.

Table 2.2. Literature Review for Unrelated Parallel Machine

| References | Problem | Approach |
| :---: | :---: | :---: |
| Hu et al.(2016) | $R / S T_{s d}, r_{j} / C_{\text {max }}$ | Robust min-max regret scheduling model - MILP and exact model - ABC algorithm |
| Al-Harkan and Qamhan (2019) | $R / S T_{s d}, r_{j}$, res $/ C_{\text {max }}$ | MILP model - hybrid VNA and SA (TVNS_SA) metaheuristic |
| Bektur and Sarac (2019) | $R / S T_{s d}, S, M_{j} / \Sigma w_{j} T_{j}$ | MILP model - TS and SA algorithms - ATCS dispatching rule |
| Naderi-Beni et al.(2014) | $\begin{aligned} R / S T_{s d}, M_{j}, r_{j} / & \Sigma\left(M L_{\max }\right. \\ & \left.-M L_{j}\right), \Sigma T j \end{aligned}$ | Fuzzy bi-objective MILP (FBOMILP) model - Fuzzy multiobjective particle swarm optimisation (FMOPSO) and Fuzzy nondominated sorting genetic algorithm (FNSGA-II) |
| Wang et al.(2016) | $R / S T_{s d} / C_{\text {max }}$ | Hybrid EDA and IG (EDA_IG) metaheuristic |
| Abreu and Prata (2019) | $R / S T_{s d} / C_{\text {max }}$ | Hybrid meta-heuristic based on GA, SA, VND and path relinking |
| Rauchecker and Schryen (2019) | $R / S T_{s d}, M_{j} / \Sigma w_{j} C_{j}$ | B\&P algorithm -Distributed-memory parallelization with a master/worker approach |
| Tozzo et al.(2018) | $R / S T_{s d} / C_{\text {max }}$ | GA and VNS metaheuristic |
| Ezugwu et al.(2018) | $R / S T_{s d} / C_{\text {max }}$ | ILS strategy - SOS metaheuristic - LPT rules |
| Afzalirad and Rezaeian (2016) | $\begin{array}{r} R / S T_{\text {sd }}, r_{j}, M_{j}, \text { Prec, res } \\ / C_{\max } \end{array}$ | Pure integer mathematical model - GA and AIS algorithms |

Table 2.2 (cont'd). Literature Review for Unrelated Parallel Machine

| References | Problem | Approach |
| :---: | :---: | :---: |
| $\begin{aligned} & \text { Zeidi and Hosseini } \\ & (2015) \end{aligned}$ | $R / S T_{s d} /\left(\Sigma e_{j} E_{j}+t_{j} T_{j}\right)$ | Mathematical model - GA and SA metaheuristic |
| Diana et al.(2015) | $R / S T_{s d} / C_{\text {max }}$ | Immune-inspired algorithm GRASP and VND algorithm |
| Lin and Ying (2014) | $R / S T_{s d} / C_{\text {max }}$ | Hybrid artificial bee colony (HABC) algorithm |
| Caniyilmaz et al.(2015) | $R / S T_{s d}, M_{j} / C_{\text {max }}+\Sigma T_{j}$ | ABC and GA metaheuristics |
| Avalos-Rosales et al.(2015) | $R / S T_{s d} / C_{\text {max }}$ | MIP model - VND algorithm |
| Ezugwu and Akutsah (2018) | $R / S T_{s d} / C_{\text {max }}$ | FA, GA and ACO metaheuristics and Invasive weed optimization (IWO) |
| Müller et al.(2015) | $R / S T_{s d} / C_{\text {max }}$ | MIP-based heuristic combining atomic moves -Multi-start algorithm |
| Vallada and Ruiz (2011) | $R / S T_{s d} / C_{\text {max }}$ | GA - Design of Experiments (DOE) approach |
| Silva et al.(2019) | $R / S T_{s d} / C_{\text {max }}$ | Exact algorithm - VNS, GA - Relax-and-Fix (R\&F) and Fix-and-Optimize (F\&O) heuristics |
| Paula et al. (2010) | $R / S T_{s d} / \Sigma w_{j} T_{j}$ | VNS algorithm - Lagrangean relaxation |
| Rocha et al.(2008) | $R / S T_{s d} / C_{\text {max }}+\Sigma w_{j} T_{j}$ | Two MIP models - B\&B algorithm - GRASP metaheuristic |
| TavakkoliMoghaddam et al.(2009) | $R / S T_{s d}, r_{j}, \operatorname{Prec} / \Sigma U_{j}, C_{\text {max }}$ | Novel two-level MIP model - GA to solve bi-objective PMSP |
| Chen (2009) | $R / S T_{s d} / \Sigma T_{j}$ | SA and modified ATCS dispatching rule |
| Chen and Chen (2009) | $R / S T_{s d} / \Sigma w_{j} U_{j}$ | VND and TS metaheuristics |
| Safaei et al.(2015) | $\begin{aligned} R / S T_{s d}, r_{j}, \operatorname{Prec} / & \Sigma U_{j} \\ & +C_{\max } \end{aligned}$ | Multi objective genetic algorithms (MOGA) - Data envelopment analysis (DEA), |
| Lopes and Carvalho (2007) | $R / S T_{s d}, M_{j}, r_{j} / \Sigma w_{j} T_{j}$ | B\&P algorithm - DantzigWolfe decomposition and a specific branching variable selection rule |
| Zeidi et al.(2017) | $\begin{aligned} R / S T_{s d}, r_{j}, M_{j} /( & \left(\Sigma \alpha_{j} E_{j}\right. \\ & \left.+\beta_{j} T_{j}, \Sigma C_{j}\right) \end{aligned}$ | MIP model - Controlled elitism non-dominated sorting genetic algorithm (CENSGA) - Pareto-based algorithm (NSGA-II) |

Table 2.2 (cont'd). Literature Review for Unrelated Parallel Machine

| References | Problem | Approach |
| :--- | :---: | :--- |
| Kongsri and <br> Buddhakulsomsiri <br> (2020) | $R / S T_{s d} / C_{\max }+\Sigma T_{j}$ | MIP model |
| Cheng et al. (2020) | $R / S T_{s d} / C_{\max }$ | Random Forest (RF) and <br> Random-Forest-based <br> Hybrid Artificial Bee <br> Colony (RF-HABC) |
| Cota et al. (2019) | $R / S T_{s d} / C_{\max }, T E C$ | ALNS metaheuristic with <br> Learning Automata (LA) |
| Fanjul-Peyro et al. <br> (2019) | $R / S T_{s d} / C_{\max }$ | MILP and mathematical <br> programming |
| Angel-Bello et al. <br> (2018) | $R / S T_{s d}, h_{j} / C_{\max }$ | Mathematical model - Multi- <br> start algorithm |
| Arbaoui and Yalaoui <br> (2018) | $R / S T_{s d}, r e s / C_{\max }$ | CP model <br> Fanjul-Peyro et al. <br> $(2017)$ <br> $R / S T_{s d}, r e s / C_{\max }$ |
| Two integer linear <br> programming problems <br> (resemblance to strip <br> packing problems) |  |  |
| Ezugwu (2019) | $R / S T_{s d} / C_{m a x}$ | Enhanced Symbiotic <br> Organisms Search (ESOS) <br> algorithm, a Hybrid <br> Symbiotic Organisms Search <br> with Simulated Annealing <br> (HSOSSA) algorithm, and <br> an Enhanced Simulated <br> Annealing (ESA) algorithm. |
| Gedik et al. (2018) | $R / S T_{s d} / C_{m a x}$ | Noval CP model with two <br> customized branching <br> strategies |
| Ekici et al.(2019) | $R / S T_{s d} / \Sigma T_{j}+E_{j}$ | TS and sequential algorithm, <br> random set partitioning and <br> novel matheuristic approach |

### 2.1.3. Uniform Parallel Machine

Lastly, some papers considered resources in scheduling uniform parallel machines, Armentano and Franca (2007) addressed the problem of $Q / S T_{s d} / \Sigma T_{j}$. They proposed GRASP versions that incorporate adaptive memory principles for solving this problem to minimize the total tardiness with respect to job due dates. Initially, they adapted suitable components for any GRASP procedure, namely, a greedy function and neighborhoods together with a candidate list. Then, they examined the use of longterm memory composed of an elite set of high quality and sufficiently distant solutions.

Balakrishnan et al. (1999) studied the problem of $Q / S T_{s d}, r_{j} / \Sigma e_{j} E_{j}+\Sigma t_{j} T_{j}$. For this complex problem, they presented a compact mathematical model and described their computational experience in using this model to solve small-sized problems.

Table 2.3. Literature Review for Uniform Parallel Machine

| References | Problem | Approach |
| :--- | :---: | :--- |
| Armentano and Franca <br> (2007) | $Q / S T_{s d} / \Sigma T_{j}$ | GRASP and adaptive <br> memory principles |
| Balakrishnan et al. <br> (1999) | $Q / S T_{s d}, r_{j} / \Sigma e_{j} E_{j}+t_{j} T_{j}$ | Mathematical model |

## CHAPTER 3

## PROBLEM DESCRIPTION \& ANALYSIS

In this thesis, we consider the uniform parallel machine scheduling problem with sequence-dependent setup times, denoted as $Q / S T_{s d} / C_{\text {max }}$. In uniform parallel machine scheduling, $n$ jobs are processed on $m$ machines in parallel ( $n>m$ ), where machines have different processing speeds. The processing speed of machine $k,(k=$ $1,2, . ., m$, is denoted by $v_{k}$. For example, if $v_{1}=2 v_{2}$, then Machine 1 processes a job twice as fast as Machine 2 . $\operatorname{Job} i,(i=1,2, \ldots, n)$, has the processing time of $p_{i}$ at the unit processing speed. Therefore, the processing time of job $i$ on machine $k$ is $p_{i k}=p_{i} / v_{k}$. Note that when all machines have identical speeds, i.e., $v_{1}=\ldots=v_{m}$, the problem we consider herein transforms into the identical parallel machine scheduling problem. Hence the latter is a special case of the problem we consider. A setup is required before processing a job in a machine. We consider the setting where these setup times are sequence-dependent. Similar to the processing times, setup times depend on the machine speeds. Namely, if job $j$ will be processed immediately after job $i$ on the same machine, the setup time is $s_{i j}$ at the unit processing speed. For a particular machine $k$, the setup time of job $j$ immediately after job $i$ is denoted by $s_{i j k}=s_{i j} / v_{k}$. The objective is to minimize the maximum completion time (makespan).

Example 1. Suppose that there are eight jobs and three machines in the manufacturing system. All job has a processing time at the base speed, which we denoted by $p_{i}$, where $1 \leq i \leq 8$. In addition, setup time is required if job $j$ will be processed immediately after job $i$ on the same machine and denoted by $s_{i j}$, where $1 \leq i, j \leq$ 8 and $i \neq j$. Table 3.1. gives the processing times of each job and Table 3.2. provides the setup time at unit processing speed.

Table 3.1. Processing Times for Example 1

| Jobs (i) | Job 1 | Job 2 | Job 3 | Job 4 | Job 5 | Job 6 | Job 7 | Job 8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Processing <br> Time $\left(\boldsymbol{p}_{\boldsymbol{i}}\right)$ | 4 | 6 | 3 | 5 | 5 | 6 | 5 | 3 |

Table 3.2. Setup Time Matrix for Example 1

| Setup <br> Time ( $\boldsymbol{s}_{\boldsymbol{i} \boldsymbol{j}}$ | Job 1 | Job 2 | Job 3 | Job 4 | Job 5 | Job 6 | Job 7 | Job 8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Job 1 | - | 6 | 3 | 5 | 3 | 6 | 5 | 2 |
| Job 2 | 6 | - | 1 | 2 | 2 | 4 | 5 | 5 |
| Job 3 | 3 | 1 | - | 2 | 6 | 4 | 4 | 2 |
| Job 4 | 5 | 2 | 2 | - | 2 | 1 | 2 | 1 |
| Job 5 | 3 | 2 | 6 | 2 | - | 4 | 1 | 2 |
| Job 6 | 6 | 4 | 4 | 1 | 4 | - | 2 | 1 |
| Job 7 | 5 | 5 | 4 | 2 | 1 | 2 | - | 3 |
| Job 8 | 2 | 5 | 2 | 1 | 2 | 1 | 3 | - |

Figure 3.1. and Figure 3.2. show two Gantt charts for production schedules in identical and uniform parallel machines with one setup operator. In the Gantt chart, numbers in white bars indicate job indices, and black bars represent setup operations. Numbers in the bottom denote time stamps; for example, in Figure 3.1., Machine 1 finishes at 20 while the completion time of Machines 2 is 18 and Machine 3 is 19 . Assume that jobs are processed in their index order, the jobs processed for the first time on each machine do not require setups, and there is no dedicated machine constraint. When jobs are processed on identical parallel machines, their makespan is 20, as illustrated in Figure 3.1. However, the processing speed of machine $k$ is denoted by $v_{k}$, where $1 \leq k \leq 3$. When the machines have different speeds, i.e., $v_{1}, v_{2}$, and $v_{3}$ are $0.8,1$, and 1.2 , respectively, the processing times change. Therefore, the processing time of job $i$ on machine $k$ is calculated with this formulation: $p_{i k}=p_{i} / v_{k}$. In addition, for a particular machine $k$, the setup time of job $j$ immediately after job $i$ is calculated by $s_{i j k}=s_{i j} / v_{k}$. After these calculations, the schedule becomes the same as the Gantt chart in Figure 3.2. The makespan is 22.5 .


Figure 3.1. Schedule in Identical Parallel Machine for Example 1


Figure 3.2. Schedule in Uniform Parallel Machine for Example 1
We now propose an integer programming (IP) model for uniform parallel machine scheduling with sequence-dependent setup times with the objective of minimizing the maximum of machine completion times (makespan), which we denoted $Q / S T_{s d} /$ $C_{\max }$. It is assumed that the machines are not malfunctioning and that jobs are available at time zero. The machines are ready at the beginning of the scheduling period. Data is deterministic and known in advance. Breakdown and maintenance times are not considered and machines are always available if not busy. All jobs must be completed without interruption. Each job should be completed on one machine and machines can perform only one job at a given time.

Most importantly, machines are uniform $(Q)$, where the machines have different speeds but each machine processes at a consistent rate. Moreover, setup times are sequencedependent which means the setup times not only depend on the job currently being scheduled but also on the immediate preceding job. Also, setup times depend on the machine speeds. An IP model is proposed for the problem. We list the rest of our sets, indices, parameters and decision variables.

## Sets and indices

$N$ : Set of jobs to be processed, $N=\{1,2, \ldots, n\}$
$M$ : Set of uniform parallel machines, $M=\{1,2, \ldots, m\}$
$i, j$ : Indices of jobs, where $i, j \in N$
$k$ : Index of machines, where $k \in M$

## Parameters

$v_{k}$ : processing speed of machine $k$
$p_{i}:$ processing time for job $i$ at the base speed
$p_{i k}$ : processing time for job $i$ on machine $k$
$s_{i j}$ : setup time of job $j$ immediately after job $i$ at the base speed
$s_{i j k}$ : setup time of job $j$ immediately after job $i$ on machine $k$
$L$ : a large number

## Decision Variables

$x_{i j k}= \begin{cases}1, & \text { if job } i \text { is immediately after job } j \text { on machine } k \\ 0, & \text { otherwise }\end{cases}$
$y_{i k}= \begin{cases}1, & \text { if job } i \text { is assigned to machine } k \\ 0, & \text { otherwise }\end{cases}$
$C_{i}=$ completion time of job $i$
$c_{\max }=$ the maximum copletion time (makespan)
Next, we provide the IP formulation of the uniform machine scheduling problem with sequence-dependent setup times.

## Model

## Minimize $C_{\text {max }}$

Subject to

$$
\begin{array}{ll}
\sum_{i=1}^{n} x_{0 i k}=1 & \forall k \\
C_{i} \geq s_{0 i k}+p_{i k}-L\left(1-x_{0 i k}\right) & \forall i, k \\
\sum_{i=0, i \neq j}^{n} x_{i j k}=y_{j k} & \forall j, k \\
\sum_{j=1, i \neq j}^{n} x_{i j k} \leq y_{i k} & \forall i, k \\
C_{j} \geq C_{i}+\left(s_{i j k}+p_{j k}\right)-L\left(1-x_{i j k}\right) & \forall i, j, k \\
\sum_{k=1}^{m} y_{i k}=1 & \forall i \\
C_{\max } \geq C_{J,} & \forall j \\
C_{i} \geq 0 & \forall i \\
x_{i j k} \in\{0,1\} & \forall i, j, k \\
y_{i k} \in\{0,1\} & \forall i, k
\end{array}
$$

For notational convenience, we introduced a dummy job, $i=0$, for each machine. The objective function (1) is the minimization of the maximum completion time of all jobs. Constraint set (2) ensures that the dummy job 0 is the initial job for each machine. Constraint (3) ensures that the completion of the very first job of every machine is at least as much as the sum of its setup time and the processing time at that machine.

Constraint set (4) establishes that the precedence relationship exists between jobs assigned to a particular machine. Similarly, if a real job is assigned to a machine, it can succeed by at most one job. The job in the last position of the sequence on a machine will not have a succeeding job. Constraint sets (4) and (5) together verify that $n$ jobs are assigned to $m$ machines. They also ensure that if job $i$ immediately precedes job $j$ on machine $k$, then both jobs $i$ and $j$ belong to machine $k$. Constraint set (6) guarantees that the finishing time of a real job in a sequence of a machine will be more than or equal to the sum of processing time of the current job, the sequence-dependent setup time and the finishing time of the preceding job. Constraint set (7) ensures that a real job is assigned to exactly one machine. The makespan is obtained in Constraint (8) and Constraint (9) ensure a non-negative completion time for regular jobs. Finally, Constraint (10) and (11) specify that the variables in the model are binary.

The problem we consider belongs to the set of NP-hard problems. Garey and Johnson (1979) mentioned that a problem is NP-hard if an algorithm for solving it can be translated into one for solving any NP (Nondeterministic Polynomial-Time) problem. Owing to its academic and industrial importance, the UPMSP has been extensively investigated in recent decades and heuristics algorithms represent an alternative way of dealing with large-sized problems or combinatorial optimization problems. Despite the available technologies in today's sector, the computation time for the exact methods for most large-sized problems in the literature is very long and unrealizable because the time to obtain the optimal solution to the NP-hard problem increases exponentially as the size of the problem increases.

The difficulty of getting the optimal solution in a reasonable time motivated many studies, including ours, to consider heuristic solutions to obtain a near-optimal solution in a reasonable time. As a result, exact methods become ineffective for large problems, and heuristics approaches can significantly reduce computation time without necessarily leading to the optimal solution. As we mentioned in the literature review, many heuristic models such as Genetic Algorithm (GA), Simulated Annealing (SA), Variable Neighborhood Search (VNS) have been studied for parallel machine scheduling problems. This thesis proposes a simple randomized heuristic with an improvement subroutine. The following sections give a detailed description of the developed heuristic.

```
Algorithm
Set \(\mathcal{E}, C_{\text {max }}=\infty, \Delta C_{\text {max }}=\infty, N\)
while \(\Delta \mathrm{C}_{\text {max }}>\varepsilon\)
    repeat N times
            \(C_{\text {max }}^{\text {best }}=\infty\)
            Assign jobs randomly to machines in a random order
            Calculate \(\mathrm{C}_{\mathrm{m}}, \forall_{\mathrm{m}}\) and \(\mathrm{C}_{\max }^{\text {new }}\)
            \(\mathrm{C}_{\max }^{\text {old }}=\infty\)
            while \(C_{\max }^{\text {new }}<\mathrm{C}_{\max }^{\text {old }}\)
Assign last job of machine with the largest \(\mathrm{C}_{\mathrm{m}}\) to the machine with the smallest \(\mathrm{C}_{\mathrm{m}}\)
\[
\mathrm{C}_{\max }^{\text {old }}=\mathrm{C}_{\max }^{\text {new }}
\]
Calculate \(C_{\max }^{\text {new }}\) and \(C_{m}, \forall_{m}\) with the updated schedule
If \(\mathrm{C}_{\max }^{\text {old }}<\mathrm{C}_{\max }^{\text {best }} \quad \mathrm{C}_{\max }^{\text {best }}=\mathrm{C}_{\max }^{\text {old }}\)
\(\Delta \mathrm{C}_{\text {max }}=100 \times \frac{\mathrm{C}_{\text {max }}-\mathrm{C}_{\text {max }}^{\text {best }}}{\mathrm{C}_{\text {max }}}\)
\(\mathrm{C}_{\text {max }}=\mathrm{C}_{\text {max }}^{\text {best }}\)
end
```

Figure 3.3. Pseudo-Code of the Randomized Heuristic

The proposed heuristic is based on iterating a two-stage algorithm as long as we obtain a schedule with a smaller objective function value. In the first stage of this two-stage algorithm, we randomly assign jobs to the machines in random order. To elaborate, we choose one of the jobs from the set of jobs via a roulette wheel selection and randomly assign that job to one of the machines as the last assigned job that machine. We update the set of jobs by removing the assigned job from the set. We continue this assignment until the set of jobs is empty. At the end of this first algorithm stage, we obtain a feasible solution. We calculate the job completion times and the makespan for this schedule and proceed to the second stage with this information. The second stage of the algorithm relies on the observation that in the optimal solution, completion times of the last jobs of every machine are in proximity of each other. Hence, we identify the job with the largest completion time, remove that job from its assigned machine's list and append it to the job list of the machine with the shortest completion time as the last job. When we make this modification in the schedule, we also take machinespecific processing times of the jobs. After modifying the schedule, we update all the metrics, i.e., job completion times and the makespan, and repeat this improvement
process until makespan does not improve. We iteratively run this two-stage algorithm by new random assignments at every iteration until the objective function value does not improve. We present the pseudo-code of this heuristic in Figure 3.3.

Heuristic Example. Suppose that there are fifteen jobs and three machines in the manufacturing system. Table 3.3. shows the processing times for each job and machine index. Table 3.4. gives the setup with a matrix. Processing times are randomly generated between 1 and 6 and setup times are generated between 1 and 5. Also, jobs are randomly assigned to machines.

Table 3.3. Processing Times and Job Index for Heuristic Example

| Jobs | $\stackrel{\square}{\square}$ | $\begin{aligned} & \text { N } \\ & \text { O} \\ & \hline \end{aligned}$ | $\begin{aligned} & \infty \\ & 0 \\ & 0 \end{aligned}$ | $\begin{aligned} & \pm \\ & \stackrel{\rightharpoonup}{0} \end{aligned}$ | $\begin{aligned} & 10 \\ & 0 \\ & 0 \end{aligned}$ | $\begin{aligned} & 0 \\ & \stackrel{0}{0} \end{aligned}$ | $\begin{aligned} & \text { r} \\ & \text { O} \end{aligned}$ | $\begin{aligned} & \infty \\ & \stackrel{0}{0} \\ & \hline \end{aligned}$ | $\begin{aligned} & 0 \\ & 0 \\ & 0 \\ & 0 \end{aligned}$ | $\begin{aligned} & 0 \\ & 0 \\ & 0 \end{aligned}$ | $\begin{aligned} & 7 \\ & \stackrel{0}{0} \end{aligned}$ | $\begin{aligned} & \text { I } \\ & \text { O} \\ & \hline \end{aligned}$ | $\begin{aligned} & 0 \\ & 0 \\ & 0 \end{aligned}$ | $\begin{aligned} & \pm \\ & \stackrel{0}{0} \\ & \hline \end{aligned}$ | $\begin{aligned} & 10 \\ & \frac{0}{0} \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Processing Times | 3 | 3 | 4 | 1 | 2 | 3 | 2 | 3 | 3 | 4 | 5 | 2 | 6 | 5 | 2 |
| Machine Index | 2 | 2 | 2 | 2 | 3 | 1 | 3 | 2 | 2 | 3 | 3 | 1 | 1 | 3 | 2 |

Table 3.4. Setup Time Matrix for Heuristic Example

| Jobs | $\frac{1}{0}$ | $\begin{aligned} & \text { N } \\ & \text { O} \end{aligned}$ | $\begin{aligned} & 2 \\ & 0 \\ & 0 \end{aligned}$ | $\begin{aligned} & \pm \\ & \stackrel{\rightharpoonup}{9} \\ & \hline \end{aligned}$ | $\begin{aligned} & 10 \\ & 0 \\ & 0 \end{aligned}$ | $\begin{aligned} & 0 \\ & \text { O} \\ & \hline 0 \end{aligned}$ | $\begin{aligned} & n \\ & 0 \\ & 0 \end{aligned}$ | $\begin{aligned} & \infty \\ & \stackrel{0}{0} \\ & \hline \end{aligned}$ | $\begin{aligned} & 0 \\ & 0 \\ & 0 \end{aligned}$ | $\begin{aligned} & 0 \\ & 0 \\ & 0 \end{aligned}$ | $\begin{aligned} & 7 \\ & \stackrel{0}{0} \end{aligned}$ | $\begin{aligned} & \mathrm{I} \\ & \stackrel{0}{0} \end{aligned}$ | 0 <br> 0 <br> 0 <br> 0 | $\begin{aligned} & \pm \\ & \stackrel{\rightharpoonup}{0} \end{aligned}$ | -10 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Job 1 | 0 | 3 | 4 | 2 | 1 | 4 | 1 | 2 | 1 | 4 | 4 | 2 | 3 | 3 | 5 |
| Job 2 | 3 | 0 | 4 | 4 | 4 | 1 | 3 | 4 | 3 | 3 | 2 | 2 | 4 | 3 | 4 |
| Job 3 | 4 | 4 | 0 | 1 | 3 | 2 | 2 | 1 | 4 | 4 | 4 | 4 | 1 | 2 | 5 |
| Job 4 | 2 | 4 | 1 | 0 | 1 | 3 | 1 | 4 | 1 | 1 | 4 | 2 | 1 | 3 | 3 |
| Job 5 | 1 | 4 | 3 | 1 | 0 | 4 | 4 | 4 | 3 | 3 | 2 | 3 | 3 | 2 | 5 |
| Job 6 | 4 | 1 | 2 | 3 | 4 | 0 | 3 | 3 | 4 | 3 | 4 | 2 | 4 | 1 | 2 |
| Job 7 | 1 | 3 | 2 | 1 | 4 | 3 | 0 | 2 | 3 | 2 | 3 | 1 | 4 | 4 | 1 |
| Job 8 | 2 | 4 | 1 | 4 | 4 | 3 | 2 | 0 | 1 | 3 | 1 | 3 | 4 | 1 | 1 |
| Job 9 | 1 | 3 | 4 | 1 | 3 | 4 | 3 | 1 | 0 | 4 | 1 | 2 | 2 | 3 | 4 |
| Job 10 | 4 | 3 | 4 | 1 | 3 | 3 | 2 | 3 | 4 | 0 | 2 | 1 | 4 | 1 | 1 |
| Job 11 | 4 | 2 | 4 | 4 | 2 | 4 | 3 | 1 | 1 | 2 | 0 | 2 | 1 | 1 | 4 |
| Job 12 | 2 | 2 | 4 | 2 | 3 | 2 | 1 | 3 | 2 | 1 | 2 | 0 | 3 | 4 | 3 |
| Job 13 | 3 | 4 | 1 | 1 | 3 | 4 | 4 | 4 | 2 | 4 | 1 | 3 | 0 | 1 | 2 |
| Job 14 | 3 | 3 | 2 | 3 | 2 | 1 | 4 | 1 | 3 | 1 | 1 | 4 | 1 | 0 | 1 |
| Job 15 | 5 | 4 | 5 | 3 | 5 | 2 | 1 | 1 | 4 | 1 | 4 | 3 | 2 | 1 | 0 |



(a) Step 1 for Heuristic Example - Cmax=35


(b) Step 2 Heuristic Example - Cmax=32



(c) Step 3 Heuristic Example - Cmax=28

(d) Step 4 Heuristic Example - Cmax=27


Figure 3.4. Gannt Charts for Heuristic Example

According to the Table 3.3., we can see from the machine indices without any order yet, the list of jobs to be processed on the machines is as follows: Machine 1 Job List $=\{6,12,13\}, \quad$ Machine 2 Job List $=\{1,2,3,4,8,9,15\}, \quad$ and Machine 3 Job List $=\{5,7,10,11,14\}$. Note that numbers in white bars indicate job indices, and black bars represent set up operations. Numbers in the bottom denote timestamps in the Gannt charts. The first step in our heuristic modeling, jobs assigned to machines are processed in random order. To elaborate, we choose one of the jobs from the set of jobs and randomly assign that job to one of the machines as the last assigned job that machine. We update the set of jobs by removing the assigned job from the set. We continue this assignment until the set of jobs is empty. For example,
jobs assigned to machine 3 are 11,7,10,14,5, respectively. The important thing is that each job transition has setup time. At this point, it should be noted that setup time is required for each job transition. Then the completion time is calculated for each machine. You can see all the steps in Figure 3.4. In the first step (a), completion times are 16,26 and 35 for the machines and makespan is 35 . In the improvement step, we remove the last job of the machine with the longest completion time from that machine and assign it to the machine with the shortest finishing time as the last job. When we make this modification in the schedule, we also take the jobs' processing times and setup times. For instance, in step 3 (c), the longest completion time is on the second machine. So, we cut Job 9, the last job of the second machine, and assigned it to the first machine with the shortest completion time. Thus, the makespan reduced from 28 to 27 . One can see the improved schedule in step 4 (d). After modifying the schedule, we update all the metrics, i.e., job completion times and the makespan, and repeat this improvement process until makespan does not improve. In step 5 (e), there is no improvement in makespan. So, we need to stop the algorithm.

## CHAPTER 4

## COMPUTATIONAL STUDY

This section is devoted to analyzing the experiments carried out to minimize the maximum completion time in a parallel machines scheduling problem with sequencedependent setup times. To test the performance of our proposed heuristic, we have conducted a computational study. In this computation study, we have generated 320 test instances. We solved the IP model of the problem for each test instance until we obtained the optimal solution or 1-hour runtime was exceeded, whichever occurs first. We compared heuristic solutions with the IP model solutions. We solved the IP model with CPLEX 12.8 (Zarnikau, 1994) on a computer Intel Core i5-1035G1 CPU 1.19 GHz . Next, we will provide the details of our testbed and comparison results.


Figure 4.1. Combinations for 3 Machines


Figure 4.2. Combinations for 5 Machines

Our testbed comprises four different (number of machines-number of jobs) pairs. In two of these combinations, the number of jobs is twice the number of machines; and in the other combination, the number of jobs is four times the number of machines. The varieties we use are: ( $3 \mathrm{M}-6 \mathrm{~J}$ ), ( $3 \mathrm{M}-12 \mathrm{~J}$ ), ( $5 \mathrm{M}-10 \mathrm{~J}$ ), ( $5 \mathrm{M}-20 \mathrm{~J}$ ). We have constructed a setting for each pair for machine speeds, processing times, and setup times. The full factorial design is the most commonly utilized procedure for two or more factors. Our Design of Experiment (DOE) consists of all possible combinations of levels for all factors. . Kolisch et al. (1999) considered that the total number of experiments for studying $k$ factors at 2 -levels is $2^{k}$. In our problem, we used 3 factors at 2-levels. These factors are machine speeds (V1, V2), process times (P1, P2) and setup times (S1, S2). Therefore, we have $8 \times 4=32$ combinations.

As shown in Figure 4.1 and Figure 4.2, a total of 32 combinations were created in our experimental study, 16 combinations for 3 machines and 16 combinations for 5 machines. For example, when considering 3 machines (3M) combinations, we must first look at how many jobs we select. For this, we have two options, 6 jobs or 12 jobs. When we continue with 6 jobs (6J), we will have to decide on the machine speed. Assuming that we have chosen the machine speed as the first machine speed range (V1), we must decide on the processing time in the next step. We have two options for this. Let's assume that we continue with the second processing time interval (P2); the situation we need to decide in the last step will be the setup time interval. Again, we have two options for this. Assuming we choose the first range (S1), finally, we will have the combination of $3 \mathrm{M}-6 \mathrm{~J}-\mathrm{V} 1-\mathrm{P} 2-\mathrm{S} 1$ as the encoding.

Table 4.1. Testbed for the Computational Study

| Factors | Notation |
| :---: | :---: |
| 3 Machines - 6 Jobs | 3M-6J |
| 3 Machines - 12 Jobs | 3M-12J |
| 5 Machines - 10 Jobs | 5M-10J |
| 5 Machines - 20 Jobs | 5M-20J |
| Machine Speed Range $1=\mathrm{U}$ [0.50, 1.50$]$ | V1 |
| Machine Speed Range 2 $=\mathrm{U}[0.85,1.15]$ | V2 |
| Process Times Range $1=\mathrm{U}[5,45]$ | P1 |
| Process Times Range $2=\mathrm{U}[15,35]$ | P2 |
| Setup Times Range $1=\mathrm{U}[1,5]$ | S1 |
| Setup Times Range $2=$ U [2,4] | S2 |

Machine speeds are randomly generated either from Uniform [0.50,1.50] distribution or Uniform [0.85, 1.15]. Processing times are generated either from Uniform [5,45] distribution or Uniform [15,35], and setup times are generated either from Uniform [1,5] distribution or Uniform [2,4]. We also have ten different variates for each of 32 combinations. We summarize our testbed in Table 4.1.

Table 4.2. Average CPLEX and Heuristic Solutions

| \# | Combinations | CPLEX |  |  | Heuristic |  | \% Gap <br> Between Cmax |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | $\frac{\operatorname{ain}}{4} \text { Ě }$ |  | $\frac{\text { eio }}{4}$ |  |  |
| 1 | 3M-6J-V1-P1-S1 | 1 | 53.819 | 0.128 | 54.7181 | 0.037 | 1.67\% |
| 2 | 3M-6J-V1-P1-S2 | 1 | 54.451 | 0.156 | 55.1682 | 0.0235 | 1.32\% |
| 3 | 3M-6J-V1-P2-S1 | 1 | 53.958 | 0.164 | 54.7086 | 0.0324 | 1.39\% |
| 4 | 3M-6J-V1-P2-S2 | 1 | 54.635 | 0.147 | 55.1078 | 0.047 | 0.87\% |
| 5 | 3M-6J-V2-P1-S1 | 1 | 51.559 | 0.133 | 52.2999 | 0.0346 | 1.44\% |
| 6 | 3M-6J-V2-P1-S2 | 1 | 51.979 | 0.158 | 52.4425 | 0.0333 | 0.89\% |
| 7 | 3M-6J-V2-P2-S1 | 1 | 51.964 | 0.147 | 52.379 | 0.0289 | 0.80\% |
| 8 | 3M-6J-V2-P2-S2 | 1 | 52.254 | 0.167 | 52.4746 | 0.0278 | 0.42\% |
| 9 | 3M-12J-V1-P1-S1 | 0 | 100.236 | 3600.494 | 104.878 | 0.0476 | 4.63\% |
| 10 | 3M-12J-V1-P1-S2 | 0 | 102.260 | 3600.599 | 105.339 | 0.0474 | 3.01\% |
| 11 | 3M-12J-V1-P2-S1 | 0 | 103.110 | 3600.616 | 107.831 | 0.0655 | 4.58\% |
| 12 | 3M-12J-V1-PS-S2 | 0 | 105.152 | 3600.653 | 107.947 | 0.1011 | 2.66\% |
| 13 | 3M-12J-V2-P1-S1 | 0 | 99.544 | 3600.518 | 103.875 | 0.0595 | 4.35\% |
| 14 | 3M-12J-V2-P1-S2 | 0 | 101.515 | 3600.670 | 104.242 | 0.066 | 2.69\% |
| 15 | 3M-12J-V2-P2-S1 | 0 | 102.431 | 3601.070 | 107.159 | 0.0579 | 4.62\% |
| 16 | 3M-12J-V2-P2-S2 | 0 | 104.211 | 3600.924 | 107.281 | 0.0882 | 2.95\% |
| 17 | 5M-10J-V1-P1-S1 | 1 | 53.515 | 34.908 | 56.6446 | 0.0541 | 5.85\% |
| 18 | 5M-10J-V1-P1-S2 | 1 | 53.671 | 42.700 | 56.8202 | 0.0721 | 5.87\% |
| 19 | 5M-10J-V1-P2-S1 | 1 | 56.562 | 66.163 | 60.8473 | 0.0656 | 7.58\% |
| 20 | 5M-10J-V1-P2-S2 | 1 | 57.333 | 80.002 | 61.0528 | 0.0907 | 6.49\% |
| 21 | 5M-10J-V2-P1-S1 | 1 | 52.207 | 38.833 | 55.5779 | 0.1111 | 6.46\% |
| 22 | 5M-10J-V2-P1-S2 | 1 | 52.536 | 46.024 | 55.5269 | 0.0908 | 5.69\% |
| 23 | 5M-10J-V2-P2-S1 | 1 | 53.344 | 26.022 | 56.1497 | 0.0948 | 5.26\% |
| 24 | 5M-10J-V2-P2-S2 | 1 | 53.784 | 30.281 | 56.5074 | 0.1553 | 5.06\% |
| 25 | 5M-20J-V1-P1-S1 | 0 | 103.580 | 3600.728 | 108.895 | 0.1688 | 5.13\% |
| 26 | 5M-20J-V1-P1-S2 | 0 | 105.403 | 3600.780 | 109.938 | 0.0667 | 4.30\% |
| 27 | 5M-20J-V1-P2-S1 | 0 | 108.010 | 3601.233 | 114.281 | 0.1128 | 5.81\% |
| 28 | 5M-20J-V1-PS-S2 | 0 | 109.874 | 3600.917 | 114.465 | 0.0838 | 4.18\% |
| 29 | 5M-20J-V2-P1-S1 | 0 | 104.247 | 3600.644 | 110.179 | 0.0661 | 5.69\% |
| 30 | 5M-20J-V2-P1-S2 | 0 | 105.790 | 3600.724 | 111.048 | 0.0643 | 4.97\% |
| 31 | 5M-20J-V2-P2-S1 | 0 | 105.580 | 3600.431 | 112.523 | 0.0991 | 6.58\% |
| 32 | 5M-20J-V2-P2-S2 | 0 | 107.593 | 3600.403 | 113.1 | 0.1045 | 5.12\% |

The computational results of the proposed heuristic algorithm are presented in this section. To evaluate the performance of the proposed heuristic methods, 320 instances with varying job sizes and machine sizes are developed. All proposed heuristic algorithms are coded in Python programming language and heuristic algorithms solve all instances within a few seconds on an Intel Core i5 2.40 GHz computer. The relative percent deviations (RPD) from the optimal results are reported for each heuristic algorithm as below:

$$
\begin{equation*}
\text { RHD }(\% \text { Gap })=\frac{C_{\text {max }}^{\text {heuristic }}-C_{\text {max }}^{\text {optimal }}}{C_{\text {max }}^{\text {optimal }}} \times 100 \tag{1}
\end{equation*}
$$

It was explained in the previous sections that an experimental design was created by producing ten different instances for each of the 32 data combinations. In Table 4.2, solutions were obtained by taking the average of each combination's ten different instance files. If the algorithm could find the optimal value within the 1 -hour time limit, the third column in the table was indicated as 1 . If it could not reach the optimal within this time constraint, it was specified as 0 . Also, the \% Gap results in the eighth column were obtained using Equation (1) explained above.

Table 4.3. CPLEX - Average Solutions

|  | V1 | V2 | P1 | P2 | S1 | S2 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| 3M-6J | 54.22 | 51.94 | 52.95 | 53.20 | 52.83 | 53.33 |
| 3M-12J | 102.69 | 101.93 | 100.89 | 103.73 | 101.33 | 103.28 |
| 5M-10J | 55.27 | 52.97 | 52.98 | 55.26 | 53.91 | 54.33 |
| 5M-20J | 106.72 | 105.80 | 104.75 | 107.76 | 105.35 | 107.16 |

Table 4.4. Heuristic - Average Solutions

|  | V1 | V2 | P1 | P2 | S1 | S2 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| 3M-6J | 54.93 | 52.40 | 53.66 | 53.67 | 53.53 | 53.80 |
| 3M-12J | 106.50 | 105.64 | 104.58 | 107.55 | 105.94 | 106.20 |
| 5M-10J | 58.84 | 55.94 | 56.14 | 58.64 | 57.30 | 57.48 |
| 5M-20J | 111.89 | 111.71 | 110.01 | 113.59 | 111.47 | 112.14 |

The most important result of this study is that while CPLEX 12.8 takes 22.88 minutes on average and the heuristic algorithm achieves these results only in 0.062 minutes. Moreover, Tables 4.3 and 4.4 show the average solutions of the CPLEX model and
heuristic model. The average solutions obtained with the heuristic have an approximately $4 \%$ Gap value for an average CPLEX solution.

Table 4.5. Mean of Heuristic \% Gap

|  | V1 | V2 | P1 | P2 | S1 | S2 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 3M-6J | $1.33 \%$ | $0.97 \%$ | $1.47 \%$ | $0.83 \%$ | $1.34 \%$ |
| 3M-12J | $3.74 \%$ | $3.68 \%$ | $3.68 \%$ | $3.74 \%$ | $4.59 \%$ | $2.83 \%$ |
| 5M-10J | $6.43 \%$ | $5.75 \%$ | $6.16 \%$ | $6.02 \%$ | $6.35 \%$ | $5.83 \%$ |
| 5M-20J | $4.90 \%$ | $5.60 \%$ | $5.10 \%$ | $5.40 \%$ | $5.85 \%$ | $4.65 \%$ |

Table 4.6. Median of Heuristic \% Gap

|  | V1 | V2 | P1 | P2 | S1 | S2 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| 3M-6J | $0.00 \%$ | $0.00 \%$ | $0.00 \%$ | $0.00 \%$ | $0.00 \%$ | $0.00 \%$ |
| 3M-12J | $0.88 \%$ | $0.00 \%$ | $0.00 \%$ | $2.03 \%$ | $1.47 \%$ | $0.88 \%$ |
| 5M-10J | $0.78 \%$ | $0.00 \%$ | $0.74 \%$ | $0.00 \%$ | $0.00 \%$ | $0.35 \%$ |
| 5M-20J | $0.39 \%$ | $1.21 \%$ | $0.39 \%$ | $0.87 \%$ | $1.20 \%$ | $0.39 \%$ |

In Tables 4.5 and 4.6 you can see the impact of all our factors on the results. Table 4.5. indicates the mean calculations of these \% Gap values, while Table 4.6. is for the median calculations.

Table 4.7. \% Gap Deviation for All Instances

|  | $\mathbf{\leq 1 \%}$ | $\mathbf{1 \% - 5 \%}$ | $\mathbf{5 \% - 1 0 \%}$ | $\geq \mathbf{1 0 \%}$ |
| :---: | :---: | :---: | :---: | :---: |
| Optimal | 50 | 56 | 48 | 6 |
| Not Optimal | 1 | 102 | 57 | 0 |
| $\boldsymbol{\%}$ | $15.94 \%$ | $49.38 \%$ | $32.81 \%$ | $1.88 \%$ |

We compared the results we obtained after solving the mathematical modeling and the proposed heuristic algorithm, and we calculated the \% Gap deviations at certain percentage intervals using Equation (1). The percentage values in the last row of Table 4.7. compare the solutions in that range with 320 instances. For example, 48 optimal and 57 non-optimal results were found between $5 \%$ and $10 \%$ gap intervals. In other words, a total of 105 instances gave a solution in this range, and this has a rate of $32.81 \%$ among 320 instances.

As we explained in the heuristic section, the system we have established consists of two main parts: random assignment and improvement subroutine. The contribution of the improvement subroutine step to the overall performance of the heuristic is $73.34 \%$
on average. This means that the improvements made on the initial solution created due to random assignment have made the system much more intelligent.

Another significant result in this experimental design is when the CPLEX 12.8 runs with a given one-hour time limitation. 160 out of 320 instances can be found optimal result and proposed randomized heuristic results found 19 out of these 160 instances. This means that our randomized heuristic algorithm can achieve optimal results with a rate of $11.88 \%$ on average.

## CHAPTER 5

## CONCLUSION AND FUTURE RESEARCH

This thesis considered a uniform parallel machine scheduling problem with sequencedependent setup times to minimize the maximum completion time (makespan). We present an IP formulation, which clearly describes our problem and can be used to obtain optimal solutions for small-sized problems. Our problem is NP-hard which means that the time to obtain the optimal solution to the problem increases exponentially as the size of the problem increases. Therefore, we propose a randomized heuristic algorithm with two stages: random assignment and improvement subroutine. In the first step of this two-stage algorithm, we assign random jobs to the machines in random order and continue this assignment until the job list is empty. We get a feasible solution at the end of this first algorithm step. Then, we calculate the completion times and the makespan and move on to the second step with this information. In the second step, we first determine the last job of the machine with the largest completion time and remove it from the machine with the shortest completion time as the last job. When we do these modifications, we consider the machine speeds and repeat this improvement process until makespan does not improve. The primary purpose of this improvement subroutine step is balancing loads of the machines, reducing the completion times, and reducing the makespan.

Our thesis has four different (number of machines-number of jobs) pairs for data. In two of these combinations, the number of jobs is twice the number of machines and in the other combination, the number of jobs is four times the number of machines. The performance of the algorithm is tested with 320 instance sets. We create these instances using the full factorial design of experiments (DOE). The total number of experiments for studying k factors at 2 -levels is $2^{k}$. In our problem, we used 3 factors at 2 -levels. These factors are machine speeds, process times and setup times. Also, all these data are randomly generated either from specified Uniform intervals. Therefore, we have 32 combinations and all combinations have ten replications.

In this study, we compared the results after solving the mathematical modeling and the proposed heuristic algorithm, and we calculated the \% Gap deviations at certain percentage intervals using. This study's most important numerical result is that the proposed mathematical model takes 22.88 minutes on average, and the heuristic algorithm achieves these results only in 0.062 minutes. The heuristic has an approximately $4 \%$ Gap value for an average. Also, the contribution of the improvement subroutine step to the overall performance of the heuristic is $73.34 \%$ on average. Another significant result in this experimental design is when the CPLEX runs with a given one-hour time limitation, we can find the optimal solution in half of the instances in CPLEX, whereas this number is only 19 out of 160 instances. This means that our randomized heuristic algorithm can achieve optimal results with a rate of $11.88 \%$ on average. Finally, we can conclude that the proposed randomized heuristic algorithm is very efficient and provides highly acceptable solutions.

Future work can be addressed as follows: (1) The heuristic algorithm presented in this study can be more effective and intelligent. (2) While generating the data, the size of the problem can be increased by expanding the uniform intervals, or benchmarking examples in the literature can be used for computational experimentation.

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## APPENDIX 1 - CPLEX SOLUTIONS FOR ALL INSTANCES

|  |  | CPLEX Solution |  |  |  | Lower Bound |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Opt? | $C_{\text {max }}$ | Run Time (sec.) | $\begin{gathered} \text { \% } \\ \text { Gap } \end{gathered}$ | $C_{\text {max }}$ | $\begin{gathered} \text { \% } \\ \text { Gap } \end{gathered}$ |
| $\begin{aligned} & \vec{a} \\ & \text { Bे } \\ & \text { O} \\ & \text { 合 } \end{aligned}$ | 3M-6J-V1-P1-S1-D1 | 1 | 45.256 | 0.109 | 0\% | 42.405 | 6.30\% |
|  | 3M-6J-V1-P1-S1-D2 | 1 | 52.264 | 0.172 | 0\% | 47.511 | 9.09\% |
|  | 3M-6J-V1-P1-S1-D3 | 1 | 63.314 | 0.14 | 0\% | 58.535 | 7.55\% |
|  | 3M-6J-V1-P1-S1-D4 | 1 | 67.331 | 0.156 | 0\% | 62.057 | 7.83\% |
|  | 3M-6J-V1-P1-S1-D5 | 1 | 68.858 | 0.094 | 0\% | 65.972 | 4.19\% |
|  | 3M-6J-V1-P1-S1-D6 | 1 | 40.941 | 0.094 | 0\% | 37.528 | 8.34\% |
|  | 3M-6J-V1-P1-S1-D7 | 1 | 42.482 | 0.14 | 0\% | 40.497 | 4.67\% |
|  | 3M-6J-V1-P1-S1-D8 | 1 | 44.025 | 0.141 | 0\% | 39.905 | 9.36\% |
|  | 3M-6J-V1-P1-S1-D9 | 1 | 57.809 | 0.157 | 0\% | 54.594 | 5.56\% |
|  | 3M-6J-V1-P1-S1-D10 | 1 | 55.908 | 0.078 | 0\% | 48.16 | 13.86\% |
|  | 3M-6J-V1-P1-S2-D1 | 1 | 47.313 | 0.141 | 0\% | 42.405 | 10.37\% |
|  | 3M-6J-V1-P1-S2-D2 | 1 | 51.89 | 0.141 | 0\% | 47.511 | 8.44\% |
|  | 3M-6J-V1-P1-S2-D3 | 1 | 62.409 | 0.156 | 0\% | 58.535 | 6.21\% |
|  | 3M-6J-V1-P1-S2-D4 | 1 | 67.331 | 0.078 | 0\% | 62.057 | 7.83\% |
|  | 3M-6J-V1-P1-S2-D5 | 1 | 69.421 | 0.203 | 0\% | 65.972 | 4.97\% |
|  | 3M-6J-V1-P1-S2-D6 | 1 | 42.305 | 0.188 | 0\% | 37.528 | 11.29\% |
|  | 3M-6J-V1-P1-S2-D7 | 1 | 43.98 | 0.156 | 0\% | 40.497 | 7.92\% |
|  | 3M-6J-V1-P1-S2-D8 | 1 | 45.359 | 0.188 | 0\% | 39.905 | 12.02\% |
|  | 3M-6J-V1-P1-S2-D9 | 1 | 57.839 | 0.235 | 0\% | 54.594 | 5.61\% |
|  | 3M-6J-V1-P1-S2-D10 | 1 | 56.664 | 0.078 | 0\% | 48.16 | 15.01\% |
|  | 3M-6J-V1-P2-S1-D1 | 1 | 49.37 | 0.25 | 0\% | 44.975 | 8.90\% |
|  | 3M-6J-V1-P2-S1-D2 | 1 | 63.865 | 0.157 | 0\% | 60.014 | 6.03\% |
|  | 3M-6J-V1-P2-S1-D3 | 1 | 54.411 | 0.172 | 0\% | 52.523 | 3.47\% |
|  | 3M-6J-V1-P2-S1-D4 | 1 | 69.563 | 0.14 | 0\% | 64.835 | 6.80\% |
|  | 3M-6J-V1-P2-S1-D5 | 1 | 52.065 | 0.14 | 0\% | 48.732 | 6.40\% |
|  | 3M-6J-V1-P2-S1-D6 | 1 | 46.399 | 0.141 | 0\% | 41.907 | 9.68\% |
|  | 3M-6J-V1-P2-S1-D7 | 1 | 50.794 | 0.156 | 0\% | 46.361 | 8.73\% |
|  | 3M-6J-V1-P2-S1-D8 | 1 | 48.164 | 0.125 | 0\% | 46.261 | 3.95\% |
|  | 3M-6J-V1-P2-S1-D9 | 1 | 55.844 | 0.125 | 0\% | 52.508 | 5.97\% |
|  | 3M-6J-V1-P2-S1-D10 | 1 | 49.108 | 0.234 | 0\% | 46.365 | 5.59\% |
| $\begin{aligned} & \text { + } \\ & \stackrel{\rightharpoonup}{b} \\ & \stackrel{\rightharpoonup}{c} \end{aligned}$ | 3M-6J-V1-P2-S2-D1 | 1 | 50.398 | 0.188 | 0\% | 44.975 | 10.76\% |
|  | 3M-6J-V1-P2-S2-D2 | 1 | 65.33 | 0.172 | 0\% | 60.014 | 8.14\% |
|  | 3M-6J-V1-P2-S2-D3 | 1 | 55.173 | 0.109 | 0\% | 52.523 | 4.80\% |
|  | 3M-6J-V1-P2-S2-D4 | 1 | 71.174 | 0.156 | 0\% | 64.835 | 8.91\% |
|  | 3M-6J-V1-P2-S2-D5 | 1 | 52.509 | 0.156 | 0\% | 48.732 | 7.19\% |
|  | 3M-6J-V1-P2-S2-D6 | 1 | 46.019 | 0.125 | 0\% | 41.907 | 8.94\% |
|  | 3M-6J-V1-P2-S2-D7 | 1 | 49.951 | 0.156 | 0\% | 46.361 | 7.19\% |
|  | 3M-6J-V1-P2-S2-D8 | 1 | 50.84 | 0.172 | 0\% | 46.261 | 9.01\% |
|  | 3M-6J-V1-P2-S2-D9 | 1 | 55.844 | 0.11 | 0\% | 52.508 | 5.97\% |
|  | 3M-6J-V1-P2-S2-D10 | 1 | 49.108 | 0.125 | 0\% | 46.365 | 5.59\% |


|  |  | CPLEX Solution |  |  |  | Lower Bound |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Opt? | $C_{\text {max }}$ | Run Time (sec.) | $\begin{gathered} \text { \% } \\ \text { Gap } \end{gathered}$ | $C_{\text {max }}$ | $\begin{gathered} \% \\ \text { Gap } \end{gathered}$ |
| $\begin{aligned} & \text { n } \\ & \text { S } \\ & 0 \\ & \frac{8}{0} \end{aligned}$ | 3M-6J-V2-P1-S1-D1 | 1 | 46.369 | 0.156 | 0\% | 43.509 | 6.17\% |
|  | 3M-6J-V2-P1-S1-D2 | 1 | 38.307 | 0.125 | 0\% | 35.187 | 8.14\% |
|  | 3M-6J-V2-P1-S1-D3 | 1 | 67.85 | 0.14 | 0\% | 60.693 | 10.55\% |
|  | 3M-6J-V2-P1-S1-D4 | 1 | 53.589 | 0.109 | 0\% | 48.766 | 9.00\% |
|  | 3M-6J-V2-P1-S1-D5 | 1 | 62.387 | 0.094 | 0\% | 59.17 | 5.16\% |
|  | 3M-6J-V2-P1-S1-D6 | 1 | 41.24 | 0.172 | 0\% | 39.225 | 4.89\% |
|  | 3M-6J-V2-P1-S1-D7 | 1 | 44.407 | 0.11 | 0\% | 41.309 | 6.98\% |
|  | 3M-6J-V2-P1-S1-D8 | 1 | 40.878 | 0.156 | 0\% | 38.311 | 6.28\% |
|  | 3M-6J-V2-P1-S1-D9 | 1 | 56.758 | 0.094 | 0\% | 52.992 | 6.64\% |
|  | 3M-6J-V2-P1-S1-D10 | 1 | 63.805 | 0.172 | 0\% | 51.887 | 18.68\% |
|  | 3M-6J-V2-P1-S2-D1 | 1 | 47.394 | 0.157 | 0\% | 43.509 | 8.20\% |
|  | 3M-6J-V2-P1-S2-D2 | 1 | 39.979 | 0.219 | 0\% | 35.187 | 11.99\% |
|  | 3M-6J-V2-P1-S2-D3 | 1 | 66.881 | 0.187 | 0\% | 60.693 | 9.25\% |
|  | 3M-6J-V2-P1-S2-D4 | 1 | 53.589 | 0.187 | 0\% | 48.766 | 9.00\% |
|  | 3M-6J-V2-P1-S2-D5 | 1 | 61.877 | 0.203 | 0\% | 59.17 | 4.37\% |
|  | 3M-6J-V2-P1-S2-D6 | 1 | 42.887 | 0.094 | 0\% | 39.225 | 8.54\% |
|  | 3M-6J-V2-P1-S2-D7 | 1 | 44.885 | 0.141 | 0\% | 41.309 | 7.97\% |
|  | 3M-6J-V2-P1-S2-D8 | 1 | 41.748 | 0.109 | 0\% | 38.311 | 8.23\% |
|  | 3M-6J-V2-P1-S2-D9 | 1 | 57.659 | 0.141 | 0\% | 52.992 | 8.09\% |
|  | 3M-6J-V2-P1-S2-D10 | 1 | 62.894 | 0.141 | 0\% | 51.887 | 17.50\% |
|  | 3M-6J-V2-P2-S1-D1 | 1 | 50.079 | 0.219 | 0\% | 46.146 | 7.85\% |
|  | 3M-6J-V2-P2-S1-D2 | 1 | 48.623 | 0.141 | 0\% | 44.447 | 8.59\% |
|  | 3M-6J-V2-P2-S1-D3 | 1 | 58.157 | 0.094 | 0\% | 54.459 | 6.36\% |
|  | 3M-6J-V2-P2-S1-D4 | 1 | 54.196 | 0.172 | 0\% | 50.95 | 5.99\% |
|  | 3M-6J-V2-P2-S1-D5 | 1 | 56.233 | 0.141 | 0\% | 52.74 | 6.21\% |
|  | 3M-6J-V2-P2-S1-D6 | 1 | 45.627 | 0.156 | 0\% | 43.801 | 4.00\% |
|  | 3M-6J-V2-P2-S1-D7 | 1 | 50.164 | 0.11 | 0\% | 46.342 | 7.62\% |
|  | 3M-6J-V2-P2-S1-D8 | 1 | 46.967 | 0.125 | 0\% | 44.414 | 5.44\% |
|  | 3M-6J-V2-P2-S1-D9 | 1 | 53.995 | 0.172 | 0\% | 50.966 | 5.61\% |
|  | 3M-6J-V2-P2-S1-D10 | 1 | 55.602 | 0.141 | 0\% | 49.953 | 10.16\% |
| $\begin{aligned} & \infty \\ & \stackrel{\infty}{0} \\ & \stackrel{\text { ®}}{0} \end{aligned}$ | 3M-6J-V2-P2-S2-D1 | 1 | 49.411 | 0.125 | 0\% | 46.146 | 6.61\% |
|  | 3M-6J-V2-P2-S2-D2 | 1 | 48.623 | 0.172 | 0\% | 44.447 | 8.59\% |
|  | 3M-6J-V2-P2-S2-D3 | 1 | 58.157 | 0.094 | 0\% | 54.459 | 6.36\% |
|  | 3M-6J-V2-P2-S2-D4 | 1 | 55.182 | 0.281 | 0\% | 50.95 | 7.67\% |
|  | 3M-6J-V2-P2-S2-D5 | 1 | 55.152 | 0.218 | 0\% | 52.74 | 4.37\% |
|  | 3M-6J-V2-P2-S2-D6 | 1 | 46.786 | 0.234 | 0\% | 43.801 | 6.38\% |
|  | 3M-6J-V2-P2-S2-D7 | 1 | 50.164 | 0.156 | 0\% | 46.342 | 7.62\% |
|  | 3M-6J-V2-P2-S2-D8 | 1 | 47.969 | 0.109 | 0\% | 44.414 | 7.41\% |
|  | 3M-6J-V2-P2-S2-D9 | 1 | 55.168 | 0.14 | 0\% | 50.966 | 7.62\% |
|  | 3M-6J-V2-P2-S2-D10 | 1 | 55.931 | 0.14 | 0\% | 49.953 | 10.69\% |


|  |  | CPLEX Solution |  |  |  | Lower Bound |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Opt? | $C_{\text {max }}$ | Run Time (sec.) | $\begin{gathered} \% \\ \text { Gap } \end{gathered}$ | $C_{\text {max }}$ | $\begin{gathered} \text { \% } \\ \text { Gap } \end{gathered}$ |
| $\begin{aligned} & \text { a } \\ & \text { 官 } \\ & 0 \\ & \text { 合 } \end{aligned}$ | 3M-12J-V1-P1-S1-D1 | 0 | 109.776 | 3600.36 | 52\% | 105.117 | 4.24\% |
|  | 3M-12J-V1-P1-S1-D2 | 0 | 74.013 | 3600.453 | 41\% | 70.429 | 4.84\% |
|  | 3M-12J-V1-P1-S1-D3 | 0 | 110.393 | 3600.86 | 48\% | 106.158 | 3.84\% |
|  | 3M-12J-V1-P1-S1-D4 | 0 | 80.741 | 3600.281 | 47\% | 76.653 | 5.06\% |
|  | 3M-12J-V1-P1-S1-D5 | 0 | 105.959 | 3600.391 | 48\% | 101.011 | 4.67\% |
|  | 3M-12J-V1-P1-S1-D6 | 0 | 86.795 | 3600.297 | 47\% | 81.708 | 5.86\% |
|  | 3M-12J-V1-P1-S1-D7 | 0 | 138.631 | 3600.281 | 45\% | 131.798 | 4.93\% |
|  | 3M-12J-V1-P1-S1-D8 | 0 | 83.196 | 3600.953 | 46\% | 78.909 | 5.15\% |
|  | 3M-12J-V1-P1-S1-D9 | 0 | 93.325 | 3600.485 | 45\% | 89.9 | 3.67\% |
|  | 3M-12J-V1-P1-S1-D10 | 0 | 119.529 | 3600.578 | 48\% | 112.76 | 5.66\% |
|  | 3M-12J-V1-P1-S2-D1 | 0 | 112.295 | 3600.547 | 52\% | 105.117 | 6.39\% |
|  | 3M-12J-V1-P1-S2-D2 | 0 | 75.539 | 3600.484 | 48\% | 70.429 | 6.76\% |
|  | 3M-12J-V1-P1-S2-D3 | 0 | 112.46 | 3600.844 | 49\% | 106.158 | 5.60\% |
|  | 3M-12J-V1-P1-S2-D4 | 0 | 82.993 | 3600.625 | 49\% | 76.653 | 7.64\% |
|  | 3M-12J-V1-P1-S2-D5 | 0 | 107.978 | 3600.312 | 48\% | 101.011 | 6.45\% |
|  | 3M-12J-V1-P1-S2-D6 | 0 | 87.817 | 3600.344 | 44\% | 81.708 | 6.96\% |
|  | 3M-12J-V1-P1-S2-D7 | 0 | 142.141 | 3600.266 | 46\% | 131.798 | 7.28\% |
|  | 3M-12J-V1-P1-S2-D8 | 0 | 85.493 | 3600.656 | 49\% | 78.909 | 7.70\% |
|  | 3M-12J-V1-P1-S2-D9 | 0 | 95.378 | 3600.344 | 48\% | 89.9 | 5.74\% |
|  | 3M-12J-V1-P1-S2-D10 | 0 | 120.509 | 3601.563 | 51\% | 112.76 | 6.43\% |
|  | 3M-12J-V1-P2-S1-D1 | 0 | 96.167 | 3600.594 | 53\% | 91.716 | 4.63\% |
|  | 3M-12J-V1-P2-S1-D2 | 0 | 77.883 | 3600.703 | 51\% | 73.571 | 5.54\% |
|  | 3M-12J-V1-P2-S1-D3 | 0 | 100.793 | 3600.625 | 47\% | 96.243 | 4.51\% |
|  | 3M-12J-V1-P2-S1-D4 | 0 | 86.892 | 3600.422 | 52\% | 82.737 | 4.78\% |
|  | 3M-12J-V1-P2-S1-D5 | 0 | 102.088 | 3600.656 | 55\% | 97.405 | 4.59\% |
|  | 3M-12J-V1-P2-S1-D6 | 0 | 89.867 | 3600.578 | 52\% | 85.34 | 5.04\% |
|  | 3M-12J-V1-P2-S1-D7 | 0 | 139.407 | 3601.109 | 54\% | 132.954 | 4.63\% |
|  | 3M-12J-V1-P2-S1-D8 | 0 | 91.277 | 3600.563 | 46\% | 87.75 | 3.86\% |
|  | 3M-12J-V1-P2-S1-D9 | 0 | 90.504 | 3600.531 | 51\% | 87.019 | 3.85\% |
|  | 3M-12J-V1-P2-S1-D10 | 0 | 156.225 | 3600.375 | 57\% | 149.007 | 4.62\% |
|  | 3M-12J-V1-P2-S2-D1 | 0 | 97.773 | 3600.218 | 54\% | 91.716 | 6.19\% |
|  | 3M-12J-V1-P2-S2-D2 | 0 | 79.053 | 3600.531 | 51\% | 73.571 | 6.93\% |
|  | 3M-12J-V1-P2-S2-D3 | 0 | 102.78 | 3600.688 | 51\% | 96.243 | 6.36\% |
|  | 3M-12J-V1-P2-S2-D4 | 0 | 89.316 | 3600.531 | 54\% | 82.737 | 7.37\% |
|  | 3M-12J-V1-P2-S2-D5 | 0 | 103.32 | 3600.641 | 54\% | 97.405 | 5.72\% |
|  | 3M-12J-V1-P2-S2-D6 | 0 | 91.883 | 3600.609 | 54\% | 85.34 | 7.12\% |
|  | 3M-12J-V1-P2-S2-D7 | 0 | 141.65 | 3600.781 | 55\% | 132.954 | 6.14\% |
|  | 3M-12J-V1-P2-S2-D8 | 0 | 94.581 | 3600.687 | 51\% | 87.75 | 7.22\% |
|  | 3M-12J-V1-P2-S2-D9 | 0 | 92.593 | 3601.062 | 53\% | 87.019 | 6.02\% |
|  | 3M-12J-V1-P2-S2-D10 | 0 | 158.572 | 3600.782 | 57\% | 149.007 | 6.03\% |


|  |  | CPLEX Solution |  |  |  | Lower Bound |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Opt? | $C_{\text {max }}$ | Run Time (sec.) | $\begin{gathered} \text { \% } \\ \text { Gap } \end{gathered}$ | $C_{\text {max }}$ | $\begin{gathered} \% \\ \text { Gap } \end{gathered}$ |
| $\begin{aligned} & \text { n} \\ & \text { eै } \\ & 0 \\ & \underset{\sim}{c} \end{aligned}$ | 3M-12J-V2-P1-S1-D1 | 0 | 104.099 | 3601.032 | 51\% | 100.032 | 3.91\% |
|  | 3M-12J-V2-P1-S1-D2 | 0 | 88.33 | 3601.078 | 50\% | 82.876 | 6.17\% |
|  | 3M-12J-V2-P1-S1-D3 | 0 | 122.033 | 3600.666 | 50\% | 116.344 | 4.66\% |
|  | 3M-12J-V2-P1-S1-D4 | 0 | 87.073 | 3600.082 | 51\% | 81.652 | 6.23\% |
|  | 3M-12J-V2-P1-S1-D5 | 0 | 102.204 | 3600.076 | 51\% | 97.45 | 4.65\% |
|  | 3M-12J-V2-P1-S1-D6 | 0 | 91.695 | 3600.081 | 55\% | 87.341 | 4.75\% |
|  | 3M-12J-V2-P1-S1-D7 | 0 | 104.483 | 3601.07 | 49\% | 99.178 | 5.08\% |
|  | 3M-12J-V2-P1-S1-D8 | 0 | 85.043 | 3600.076 | 54\% | 79.901 | 6.05\% |
|  | 3M-12J-V2-P1-S1-D9 | 0 | 103.456 | 3601.012 | 49\% | 99.327 | 3.99\% |
|  | 3M-12J-V2-P1-S1-D10 | 0 | 107.027 | 3600.005 | 49\% | 101.753 | 4.93\% |
| $\begin{aligned} & \pm \\ & \stackrel{\rightharpoonup}{3} \\ & \stackrel{\rightharpoonup}{c} \\ & \underset{\sim}{c} \end{aligned}$ | 3M-12J-V2-P1-S2-D1 | 0 | 107.161 | 3600.656 | 53\% | 100.032 | 6.65\% |
|  | 3M-12J-V2-P1-S2-D2 | 0 | 89.29 | 3600.765 | 48\% | 82.876 | 7.18\% |
|  | 3M-12J-V2-P1-S2-D3 | 0 | 123.124 | 3600.656 | 54\% | 116.344 | 5.51\% |
|  | 3M-12J-V2-P1-S2-D4 | 0 | 87.999 | 3600.391 | 47\% | 81.652 | 7.21\% |
|  | 3M-12J-V2-P1-S2-D5 | 0 | 104.454 | 3600.906 | 47\% | 97.45 | 6.71\% |
|  | 3M-12J-V2-P1-S2-D6 | 0 | 94.439 | 3601.281 | 50\% | 87.341 | 7.52\% |
|  | 3M-12J-V2-P1-S2-D7 | 0 | 107.927 | 3600.212 | 54\% | 99.178 | 8.11\% |
|  | 3M-12J-V2-P1-S2-D8 | 0 | 86.326 | 3600.068 | 57\% | 79.901 | 7.44\% |
|  | 3M-12J-V2-P1-S2-D9 | 0 | 105.24 | 3601.009 | 51\% | 99.327 | 5.62\% |
|  | 3M-12J-V2-P1-S2-D10 | 0 | 109.189 | 3600.759 | 50\% | 101.753 | 6.81\% |
| $\begin{aligned} & \text { n } \\ & \text { ? } \\ & 0 \\ & \text { env } \end{aligned}$ | 3M-12J-V2-P2-S1-D1 | 0 | 101.968 | 3600.687 | 48\% | 97.362 | 4.52\% |
|  | 3M-12J-V2-P2-S1-D2 | 0 | 91.049 | 3600.969 | 49\% | 86.573 | 4.92\% |
|  | 3M-12J-V2-P2-S1-D3 | 0 | 110.453 | 3600.766 | 49\% | 105.477 | 4.51\% |
|  | 3M-12J-V2-P2-S1-D4 | 0 | 93.557 | 3600.843 | 51\% | 88.132 | 5.80\% |
|  | 3M-12J-V2-P2-S1-D5 | 0 | 104.454 | 3601.125 | 50\% | 100.122 | 4.15\% |
|  | 3M-12J-V2-P2-S1-D6 | 0 | 96.586 | 3600.922 | 50\% | 91.223 | 5.55\% |
|  | 3M-12J-V2-P2-S1-D7 | 0 | 111.743 | 3600.656 | 51\% | 106.666 | 4.54\% |
|  | 3M-12J-V2-P2-S1-D8 | 0 | 93.141 | 3600.75 | 51\% | 88.852 | 4.60\% |
|  | 3M-12J-V2-P2-S1-D9 | 0 | 99.997 | 3603.609 | 48\% | 96.143 | 3.85\% |
|  | 3M-12J-V2-P2-S1-D10 | 0 | 121.36 | 3600.375 | 52\% | 114.645 | 5.53\% |
| $\begin{aligned} & 0 \\ & \stackrel{0}{3} \\ & 0 \\ & \text { en } \end{aligned}$ | 3M-12J-V2-P2-S2-D1 | 0 | 104.38 | 3600.688 | 52\% | 97.362 | 6.72\% |
|  | 3M-12J-V2-P2-S2-D2 | 0 | 93.05 | 3600.969 | 48\% | 86.573 | 6.96\% |
|  | 3M-12J-V2-P2-S2-D3 | 0 | 112.034 | 3602.578 | 51\% | 105.477 | 5.85\% |
|  | 3M-12J-V2-P2-S2-D4 | 0 | 94.483 | 3600.672 | 50\% | 88.132 | 6.72\% |
|  | 3M-12J-V2-P2-S2-D5 | 0 | 106.255 | 3600.984 | 49\% | 100.122 | 5.77\% |
|  | 3M-12J-V2-P2-S2-D6 | 0 | 98.113 | 3601.029 | 50\% | 91.223 | 7.02\% |
|  | 3M-12J-V2-P2-S2-D7 | 0 | 114.183 | 3601.15 | 48\% | 106.666 | 6.58\% |
|  | 3M-12J-V2-P2-S2-D8 | 0 | 95.341 | 3600.043 | 49\% | 88.852 | 6.81\% |
|  | 3M-12J-V2-P2-S2-D9 | 0 | 102.827 | 3601.056 | 49\% | 96.143 | 6.50\% |
|  | 3M-12J-V2-P2-S2-D10 | 0 | 121.444 | 3600.071 | 52\% | 114.645 | 5.60\% |


|  |  | CPLEX Solution |  |  |  | Lower Bound |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Opt? | $C_{\text {max }}$ | Run Time (sec.) | $\begin{gathered} \% \\ \text { Gap } \end{gathered}$ | $C_{\text {max }}$ | $\begin{gathered} \text { \% } \\ \text { Gap } \end{gathered}$ |
| $\begin{aligned} & \text { Na } \\ & \hat{B} \\ & 0 \\ & \underset{\sim}{c} \end{aligned}$ | 5M-10J-V1-P1-S1-D1 | 1 | 55.568 | 27.187 | 0\% | 53.084 | 4.47\% |
|  | 5M-10J-V1-P1-S1-D2 | 1 | 41.421 | 42.219 | 0\% | 38.877 | 6.14\% |
|  | 5M-10J-V1-P1-S1-D3 | 1 | 64.218 | 55.438 | 0\% | 60.465 | 5.84\% |
|  | 5M-10J-V1-P1-S1-D4 | 1 | 41.156 | 27.594 | 0\% | 38.509 | 6.43\% |
|  | 5M-10J-V1-P1-S1-D5 | 1 | 55.633 | 36.172 | 0\% | 50.31 | 9.57\% |
|  | 5M-10J-V1-P1-S1-D6 | 1 | 56.83 | 33.391 | 0\% | 54.309 | 4.44\% |
|  | 5M-10J-V1-P1-S1-D7 | 1 | 52.655 | 14.047 | 0\% | 48.979 | 6.98\% |
|  | 5M-10J-V1-P1-S1-D8 | 1 | 44.221 | 35.281 | 0\% | 40.559 | 8.28\% |
|  | 5M-10J-V1-P1-S1-D9 | 1 | 58.209 | 25.938 | 0\% | 55.213 | 5.15\% |
|  | 5M-10J-V1-P1-S1-D10 | 1 | 65.235 | 51.812 | 0\% | 61.421 | 5.85\% |
| $\begin{aligned} & \infty \\ & \stackrel{\infty}{3} \\ & 0 \\ & \underset{\sim}{c} \\ & \hline \end{aligned}$ | 5M-10J-V1-P1-S2-D1 | 1 | 55.748 | 33.75 | 0\% | 53.084 | 4.78\% |
|  | 5M-10J-V1-P1-S2-D2 | 1 | 42.328 | 57.844 | 0\% | 38.877 | 8.15\% |
|  | 5M-10J-V1-P1-S2-D3 | 1 | 63.883 | 76.469 | 0\% | 60.465 | 5.35\% |
|  | 5M-10J-V1-P1-S2-D4 | 1 | 42.281 | 32.875 | 0\% | 38.509 | 8.92\% |
|  | 5M-10J-V1-P1-S2-D5 | 1 | 54.715 | 29.078 | 0\% | 50.31 | 8.05\% |
|  | 5M-10J-V1-P1-S2-D6 | 1 | 57.643 | 29.203 | 0\% | 54.309 | 5.78\% |
|  | 5M-10J-V1-P1-S2-D7 | 1 | 52.655 | 14.516 | 0\% | 48.979 | 6.98\% |
|  | 5M-10J-V1-P1-S2-D8 | 1 | 43.789 | 48.75 | 0\% | 40.559 | 7.38\% |
|  | 5M-10J-V1-P1-S2-D9 | 1 | 58.538 | 31.719 | 0\% | 55.213 | 5.68\% |
|  | 5M-10J-V1-P1-S2-D10 | 1 | 65.128 | 72.797 | 0\% | 61.421 | 5.69\% |
| $\begin{aligned} & \stackrel{\rightharpoonup}{2} \\ & \stackrel{3}{3} \\ & \stackrel{y}{c} \\ & \hline \end{aligned}$ | 5M-10J-V1-P2-S1-D1 | 1 | 58.393 | 79.641 | 0\% | 55.776 | 4.48\% |
|  | 5M-10J-V1-P2-S1-D2 | 1 | 43.174 | 54.844 | 0\% | 40.998 | 5.04\% |
|  | 5M-10J-V1-P2-S1-D3 | 1 | 57.887 | 49.766 | 0\% | 53.768 | 7.12\% |
|  | 5M-10J-V1-P2-S1-D4 | 1 | 46.307 | 39.218 | 0\% | 44.01 | 4.96\% |
|  | 5M-10J-V1-P2-S1-D5 | 1 | 58.935 | 81.797 | 0\% | 55.724 | 5.45\% |
|  | 5M-10J-V1-P2-S1-D6 | 1 | 57.643 | 42.11 | 0\% | 54.991 | 4.60\% |
|  | 5M-10J-V1-P2-S1-D7 | 1 | 73.903 | 69.265 | 0\% | 68.766 | 6.95\% |
|  | 5M-10J-V1-P2-S1-D8 | 1 | 50.252 | 67.672 | 0\% | 46.233 | 8.00\% |
|  | 5M-10J-V1-P2-S1-D9 | 1 | 56.418 | 126.657 | 0\% | 53.508 | 5.16\% |
|  | 5M-10J-V1-P2-S1-D10 | 1 | 62.703 | 50.656 | 0\% | 58.475 | 6.74\% |
|  | 5M-10J-V1-P2-S2-D1 | 1 | 58.936 | 79.875 | 0\% | 55.776 | 5.36\% |
|  | 5M-10J-V1-P2-S2-D2 | 1 | 44.021 | 71.641 | 0\% | 40.998 | 6.87\% |
|  | 5M-10J-V1-P2-S2-D3 | 1 | 58.791 | 86.25 | 0\% | 53.768 | 8.54\% |
|  | 5M-10J-V1-P2-S2-D4 | 1 | 47.043 | 40.594 | 0\% | 44.01 | 6.45\% |
|  | 5M-10J-V1-P2-S2-D5 | 1 | 59.247 | 98.734 | 0\% | 55.724 | 5.95\% |
|  | 5M-10J-V1-P2-S2-D6 | 1 | 58.654 | 38.094 | 0\% | 54.991 | 6.25\% |
|  | 5M-10J-V1-P2-S2-D7 | 1 | 75.457 | 80.844 | 0\% | 68.766 | 8.87\% |
|  | 5M-10J-V1-P2-S2-D8 | 1 | 50.252 | 66.625 | 0\% | 46.233 | 8.00\% |
|  | 5M-10J-V1-P2-S2-D9 | 1 | 57.314 | 133.656 | 0\% | 53.508 | 6.64\% |
|  | 5M-10J-V1-P2-S2-D10 | 1 | 63.614 | 103.703 | 0\% | 58.475 | 8.08\% |


|  |  | CPLEX Solution |  |  |  | Lower Bound |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Opt? | $C_{\text {max }}$ | Run Time (sec.) | $\begin{gathered} \text { \% } \\ \text { Gap } \end{gathered}$ | $C_{\text {max }}$ | $\begin{aligned} & \text { \% } \\ & \text { Gap } \end{aligned}$ |
| $\begin{aligned} & \vec{N} \\ & \text { é } \\ & 0 \\ & \text { ouv } \end{aligned}$ | 5M-10J-V2-P1-S1-D1 | 1 | 53.581 | 22.641 | 0\% | 50.45 | 5.84\% |
|  | 5M-10J-V2-P1-S1-D2 | 1 | 46.472 | 34.172 | 0\% | 42.327 | 8.92\% |
|  | 5M-10J-V2-P1-S1-D3 | 1 | 69.478 | 49.781 | 0\% | 62.354 | 10.25\% |
|  | 5M-10J-V2-P1-S1-D4 | 1 | 40.401 | 15.828 | 0\% | 38.01 | 5.92\% |
|  | 5M-10J-V2-P1-S1-D5 | 1 | 49.966 | 30.328 | 0\% | 46.471 | 6.99\% |
|  | 5M-10J-V2-P1-S1-D6 | 1 | 52.174 | 34.672 | 0\% | 49.583 | 4.97\% |
|  | 5M-10J-V2-P1-S1-D7 | 1 | 47.712 | 29.625 | 0\% | 44.484 | 6.77\% |
|  | 5M-10J-V2-P1-S1-D8 | 1 | 42.203 | 26.235 | 0\% | 39.168 | 7.19\% |
|  | 5M-10J-V2-P1-S1-D9 | 1 | 55.072 | 21.219 | 0\% | 52.779 | 4.16\% |
|  | 5M-10J-V2-P1-S1-D10 | 1 | 65.006 | 123.828 | 0\% | 56.182 | 13.57\% |
|  | 5M-10J-V2-P1-S2-D1 | 1 | 54.659 | 30.891 | 0\% | 50.45 | 7.70\% |
|  | 5M-10J-V2-P1-S2-D2 | 1 | 46.09 | 22.547 | 0\% | 42.327 | 8.16\% |
|  | 5M-10J-V2-P1-S2-D3 | 1 | 69.789 | 53.828 | 0\% | 62.354 | 10.65\% |
|  | 5M-10J-V2-P1-S2-D4 | 1 | 40.751 | 26.656 | 0\% | 38.01 | 6.73\% |
|  | 5M-10J-V2-P1-S2-D5 | 1 | 50.426 | 45.016 | 0\% | 46.471 | 7.84\% |
|  | 5M-10J-V2-P1-S2-D6 | 1 | 52.78 | 40.688 | 0\% | 49.583 | 6.06\% |
|  | 5M-10J-V2-P1-S2-D7 | 1 | 47.712 | 61.703 | 0\% | 44.484 | 6.77\% |
|  | 5M-10J-V2-P1-S2-D8 | 1 | 42.063 | 30.625 | 0\% | 39.168 | 6.88\% |
|  | 5M-10J-V2-P1-S2-D9 | 1 | 56.086 | 51.437 | 0\% | 52.779 | 5.90\% |
|  | 5M-10J-V2-P1-S2-D10 | 1 | 65.006 | 96.844 | 0\% | 56.182 | 13.57\% |
| $\begin{aligned} & \text { Nu} \\ & \text { Sै } \\ & 0 \\ & \text { 룽 } \end{aligned}$ | 5M-10J-V2-P2-S1-D1 | 1 | 55.798 | 25.032 | 0\% | 53.224 | 4.61\% |
|  | 5M-10J-V2-P2-S1-D2 | 1 | 48.369 | 38.75 | 0\% | 44.636 | 7.72\% |
|  | 5M-10J-V2-P2-S1-D3 | 1 | 58.157 | 15.906 | 0\% | 55.448 | 4.66\% |
|  | 5M-10J-V2-P2-S1-D4 | 1 | 45.721 | 32.11 | 0\% | 43.44 | 4.99\% |
|  | 5M-10J-V2-P2-S1-D5 | 1 | 56.563 | 18.578 | 0\% | 53.933 | 4.65\% |
|  | 5M-10J-V2-P2-S1-D6 | 1 | 52.864 | 20.266 | 0\% | 50.205 | 5.03\% |
|  | 5M-10J-V2-P2-S1-D7 | 1 | 58.868 | 46.14 | 0\% | 54.126 | 8.06\% |
|  | 5M-10J-V2-P2-S1-D8 | 1 | 47.106 | 15.437 | 0\% | 44.647 | 5.22\% |
|  | 5M-10J-V2-P2-S1-D9 | 1 | 53.595 | 24.375 | 0\% | 51.149 | 4.56\% |
|  | 5M-10J-V2-P2-S1-D10 | 1 | 56.403 | 23.625 | 0\% | 53.487 | 5.17\% |
|  | 5M-10J-V2-P2-S2-D1 | 1 | 56.326 | 23.828 | 0\% | 53.224 | 5.51\% |
|  | 5M-10J-V2-P2-S2-D2 | 1 | 47.658 | 43.688 | 0\% | 44.636 | 6.34\% |
|  | 5M-10J-V2-P2-S2-D3 | 1 | 58.4 | 16.968 | 0\% | 55.448 | 5.05\% |
|  | 5M-10J-V2-P2-S2-D4 | 1 | 46.967 | 29.937 | 0\% | 43.44 | 7.51\% |
|  | 5M-10J-V2-P2-S2-D5 | 1 | 57.248 | 20.453 | 0\% | 53.933 | 5.79\% |
|  | 5M-10J-V2-P2-S2-D6 | 1 | 53.069 | 21.562 | 0\% | 50.205 | 5.40\% |
|  | 5M-10J-V2-P2-S2-D7 | 1 | 59.704 | 44.938 | 0\% | 54.126 | 9.34\% |
|  | 5M-10J-V2-P2-S2-D8 | 1 | 47.958 | 49.031 | 0\% | 44.647 | 6.90\% |
|  | 5M-10J-V2-P2-S2-D9 | 1 | 54.106 | 27.125 | 0\% | 51.149 | 5.47\% |
|  | 5M-10J-V2-P2-S2-D10 | 1 | 56.403 | 25.281 | 0\% | 53.487 | 5.17\% |


|  |  | CPLEX Solution |  |  |  | Lower Bound |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Opt? | $C_{\text {max }}$ | Run Time (sec.) | $\begin{gathered} \% \\ \text { Gap } \end{gathered}$ | $C_{\text {max }}$ | $\begin{gathered} \text { \% } \\ \text { Gap } \end{gathered}$ |
|  | 5M-20J-V1-P1-S1-D1 | 0 | 122.334 | 3602.328 | 76\% | 115.476 | 5.61\% |
|  | 5M-20J-V1-P1-S1-D2 | 0 | 91.433 | 3600.469 | 73\% | 86.983 | 4.87\% |
|  | 5M-20J-V1-P1-S1-D3 | 0 | 122.481 | 3600.391 | 78\% | 115.773 | 5.48\% |
|  | 5M-20J-V1-P1-S1-D4 | 0 | 101.281 | 3600.531 | 73\% | 93.495 | 7.69\% |
|  | 5M-20J-V1-P1-S1-D5 | 0 | 98.262 | 3600.422 | 67\% | 92.189 | 6.18\% |
|  | 5M-20J-V1-P1-S1-D6 | 0 | 88.571 | 3600.89 | 67\% | 83.611 | 5.60\% |
|  | 5M-20J-V1-P1-S1-D7 | 0 | 96.786 | 3600.484 | 75\% | 90.566 | 6.43\% |
|  | 5M-20J-V1-P1-S1-D8 | 0 | 89.752 | 3600.344 | 67\% | 82.502 | 8.08\% |
|  | 5M-20J-V1-P1-S1-D9 | 0 | 127.121 | 3600.421 | 76\% | 121.275 | 4.60\% |
|  | 5M-20J-V1-P1-S1-D10 | 0 | 97.782 | 3601 | 69\% | 91.825 | 6.09\% |
|  | 5M-20J-V1-P1-S2-D1 | 0 | 127.228 | 3601.156 | 85\% | 115.476 | 9.24\% |
|  | 5M-20J-V1-P1-S2-D2 | 0 | 94.283 | 3600.344 | 76\% | 86.983 | 7.74\% |
|  | 5M-20J-V1-P1-S2-D3 | 0 | 122.96 | 3600.953 | 73\% | 115.773 | 5.84\% |
|  | 5M-20J-V1-P1-S2-D4 | 0 | 101.281 | 3600.609 | 79\% | 93.495 | 7.69\% |
|  | 5M-20J-V1-P1-S2-D5 | 0 | 100.639 | 3600.438 | 74\% | 92.189 | 8.40\% |
|  | 5M-20J-V1-P1-S2-D6 | 0 | 90.987 | 3600.968 | 76\% | 83.611 | 8.11\% |
|  | 5M-20J-V1-P1-S2-D7 | 0 | 98.169 | 3600.375 | 70\% | 90.566 | 7.74\% |
|  | 5M-20J-V1-P1-S2-D8 | 0 | 89.331 | 3601.219 | 85\% | 82.502 | 7.64\% |
|  | 5M-20J-V1-P1-S2-D9 | 0 | 130.633 | 3601.204 | 80\% | 121.275 | 7.16\% |
|  | 5M-20J-V1-P1-S2-D10 | 0 | 98.517 | 3600.532 | 80\% | 91.825 | 6.79\% |
|  | 5M-20J-V1-P2-S1-D1 | 0 | 99.898 | 3600.609 | 72\% | 94.039 | 5.86\% |
|  | 5M-20J-V1-P2-S1-D2 | 0 | 88.816 | 3600.421 | 73\% | 83.853 | 5.59\% |
|  | 5M-20J-V1-P2-S1-D3 | 0 | 112.201 | 3604.672 | 79\% | 104.765 | 6.63\% |
|  | 5M-20J-V1-P2-S1-D4 | 0 | 105.227 | 3601.985 | 73\% | 99.325 | 5.61\% |
|  | 5M-20J-V1-P2-S1-D5 | 0 | 117.719 | 3601.094 | 75\% | 109.562 | 6.93\% |
|  | 5M-20J-V1-P2-S1-D6 | 0 | 89.431 | 3600.406 | 71\% | 84.479 | 5.54\% |
|  | 5M-20J-V1-P2-S1-D7 | 0 | 93.753 | 3600.75 | 69\% | 87.748 | 6.41\% |
|  | 5M-20J-V1-P2-S1-D8 | 0 | 137.567 | 3600.5 | 79\% | 128.282 | 6.75\% |
|  | 5M-20J-V1-P2-S1-D9 | 0 | 122.76 | 3600.453 | 80\% | 115.639 | 5.80\% |
|  | 5M-20J-V1-P2-S1-D10 | 0 | 112.73 | 3601.437 | 79\% | 106.386 | 5.63\% |
|  | 5M-20J-V1-P2-S2-D1 | 0 | 101.511 | 3601.546 | 72\% | 94.039 | 7.36\% |
|  | 5M-20J-V1-P2-S2-D2 | 0 | 92.591 | 3600.75 | 74\% | 83.853 | 9.44\% |
|  | 5M-20J-V1-P2-S2-D3 | 0 | 111.494 | 3600.578 | 78\% | 104.765 | 6.04\% |
|  | 5M-20J-V1-P2-S2-D4 | 0 | 110.341 | 3601.782 | 74\% | 99.325 | 9.98\% |
|  | 5M-20J-V1-P2-S2-D5 | 0 | 118.594 | 3601.031 | 75\% | 109.562 | 7.62\% |
|  | 5M-20J-V1-P2-S2-D6 | 0 | 90.869 | 3600.89 | 71\% | 84.479 | 7.03\% |
|  | 5M-20J-V1-P2-S2-D7 | 0 | 96.406 | 3600.797 | 70\% | 87.748 | 8.98\% |
|  | 5M-20J-V1-P2-S2-D8 | 0 | 137.567 | 3600.531 | 79\% | 128.282 | 6.75\% |
|  | 5M-20J-V1-P2-S2-D9 | 0 | 123.227 | 3600.515 | 80\% | 115.639 | 6.16\% |
|  | 5M-20J-V1-P2-S2-D10 | 0 | 116.144 | 3600.75 | 77\% | 106.386 | 8.40\% |


|  |  | CPLEX Solution |  |  |  | Lower Bound |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Opt? | $C_{\text {max }}$ | Run Time (sec.) | $\begin{gathered} \text { \% } \\ \text { Gap } \end{gathered}$ | $C_{\text {max }}$ | $\begin{gathered} \% \\ \text { Gap } \end{gathered}$ |
|  | 5M-20J-V2-P1-S1-D1 | 0 | 106.852 | 3600.312 | 81\% | 101.581 | 4.93\% |
|  | 5M-20J-V2-P1-S1-D2 | 0 | 104.381 | 3600.484 | 69\% | 99.229 | 4.94\% |
|  | 5M-20J-V2-P1-S1-D3 | 0 | 126.23 | 3600.625 | 69\% | 120.063 | 4.89\% |
|  | 5M-20J-V2-P1-S1-D4 | 0 | 94.774 | 3600.406 | 74\% | 88.559 | 6.56\% |
|  | 5M-20J-V2-P1-S1-D5 | 0 | 99.488 | 3600.437 | 69\% | 93.588 | 5.93\% |
|  | 5M-20J-V2-P1-S1-D6 | 0 | 98.2 | 3600.469 | 63\% | 92.171 | 6.14\% |
|  | 5M-20J-V2-P1-S1-D7 | 0 | 93.786 | 3601.25 | 81\% | 87.032 | 7.20\% |
|  | 5M-20J-V2-P1-S1-D8 | 0 | 97.429 | 3601.61 | 72\% | 90.742 | 6.86\% |
|  | 5M-20J-V2-P1-S1-D9 | 0 | 116.61 | 3600.328 | 67\% | 111.367 | 4.50\% |
|  | 5M-20J-V2-P1-S1-D10 | 0 | 104.719 | 3600.516 | 76\% | 95.658 | 8.65\% |
| $\begin{aligned} & \text { en } \\ & \text { eै } \\ & 0 \\ & \text { env } \end{aligned}$ | 5M-20J-V2-P1-S2-D1 | 0 | 109.723 | 3600.375 | 76\% | 101.581 | 7.42\% |
|  | 5M-20J-V2-P1-S2-D2 | 0 | 107.08 | 3600.735 | 75\% | 99.229 | 7.33\% |
|  | 5M-20J-V2-P1-S2-D3 | 0 | 127.828 | 3600.375 | 77\% | 120.063 | 6.07\% |
|  | 5M-20J-V2-P1-S2-D4 | 0 | 96.909 | 3600.328 | 78\% | 88.559 | 8.62\% |
|  | 5M-20J-V2-P1-S2-D5 | 0 | 100.879 | 3600.297 | $71 \%$ | 93.588 | 7.23\% |
|  | 5M-20J-V2-P1-S2-D6 | 0 | 99.708 | 3600.562 | 79\% | 92.171 | 7.56\% |
|  | 5M-20J-V2-P1-S2-D7 | 0 | 94.131 | 3601.782 | 61\% | 87.032 | 7.54\% |
|  | 5M-20J-V2-P1-S2-D8 | 0 | 98.08 | 3600.454 | 67\% | 90.742 | 7.48\% |
|  | 5M-20J-V2-P1-S2-D9 | 0 | 119.771 | 3600.032 | 68\% | 111.367 | 7.02\% |
|  | 5M-20J-V2-P1-S2-D10 | 0 | 103.786 | 3602.297 | 90\% | 95.658 | 7.83\% |
|  | 5M-20J-V2-P2-S1-D1 | 0 | 103.587 | 3600.359 | 75\% | 98.268 | 5.13\% |
|  | 5M-20J-V2-P2-S1-D2 | 0 | 100.924 | 3600.468 | 69\% | 95.658 | 5.22\% |
|  | 5M-20J-V2-P2-S1-D3 | 0 | 113.807 | 3600.36 | 74\% | 108.647 | 4.53\% |
|  | 5M-20J-V2-P2-S1-D4 | 0 | 99.103 | 3600.453 | 71\% | 94.081 | 5.07\% |
|  | 5M-20J-V2-P2-S1-D5 | 0 | 111.249 | 3600.297 | 77\% | 104.739 | 5.85\% |
|  | 5M-20J-V2-P2-S1-D6 | 0 | 99.114 | 3600.515 | 70\% | 93.127 | 6.04\% |
|  | 5M-20J-V2-P2-S1-D7 | 0 | 96.521 | 3600.375 | 78\% | 90.818 | 5.91\% |
|  | 5M-20J-V2-P2-S1-D8 | 0 | 113.477 | 3600.515 | 77\% | 106.439 | 6.20\% |
|  | 5M-20J-V2-P2-S1-D9 | 0 | 110.349 | 3600.453 | 74\% | 106.192 | 3.77\% |
|  | 5M-20J-V2-P2-S1-D10 | 0 | 107.67 | 3600.516 | 74\% | 101.252 | 5.96\% |
| $\begin{aligned} & \text { N} \\ & \text { eै } \\ & 0 \\ & \underset{\sim}{c} \\ & \hline \end{aligned}$ | 5M-20J-V2-P2-S2-D1 | 0 | 105.02 | 3600.312 | 75\% | 98.268 | 6.43\% |
|  | 5M-20J-V2-P2-S2-D2 | 0 | 102.581 | 3600.5 | 77\% | 95.658 | 6.75\% |
|  | 5M-20J-V2-P2-S2-D3 | 0 | 116.172 | 3600.312 | 74\% | 108.647 | 6.48\% |
|  | 5M-20J-V2-P2-S2-D4 | 0 | 103.766 | 3600.391 | 77\% | 94.081 | 9.33\% |
|  | 5M-20J-V2-P2-S2-D5 | 0 | 111.473 | 3600.469 | 76\% | 104.739 | 6.04\% |
|  | 5M-20J-V2-P2-S2-D6 | 0 | 100.107 | 3600.313 | 72\% | 93.127 | 6.97\% |
|  | 5M-20J-V2-P2-S2-D7 | 0 | 99.054 | 3600.453 | 73\% | 90.818 | 8.31\% |
|  | 5M-20J-V2-P2-S2-D8 | 0 | 114.579 | 3600.391 | 79\% | 106.439 | 7.10\% |
|  | 5M-20J-V2-P2-S2-D9 | 0 | 114.448 | 3600.453 | 77\% | 106.192 | 7.21\% |
|  | 5M-20J-V2-P2-S2-D10 | 0 | 108.726 | 3600.438 | 72\% | 101.252 | 6.87\% |

## APPENDIX 2 - IMPROVED HEURISTIC SOLUTIONS FOR ALL

INSTANCES WITH REPITATION TIMES

|  |  | $\underset{\mathbf{C}_{\text {max }}}{\text { H } 100}$ | $\begin{gathered} \text { H } 200 \\ \mathbf{C}_{\text {max }} \end{gathered}$ | $\begin{gathered} \text { H } 400 \\ \mathbf{C}_{\text {max }} \end{gathered}$ | $\begin{gathered} \mathbf{H}_{800}^{\mathbf{C}_{\text {max }}} \end{gathered}$ | $\underset{\mathbf{C}_{\max }}{\mathrm{H} 1600}$ | $\underset{\mathbf{C}_{\text {max }}}{\text { H-Best }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \overrightarrow{\text { a }} \\ & \text { O} \\ & \text { ? } \end{aligned}$ | 3M-6J-V1-P1-S1-D1 | 46.611 | 46.611 |  |  |  | 46.611 |
|  | 3M-6J-V1-P1-S1-D2 | 53.221 | 52.265 | 52.265 |  |  | 52.265 |
|  | 3M-6J-V1-P1-S1-D3 | 65.123 | 64.764 |  |  |  | 64.764 |
|  | 3M-6J-V1-P1-S1-D4 | 67.658 | 67.331 |  |  |  | 67.331 |
|  | 3M-6J-V1-P1-S1-D5 | 72.091 | 72.091 |  |  |  | 72.091 |
|  | 3M-6J-V1-P1-S1-D6 | 40.941 | 40.941 |  |  |  | 40.941 |
|  | 3M-6J-V1-P1-S1-D7 | 44.33 | 44.33 |  |  |  | 44.330 |
|  | 3M-6J-V1-P1-S1-D8 | 46.139 | 44.693 | 44.693 |  |  | 44.693 |
|  | 3M-6J-V1-P1-S1-D9 | 57.809 | 57.809 |  |  |  | 57.809 |
|  | 3M-6J-V1-P1-S1-D10 | 58.066 | 56.346 | 56.346 |  |  | 56.346 |
| $\begin{aligned} & \text { N } \\ & \text { है } \\ & 0 \\ & \text { y } \end{aligned}$ | 3M-6J-V1-P1-S2-D1 | 48.342 | 48.342 |  |  |  | 48.342 |
|  | 3M-6J-V1-P1-S2-D2 | 51.89 | 51.89 |  |  |  | 51.890 |
|  | 3M-6J-V1-P1-S2-D3 | 62.41 | 62.41 |  |  |  | 62.410 |
|  | 3M-6J-V1-P1-S2-D4 | 67.331 | 67.331 |  |  |  | 67.331 |
|  | 3M-6J-V1-P1-S2-D5 | 69.751 | 69.751 |  |  |  | 69.751 |
|  | 3M-6J-V1-P1-S2-D6 | 44.353 | 44.353 |  |  |  | 44.353 |
|  | 3M-6J-V1-P1-S2-D7 | 45.254 | 45.254 |  |  |  | 45.254 |
|  | 3M-6J-V1-P1-S2-D8 | 47.848 | 47.848 |  |  |  | 47.848 |
|  | 3M-6J-V1-P1-S2-D9 | 57.839 | 57.839 |  |  |  | 57.839 |
|  | 3M-6J-V1-P1-S2-D10 | 56.664 | 56.664 |  |  |  | 56.664 |
| $\begin{aligned} & \infty \\ & \text { eै } \\ & 0 \\ & \underset{\sim}{c} \end{aligned}$ | 3M-6J-V1-P2-S1-D1 | 52.341 | 49.37 | 49.37 |  |  | 49.370 |
|  | 3M-6J-V1-P2-S1-D2 | 65.991 | 65.991 |  |  |  | 65.991 |
|  | 3M-6J-V1-P2-S1-D3 | 55.438 | 55.438 |  |  |  | 55.438 |
|  | 3M-6J-V1-P2-S1-D4 | 72.422 | 72.422 |  |  |  | 72.422 |
|  | 3M-6J-V1-P2-S1-D5 | 52.066 | 52.066 |  |  |  | 52.066 |
|  | 3M-6J-V1-P2-S1-D6 | 46.94 | 46.47 | 46.47 |  |  | 46.470 |
|  | 3M-6J-V1-P2-S1-D7 | 50.795 | 50.795 |  |  |  | 50.795 |
|  | 3M-6J-V1-P2-S1-D8 | 52.178 | 48.695 | 48.695 |  |  | 48.695 |
|  | 3M-6J-V1-P2-S1-D9 | 57.263 | 56.346 | 56.346 |  |  | 56.346 |
|  | 3M-6J-V1-P2-S1-D10 | 49.568 | 49.493 |  |  |  | 49.493 |
|  | 3M-6J-V1-P2-S2-D1 | 51.427 | 51.427 |  |  |  | 51.427 |
|  | 3M-6J-V1-P2-S2-D2 | 69.064 | 65.331 | 65.331 |  |  | 65.331 |
|  | 3M-6J-V1-P2-S2-D3 | 55.174 | 55.174 |  |  |  | 55.174 |
|  | 3M-6J-V1-P2-S2-D4 | 72.422 | 72.422 |  |  |  | 72.422 |
|  | 3M-6J-V1-P2-S2-D5 | 54.077 | 54.077 |  |  |  | 54.077 |
|  | 3M-6J-V1-P2-S2-D6 | 46.4 | 46.4 |  |  |  | 46.400 |
|  | 3M-6J-V1-P2-S2-D7 | 49.952 | 49.952 |  |  |  | 49.952 |
|  | 3M-6J-V1-P2-S2-D8 | 50.84 | 50.84 |  |  |  | 50.840 |
|  | 3M-6J-V1-P2-S2-D9 | 56.346 | 56.346 |  |  |  | 56.346 |
|  | 3M-6J-V1-P2-S2-D10 | 49.109 | 49.109 |  |  |  | 49.109 |

* H is the reputation time

|  |  | $\underset{\sim}{\text { H } 100}$ | $\underset{\mathbf{C}_{\text {max }}}{\text { H } 200}$ | $\begin{gathered} \text { H } 400 \\ \text { C }_{\text {max }} \end{gathered}$ | $\begin{gathered} \text { H } 800 \\ \mathbf{C}_{\text {max }} \end{gathered}$ | $\underset{\mathbf{C}_{\max }}{\mathbf{H} 1600}$ | $\underset{\mathbf{C}_{\text {max }}}{\text { H-Best }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { n } \\ & \text { B } \\ & 0 \\ & \text { or } \end{aligned}$ | 3M-6J-V2-P1-S1-D1 | 46.686 | 46.686 |  |  |  | 46.686 |
|  | 3M-6J-V2-P1-S1-D2 | 41.825 | 40.664 | 40.664 |  |  | 40.664 |
|  | 3M-6J-V2-P1-S1-D3 | 67.851 | 67.851 |  |  |  | 67.851 |
|  | 3M-6J-V2-P1-S1-D4 | 53.59 | 53.59 |  |  |  | 53.590 |
|  | 3M-6J-V2-P1-S1-D5 | 65.966 | 62.388 | 62.388 |  |  | 62.388 |
|  | 3M-6J-V2-P1-S1-D6 | 42.995 | 42.995 |  |  |  | 42.995 |
|  | 3M-6J-V2-P1-S1-D7 | 44.407 | 44.407 |  |  |  | 44.407 |
|  | 3M-6J-V2-P1-S1-D8 | 42.197 | 41.749 | 41.749 |  |  | 41.749 |
|  | 3M-6J-V2-P1-S1-D9 | 57.952 | 57.952 |  |  |  | 57.952 |
|  | 3M-6J-V2-P1-S1-D10 | 64.9 | 64.717 |  |  |  | 64.717 |
| $\begin{aligned} & 0 \\ & \text { b } \\ & \text { O} \\ & \text { 合 } \end{aligned}$ | 3M-6J-V2-P1-S2-D1 | 48.761 | 48.225 | 48.225 |  |  | 48.225 |
|  | 3M-6J-V2-P1-S2-D2 | 41.825 | 40.496 | 39.979 | 39.979 |  | 39.979 |
|  | 3M-6J-V2-P1-S2-D3 | 66.881 | 66.881 |  |  |  | 66.881 |
|  | 3M-6J-V2-P1-S2-D4 | 55.182 | 54.73 |  |  |  | 54.730 |
|  | 3M-6J-V2-P1-S2-D5 | 62.388 | 62.388 |  |  |  | 62.388 |
|  | 3M-6J-V2-P1-S2-D6 | 43.873 | 43.873 |  |  |  | 43.873 |
|  | 3M-6J-V2-P1-S2-D7 | 46.308 | 44.885 | 44.885 |  |  | 44.885 |
|  | 3M-6J-V2-P1-S2-D8 | 42.618 | 42.618 |  |  |  | 42.618 |
|  | 3M-6J-V2-P1-S2-D9 | 57.952 | 57.952 |  |  |  | 57.952 |
|  | 3M-6J-V2-P1-S2-D10 | 62.894 | 62.894 |  |  |  | 62.894 |
|  | 3M-6J-V2-P2-S1-D1 | 51.934 | 50.079 | 50.079 |  |  | 50.079 |
|  | 3M-6J-V2-P2-S1-D2 | 49.252 | 48.624 | 48.624 |  |  | 48.624 |
|  | 3M-6J-V2-P2-S1-D3 | 58.579 | 58.579 |  |  |  | 58.579 |
|  | 3M-6J-V2-P2-S1-D4 | 54.91 | 54.91 |  |  |  | 54.910 |
|  | 3M-6J-V2-P2-S1-D5 | 56.336 | 56.336 |  |  |  | 56.336 |
|  | 3M-6J-V2-P2-S1-D6 | 46.505 | 46.505 |  |  |  | 46.505 |
|  | 3M-6J-V2-P2-S1-D7 | 51.077 | 51.077 |  |  |  | 51.077 |
|  | 3M-6J-V2-P2-S1-D8 | 46.967 | 46.967 |  |  |  | 46.967 |
|  | 3M-6J-V2-P2-S1-D9 | 55.169 | 54.954 |  |  |  | 54.954 |
|  | 3M-6J-V2-P2-S1-D10 | 55.759 | 55.759 |  |  |  | 55.759 |
| $\begin{aligned} & \infty \\ & \text { Q } \\ & \text { O} \\ & \text { ? } \end{aligned}$ | 3M-6J-V2-P2-S2-D1 | 49.411 | 49.411 |  |  |  | 49.411 |
|  | 3M-6J-V2-P2-S2-D2 | 48.624 | 48.624 |  |  |  | 48.624 |
|  | 3M-6J-V2-P2-S2-D3 | 58.158 | 58.158 |  |  |  | 58.158 |
|  | 3M-6J-V2-P2-S2-D4 | 55.182 | 55.182 |  |  |  | 55.182 |
|  | 3M-6J-V2-P2-S2-D5 | 56.233 | 55.152 | 55.152 |  |  | 55.152 |
|  | 3M-6J-V2-P2-S2-D6 | 47.761 | 47.383 |  |  |  | 47.383 |
|  | 3M-6J-V2-P2-S2-D7 | 51.077 | 51.077 |  |  |  | 51.077 |
|  | 3M-6J-V2-P2-S2-D8 | 47.97 | 47.97 |  |  |  | 47.970 |
|  | 3M-6J-V2-P2-S2-D9 | 56.343 | 55.857 |  |  |  | 55.857 |
|  | 3M-6J-V2-P2-S2-D10 | 55.932 | 55.932 |  |  |  | 55.932 |

* H is the reputation time

|  |  | H 100 <br> $\mathbf{C}_{\text {max }}$ | H 200 <br> $\mathbf{C}_{\text {max }}$ | H 400 <br> $\mathbf{C}_{\text {max }}$ | H 800 <br> $\mathbf{C}_{\text {max }}$ | H 1600 <br> $\mathbf{C}_{\text {max }}$ | H-Best <br> $\mathbf{C}_{\text {max }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \hat{0} \\ & \stackrel{\rightharpoonup}{0} \\ & \underset{\sim}{2} \end{aligned}$ | 3M-12J-V1-P1-S1-D1 | 117.347 | 116.857 |  |  |  | 116.857 |
|  | 3M-12J-V1-P1-S1-D2 | 78.175 | 76.418 | 76.418 |  |  | 76.418 |
|  | 3M-12J-V1-P1-S1-D3 | 116.587 | 115.152 | 115.152 |  |  | 115.152 |
|  | 3M-12J-V1-P1-S1-D4 | 84.496 | 84.496 |  |  |  | 84.496 |
|  | 3M-12J-V1-P1-S1-D5 | 110.132 | 110.132 |  |  |  | 110.132 |
|  | 3M-12J-V1-P1-S1-D6 | 93.708 | 91.404 | 91.07 |  |  | 91.070 |
|  | 3M-12J-V1-P1-S1-D7 | 146.978 | 145.666 |  |  |  | 145.666 |
|  | 3M-12J-V1-P1-S1-D8 | 87.579 | 87.579 |  |  |  | 87.579 |
|  | 3M-12J-V1-P1-S1-D9 | 96.074 | 96.074 |  |  |  | 96.074 |
|  | 3M-12J-V1-P1-S1-D10 | 126.388 | 125.334 |  |  |  | 125.334 |
| $\begin{aligned} & e \\ & \stackrel{3}{3} \\ & 0 \\ & \frac{0}{c} \end{aligned}$ | 3M-12J-V1-P1-S2-D1 | 117.347 | 117.347 |  |  |  | 117.347 |
|  | 3M-12J-V1-P1-S2-D2 | 79.053 | 78.681 |  |  |  | 78.681 |
|  | 3M-12J-V1-P1-S2-D3 | 117.055 | 114.99 | 114.99 |  |  | 114.990 |
|  | 3M-12J-V1-P1-S2-D4 | 86.124 | 85.365 |  |  |  | 85.365 |
|  | 3M-12J-V1-P1-S2-D5 | 112.962 | 111.3 | 111.3 |  |  | 111.300 |
|  | 3M-12J-V1-P1-S2-D6 | 91.404 | 89.868 | 89.868 |  |  | 89.868 |
|  | 3M-12J-V1-P1-S2-D7 | 146.737 | 145.117 | 145.117 |  |  | 145.117 |
|  | 3M-12J-V1-P1-S2-D8 | 88.13 | 88.13 |  |  |  | 88.130 |
|  | 3M-12J-V1-P1-S2-D9 | 98.163 | 98.163 |  |  |  | 98.163 |
|  | 3M-12J-V1-P1-S2-D10 | 125.638 | 124.43 |  |  |  | 124.430 |
|  | 3M-12J-V1-P2-S1-D1 | 101.197 | 100.48 |  |  |  | 100.480 |
|  | 3M-12J-V1-P2-S1-D2 | 81.27 | 81.27 |  |  |  | 81.270 |
|  | 3M-12J-V1-P2-S1-D3 | 105.238 | 105.238 |  |  |  | 105.238 |
|  | 3M-12J-V1-P2-S1-D4 | 92.807 | 92.807 |  |  |  | 92.807 |
|  | 3M-12J-V1-P2-S1-D5 | 107.824 | 105.229 | 105.229 |  |  | 105.229 |
|  | 3M-12J-V1-P2-S1-D6 | 95.135 | 95.135 |  |  |  | 95.135 |
|  | 3M-12J-V1-P2-S1-D7 | 149.714 | 145.516 | 145.516 |  |  | 145.516 |
|  | 3M-12J-V1-P2-S1-D8 | 96.962 | 96.524 |  |  |  | 96.524 |
|  | 3M-12J-V1-P2-S1-D9 | 94.682 | 94.682 |  |  |  | 94.682 |
|  | 3M-12J-V1-P2-S1-D10 | 162.612 | 161.433 |  |  |  | 161.433 |
| $\begin{aligned} & \text { N } \\ & \text { en } \\ & 0 \\ & \underset{\sim}{c} \end{aligned}$ | 3M-12J-V1-P2-S2-D1 | 103.35 | 101.197 | 101.145 |  |  | 101.145 |
|  | 3M-12J-V1-P2-S2-D2 | 81.688 | 80.81 | 80.81 |  |  | 80.810 |
|  | 3M-12J-V1-P2-S2-D3 | 105.762 | 105.053 |  |  |  | 105.053 |
|  | 3M-12J-V1-P2-S2-D4 | 93.045 | 91.688 | 91.507 |  |  | 91.507 |
|  | 3M-12J-V1-P2-S2-D5 | 106.726 | 106.726 |  |  |  | 106.726 |
|  | 3M-12J-V1-P2-S2-D6 | 97.062 | 93.509 | 93.509 |  |  | 93.509 |
|  | 3M-12J-V1-P2-S2-D7 | 149.714 | 145.516 | 145.516 |  |  | 145.516 |
|  | 3M-12J-V1-P2-S2-D8 | 100.09 | 99.048 | 96.333 | 96.333 |  | 96.333 |
|  | 3M-12J-V1-P2-S2-D9 | 96.074 | 96.074 |  |  |  | 96.074 |
|  | 3M-12J-V1-P2-S2-D10 | 166.541 | 162.798 | 162.798 |  |  | 162.798 |

* H is the reputation time

|  |  | H 100 $\mathrm{C}_{\text {max }}$ | $\begin{gathered} \text { H } 200 \\ \mathbf{C}_{\text {max }} \end{gathered}$ | H 400 $\mathrm{C}_{\text {max }}$ | $\begin{gathered} \text { H } 800 \\ \mathbf{C}_{\text {max }} \end{gathered}$ | $\underset{\mathbf{C}_{\text {max }}}{H 1600}$ | H-Best $\mathbf{C}_{\text {max }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 3M-12J-V2-P1-S1-D1 | 111.744 | 111.744 |  |  |  | 111.744 |
|  | 3M-12J-V2-P1-S1-D2 | 93.05 | 92.181 |  |  |  | 92.181 |
|  | 3M-12J-V2-P1-S1-D3 | 128.268 | 124.146 | 124.146 |  |  | 124.146 |
|  | 3M-12J-V2-P1-S1-D4 | 90.554 | 90.554 |  |  |  | 90.554 |
|  | 3M-12J-V2-P1-S1-D5 | 108.957 | 107.156 | 105.784 | 105.784 |  | 105.784 |
|  | 3M-12J-V2-P1-S1-D6 | 96.586 | 96.586 |  |  |  | 96.586 |
|  | 3M-12J-V2-P1-S1-D7 | 110.194 | 110.194 |  |  |  | 110.194 |
|  | 3M-12J-V2-P1-S1-D8 | 89.255 | 89.255 |  |  |  | 89.255 |
|  | 3M-12J-V2-P1-S1-D9 | 106.993 | 106.993 |  |  |  | 106.993 |
|  | 3M-12J-V2-P1-S1-D10 | 114.595 | 111.775 | 111.31 |  |  | 111.310 |
|  | 3M-12J-V2-P1-S2-D1 | 110.836 | 110.836 |  |  |  | 110.836 |
|  | 3M-12J-V2-P1-S2-D2 | 92.946 | 91.998 | 91.998 |  |  | 91.998 |
|  | 3M-12J-V2-P1-S2-D3 | 127.174 | 127.174 |  |  |  | 127.174 |
|  | 3M-12J-V2-P1-S2-D4 | 91.732 | 91.732 |  |  |  | 91.732 |
|  | 3M-12J-V2-P1-S2-D5 | 109.933 | 106.821 | 106.821 |  |  | 106.821 |
|  | 3M-12J-V2-P1-S2-D6 | 97.196 | 97.196 |  |  |  | 97.196 |
|  | 3M-12J-V2-P1-S2-D7 | 110.224 | 110.224 |  |  |  | 110.224 |
|  | 3M-12J-V2-P1-S2-D8 | 91.117 | 88.241 | 88.241 |  |  | 88.241 |
|  | 3M-12J-V2-P1-S2-D9 | 108.488 | 107.877 |  |  |  | 107.877 |
|  | 3M-12J-V2-P1-S2-D10 | 114.291 | 112.304 | 110.316 | 110.316 |  | 110.316 |
| $$ | 3M-12J-V2-P2-S1-D1 | 107.391 | 106.521 |  |  |  | 106.521 |
|  | 3M-12J-V2-P2-S1-D2 | 96.972 | 96.529 |  |  |  | 96.529 |
|  | 3M-12J-V2-P2-S1-D3 | 114.016 | 114.016 |  |  |  | 114.016 |
|  | 3M-12J-V2-P2-S1-D4 | 97.1 | 97.1 |  |  |  | 97.100 |
|  | 3M-12J-V2-P2-S1-D5 | 109.2 | 109.2 |  |  |  | 109.200 |
|  | 3M-12J-V2-P2-S1-D6 | 102.905 | 101.969 |  |  |  | 101.969 |
|  | 3M-12J-V2-P2-S1-D7 | 117.894 | 115.325 | 115.325 |  |  | 115.325 |
|  | 3M-12J-V2-P2-S1-D8 | 98.795 | 98.795 |  |  |  | 98.795 |
|  | 3M-12J-V2-P2-S1-D9 | 106.293 | 106.109 |  |  |  | 106.109 |
|  | 3M-12J-V2-P2-S1-D10 | 126.027 | 126.027 |  |  |  | 126.027 |
| $\begin{aligned} & 0 \\ & \stackrel{0}{3} \\ & 0 \\ & \stackrel{\rightharpoonup}{c} \end{aligned}$ | 3M-12J-V2-P2-S2-D1 | 107.391 | 107.391 |  |  |  | 107.391 |
|  | 3M-12J-V2-P2-S2-D2 | 95.791 | 95.791 |  |  |  | 95.791 |
|  | 3M-12J-V2-P2-S2-D3 | 117.579 | 116.229 | 116.229 |  |  | 116.229 |
|  | 3M-12J-V2-P2-S2-D4 | 99.988 | 99.115 |  |  |  | 99.115 |
|  | 3M-12J-V2-P2-S2-D5 | 109.857 | 108.16 | 108.16 |  |  | 108.160 |
|  | 3M-12J-V2-P2-S2-D6 | 100.879 | 100.879 |  |  |  | 100.879 |
|  | 3M-12J-V2-P2-S2-D7 | 118.919 | 117.609 | 116.467 |  |  | 116.467 |
|  | 3M-12J-V2-P2-S2-D8 | 97.369 | 97.369 |  |  |  | 97.369 |
|  | 3M-12J-V2-P2-S2-D9 | 105.24 | 104.714 |  |  |  | 104.714 |
|  | 3M-12J-V2-P2-S2-D10 | 127.379 | 126.697 |  |  |  | 126.697 |

* H is the reputation time

|  |  | $\begin{gathered} \text { H } 100 \\ \mathbf{C}_{\text {max }} \end{gathered}$ | $\begin{gathered} \text { H } 200 \\ \mathbf{C}_{\text {max }} \end{gathered}$ | $\begin{gathered} \text { H } 400 \\ \mathbf{C}_{\text {max }} \end{gathered}$ | $\begin{gathered} \text { H } 800 \\ \mathbf{C}_{\text {max }} \end{gathered}$ | $\begin{gathered} \text { H } 1600 \\ \mathbf{C}_{\text {max }} \end{gathered}$ | H-Best $\mathbf{C}_{\text {max }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 5M-10J-V1-P1-S1-D1 | 58.964 | 58.964 |  |  |  | 58.964 |
|  | 5M-10J-V1-P1-S1-D2 | 46.554 | 45.714 | 45.714 |  |  | 45.714 |
|  | 5M-10J-V1-P1-S1-D3 | 68.52 | 68.52 |  |  |  | 68.520 |
|  | 5M-10J-V1-P1-S1-D4 | 47.043 | 43.072 | 43.072 |  |  | 43.072 |
|  | 5M-10J-V1-P1-S1-D5 | 58.142 | 57.905 |  |  |  | 57.905 |
|  | 5M-10J-V1-P1-S1-D6 | 59.801 | 59.801 |  |  |  | 59.801 |
|  | 5M-10J-V1-P1-S1-D7 | 55.545 | 55.545 |  |  |  | 55.545 |
|  | 5M-10J-V1-P1-S1-D8 | 46.415 | 46.415 |  |  |  | 46.415 |
|  | 5M-10J-V1-P1-S1-D9 | 63.583 | 62.859 | 62.859 |  |  | 62.859 |
|  | 5M-10J-V1-P1-S1-D10 | 67.651 | 67.651 |  |  |  | 67.651 |
| $$ | 5M-10J-V1-P1-S2-D1 | 62.459 | 61.109 | 58.936 | 58.936 |  | 58.936 |
|  | 5M-10J-V1-P1-S2-D2 | 44.798 | 44.798 |  |  |  | 44.798 |
|  | 5M-10J-V1-P1-S2-D3 | 65.303 | 65.303 |  |  |  | 65.303 |
|  | 5M-10J-V1-P1-S2-D4 | 44.339 | 44.339 |  |  |  | 44.339 |
|  | 5M-10J-V1-P1-S2-D5 | 60.175 | 60.175 |  |  |  | 60.175 |
|  | 5M-10J-V1-P1-S2-D6 | 67.064 | 60.473 | 60.163 |  |  | 60.163 |
|  | 5M-10J-V1-P1-S2-D7 | 57.459 | 57.459 |  |  |  | 57.459 |
|  | 5M-10J-V1-P1-S2-D8 | 48.262 | 47.237 | 47.237 |  |  | 47.237 |
|  | 5M-10J-V1-P1-S2-D9 | 65.448 | 61.792 | 61.792 |  |  | 61.792 |
|  | 5M-10J-V1-P1-S2-D10 | 68 | 68 |  |  |  | 68.000 |
| $\begin{aligned} & 2 \\ & \stackrel{\rightharpoonup}{3} \\ & 0 \\ & \text { 응 } \end{aligned}$ | 5M-10J-V1-P2-S1-D1 | 62.137 | 62.137 |  |  |  | 62.137 |
|  | 5M-10J-V1-P2-S1-D2 | 44.021 | 44.021 |  |  |  | 44.021 |
|  | 5M-10J-V1-P2-S1-D3 | 60.601 | 60.601 |  |  |  | 60.601 |
|  | 5M-10J-V1-P2-S1-D4 | 49.664 | 49.664 |  |  |  | 49.664 |
|  | 5M-10J-V1-P2-S1-D5 | 63.979 | 63.979 |  |  |  | 63.979 |
|  | 5M-10J-V1-P2-S1-D6 | 63.232 | 63.232 |  |  |  | 63.232 |
|  | 5M-10J-V1-P2-S1-D7 | 82.472 | 82.472 |  |  |  | 82.472 |
|  | 5M-10J-V1-P2-S1-D8 | 55.173 | 55.173 |  |  |  | 55.173 |
|  | 5M-10J-V1-P2-S1-D9 | 60.788 | 59.358 | 57.86 | 57.86 |  | 57.860 |
|  | 5M-10J-V1-P2-S1-D10 | 69.334 | 69.334 |  |  |  | 69.334 |
|  | 5M-10J-V1-P2-S2-D1 | 63.253 | 63.253 |  |  |  | 63.253 |
|  | 5M-10J-V1-P2-S2-D2 | 46.554 | 46.554 |  |  |  | 46.554 |
|  | 5M-10J-V1-P2-S2-D3 | 62.41 | 62.41 |  |  |  | 62.410 |
|  | 5M-10J-V1-P2-S2-D4 | 49.983 | 49.983 |  |  |  | 49.983 |
|  | 5M-10J-V1-P2-S2-D5 | 65.011 | 65.011 |  |  |  | 65.011 |
|  | 5M-10J-V1-P2-S2-D6 | 63.462 | 63.462 |  |  |  | 63.462 |
|  | 5M-10J-V1-P2-S2-D7 | 80.645 | 80.645 |  |  |  | 80.645 |
|  | 5M-10J-V1-P2-S2-D8 | 54.557 | 54.557 |  |  |  | 54.557 |
|  | 5M-10J-V1-P2-S2-D9 | 58.21 | 58.21 |  |  |  | 58.210 |
|  | 5M-10J-V1-P2-S2-D10 | 70.223 | 66.443 | 66.443 |  |  | 66.443 |

* H is the reputation time

|  |  | $\begin{gathered} \text { H } 100 \\ \mathbf{C}_{\text {max }} \end{gathered}$ | $\underset{\mathbf{C}_{\text {max }}}{\text { H } 200}$ | $\begin{gathered} \text { H } 400 \\ \text { C }_{\text {max }} \end{gathered}$ | $\begin{gathered} \text { H } 800 \\ \mathbf{C}_{\text {max }} \end{gathered}$ | $\underset{\mathbf{C}_{\text {max }}}{H 1600}$ | H-Best $\mathbf{C}_{\text {max }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { N} \\ & \text { है } \\ & 0 \\ & \text { êv } \end{aligned}$ | 5M-10J-V2-P1-S1-D1 | 61.492 | 60.215 | 58.173 | 56.132 | 56.132 | 56.132 |
|  | 5M-10J-V2-P1-S1-D2 | 49.958 | 49.491 |  |  |  | 49.491 |
|  | 5M-10J-V2-P1-S1-D3 | 76.605 | 70.92 | 70.92 |  |  | 70.920 |
|  | 5M-10J-V2-P1-S1-D4 | 45.335 | 45.335 |  |  |  | 45.335 |
|  | 5M-10J-V2-P1-S1-D5 | 54.509 | 53.128 | 52.984 |  |  | 52.984 |
|  | 5M-10J-V2-P1-S1-D6 | 56.036 | 56.036 |  |  |  | 56.036 |
|  | 5M-10J-V2-P1-S1-D7 | 52.542 | 52.283 |  |  |  | 52.283 |
|  | 5M-10J-V2-P1-S1-D8 | 46.011 | 46.011 |  |  |  | 46.011 |
|  | 5M-10J-V2-P1-S1-D9 | 60.624 | 60.624 |  |  |  | 60.624 |
|  | 5M-10J-V2-P1-S1-D10 | 67.581 | 65.963 | 65.963 |  |  | 65.963 |
| $\begin{aligned} & \text { N} \\ & \text { és } \\ & 0 \\ & \underset{\sim}{c} \end{aligned}$ | 5M-10J-V2-P1-S2-D1 | 59.96 | 58.241 | 58.241 |  |  | 58.241 |
|  | 5M-10J-V2-P1-S2-D2 | 49.491 | 47.83 | 47.83 |  |  | 47.830 |
|  | 5M-10J-V2-P1-S2-D3 | 72.889 | 72.889 |  |  |  | 72.889 |
|  | 5M-10J-V2-P1-S2-D4 | 43.765 | 43.765 |  |  |  | 43.765 |
|  | 5M-10J-V2-P1-S2-D5 | 56.729 | 53.128 | 51.327 | 51.327 |  | 51.327 |
|  | 5M-10J-V2-P1-S2-D6 | 58.373 | 57.567 | 57.567 |  |  | 57.567 |
|  | 5M-10J-V2-P1-S2-D7 | 53.309 | 52.05 | 51.399 | 50.965 |  | 50.965 |
|  | 5M-10J-V2-P1-S2-D8 | 45.642 | 45.081 | 45.081 |  |  | 45.081 |
|  | 5M-10J-V2-P1-S2-D9 | 61.466 | 60.023 | 60.023 |  |  | 60.023 |
|  | 5M-10J-V2-P1-S2-D10 | 71.556 | 67.581 | 67.581 |  |  | 67.581 |
| $\begin{aligned} & \text { No } \\ & \text { eै } \\ & 0 \\ & \text { ? } \end{aligned}$ | 5M-10J-V2-P2-S1-D1 | 61.492 | 61.492 |  |  |  | 61.492 |
|  | 5M-10J-V2-P2-S1-D2 | 52.282 | 51.12 | 50.267 | 48.37 | 48.37 | 48.370 |
|  | 5M-10J-V2-P2-S1-D3 | 62.578 | 60.571 | 60.571 |  |  | 60.571 |
|  | 5M-10J-V2-P2-S1-D4 | 50.691 | 48.284 | 48.284 |  |  | 48.284 |
|  | 5M-10J-V2-P2-S1-D5 | 60.562 | 60.562 |  |  |  | 60.562 |
|  | 5M-10J-V2-P2-S1-D6 | 61.165 | 56.038 | 56.038 |  |  | 56.038 |
|  | 5M-10J-V2-P2-S1-D7 | 62.001 | 59.949 | 59.949 |  |  | 59.949 |
|  | 5M-10J-V2-P2-S1-D8 | 49.608 | 49.608 |  |  |  | 49.608 |
|  | 5M-10J-V2-P2-S1-D9 | 57.987 | 57.987 |  |  |  | 57.987 |
|  | 5M-10J-V2-P2-S1-D10 | 61.183 | 58.636 | 58.636 |  |  | 58.636 |
| $$ | 5M-10J-V2-P2-S2-D1 | 58.241 | 58.241 |  |  |  | 58.241 |
|  | 5M-10J-V2-P2-S2-D2 | 51.308 | 51.308 |  |  |  | 51.308 |
|  | 5M-10J-V2-P2-S2-D3 | 64.134 | 62.055 | 62.055 |  |  | 62.055 |
|  | 5M-10J-V2-P2-S2-D4 | 47.299 | 47.299 |  |  |  | 47.299 |
|  | 5M-10J-V2-P2-S2-D5 | 61.197 | 61.197 |  |  |  | 61.197 |
|  | 5M-10J-V2-P2-S2-D6 | 58.373 | 55.768 | 55.768 |  |  | 55.768 |
|  | 5M-10J-V2-P2-S2-D7 | 63.149 | 62.255 | 62.255 |  |  | 62.255 |
|  | 5M-10J-V2-P2-S2-D8 | 50.713 | 50.713 |  |  |  | 50.713 |
|  | 5M-10J-V2-P2-S2-D9 | 58.336 | 58.336 |  |  |  | 58.336 |
|  | 5M-10J-V2-P2-S2-D10 | 57.902 | 57.902 |  |  |  | 57.902 |

* H is the reputation time

|  |  | H 100 $\mathbf{C}_{\text {max }}$ | H 200 $\mathbf{C}_{\text {max }}$ | H 400 <br> $\mathrm{C}_{\text {max }}$ | H 800 $\mathrm{C}_{\text {max }}$ | H 1600 <br> $\mathbf{C}_{\text {max }}$ | H-Best <br> $\mathbf{C}_{\text {max }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 5M-20J-V1-P1-S1-D1 | 127.859 | 127.859 |  |  |  | 127.859 |
|  | 5M-20J-V1-P1-S1-D2 | 98.466 | 98.378 |  |  |  | 98.378 |
|  | 5M-20J-V1-P1-S1-D3 | 128.175 | 127.571 |  |  |  | 127.571 |
|  | 5M-20J-V1-P1-S1-D4 | 110.342 | 106.338 | 106.076 |  |  | 106.076 |
|  | 5M-20J-V1-P1-S1-D5 | 107.912 | 104.56 | 103.507 | 103.507 |  | 103.507 |
|  | 5M-20J-V1-P1-S1-D6 | 95.208 | 93.69 | 93.581 |  |  | 93.581 |
|  | 5M-20J-V1-P1-S1-D7 | 105.083 | 104.2 |  |  |  | 104.200 |
|  | 5M-20J-V1-P1-S1-D8 | 94.164 | 93.243 |  |  |  | 93.243 |
|  | 5M-20J-V1-P1-S1-D9 | 135.432 | 130.184 | 130.184 |  |  | 130.184 |
|  | 5M-20J-V1-P1-S1-D10 | 104.355 | 104.355 |  |  |  | 104.355 |
| Nहै00on | 5M-20J-V1-P1-S2-D1 | 129.616 | 129.616 |  |  |  | 129.616 |
|  | 5M-20J-V1-P1-S2-D2 | 99.535 | 97.221 | 97.221 |  |  | 97.221 |
|  | 5M-20J-V1-P1-S2-D3 | 129.108 | 126.888 | 126.888 |  |  | 126.888 |
|  | 5M-20J-V1-P1-S2-D4 | 110.277 | 110.277 |  |  |  | 110.277 |
|  | 5M-20J-V1-P1-S2-D5 | 101.432 | 101.432 |  |  |  | 101.432 |
|  | 5M-20J-V1-P1-S2-D6 | 93.731 | 93.731 |  |  |  | 93.731 |
|  | 5M-20J-V1-P1-S2-D7 | 103.776 | 103.776 |  |  |  | 103.776 |
|  | 5M-20J-V1-P1-S2-D8 | 95.422 | 95.181 |  |  |  | 95.181 |
|  | 5M-20J-V1-P1-S2-D9 | 137.491 | 136.854 |  |  |  | 136.854 |
|  | 5M-20J-V1-P1-S2-D10 | 104.399 | 104.399 |  |  |  | 104.399 |
| $\begin{aligned} & \text { N} \\ & \text { eै } \\ & 0 \\ & \text { êc } \end{aligned}$ | 5M-20J-V1-P2-S1-D1 | 107.246 | 107.246 |  |  |  | 107.246 |
|  | 5M-20J-V1-P2-S1-D2 | 97.221 | 91.81 | 91.81 |  |  | 91.810 |
|  | 5M-20J-V1-P2-S1-D3 | 119.879 | 117.195 | 115.433 | 115.433 |  | 115.433 |
|  | 5M-20J-V1-P2-S1-D4 | 115.528 | 113.12 | 113.12 |  |  | 113.120 |
|  | 5M-20J-V1-P2-S1-D5 | 127.2 | 124.83 | 124.442 |  |  | 124.442 |
|  | 5M-20J-V1-P2-S1-D6 | 99.095 | 94.036 | 94.036 |  |  | 94.036 |
|  | 5M-20J-V1-P2-S1-D7 | 101.803 | 101.803 |  |  |  | 101.803 |
|  | 5M-20J-V1-P2-S1-D8 | 143.016 | 143.016 |  |  |  | 143.016 |
|  | 5M-20J-V1-P2-S1-D9 | 132.388 | 132.388 |  |  |  | 132.388 |
|  | 5M-20J-V1-P2-S1-D10 | 120.559 | 119.514 |  |  |  | 119.514 |
|  | 5M-20J-V1-P2-S2-D1 | 107.747 | 107.242 |  |  |  | 107.242 |
|  | 5M-20J-V1-P2-S2-D2 | 94.204 | 94.204 |  |  |  | 94.204 |
|  | 5M-20J-V1-P2-S2-D3 | 117.64 | 117.64 |  |  |  | 117.640 |
|  | 5M-20J-V1-P2-S2-D4 | 114.435 | 114.215 |  |  |  | 114.215 |
|  | 5M-20J-V1-P2-S2-D5 | 121.385 | 121.385 |  |  |  | 121.385 |
|  | 5M-20J-V1-P2-S2-D6 | 99.679 | 95.871 | 94.977 |  |  | 94.977 |
|  | 5M-20J-V1-P2-S2-D7 | 98.371 | 98.371 |  |  |  | 98.371 |
|  | 5M-20J-V1-P2-S2-D8 | 155.772 | 143.553 | 143.553 |  |  | 143.553 |
|  | 5M-20J-V1-P2-S2-D9 | 131.434 | 131.434 |  |  |  | 131.434 |
|  | 5M-20J-V1-P2-S2-D10 | 121.626 | 121.626 |  |  |  | 121.626 |

* H is the reputation time

|  |  | H 100 $\mathbf{C}_{\text {max }}$ | H 200 $\mathbf{C}_{\text {max }}$ | H 400 <br> $\mathbf{C}_{\text {max }}$ | $\begin{gathered} \text { H } 800 \\ \mathbf{C}_{\text {max }} \end{gathered}$ | H 1600 <br> $\mathbf{C}_{\text {max }}$ | H-Best $\mathbf{C}_{\text {max }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 5M-20J-V2-P1-S1-D1 | 114.859 | 113.226 | 113.226 |  |  | 113.226 |
|  | 5M-20J-V2-P1-S1-D2 | 109.78 | 109.78 |  |  |  | 109.780 |
|  | 5M-20J-V2-P1-S1-D3 | 131.936 | 131.936 |  |  |  | 131.936 |
|  | 5M-20J-V2-P1-S1-D4 | 102.601 | 101.51 | 101.51 |  |  | 101.510 |
|  | 5M-20J-V2-P1-S1-D5 | 104.89 | 104.89 |  |  |  | 104.890 |
|  | 5M-20J-V2-P1-S1-D6 | 104.804 | 104.804 |  |  |  | 104.804 |
|  | 5M-20J-V2-P1-S1-D7 | 101.421 | 101.421 |  |  |  | 101.421 |
|  | 5M-20J-V2-P1-S1-D8 | 101.858 | 101.858 |  |  |  | 101.858 |
|  | 5M-20J-V2-P1-S1-D9 | 123.724 | 123.724 |  |  |  | 123.724 |
|  | 5M-20J-V2-P1-S1-D10 | 108.637 | 108.637 |  |  |  | 108.637 |
| $\begin{aligned} & \text { e } \\ & \text { es } \\ & 0 \\ & \stackrel{y}{c} \end{aligned}$ | 5M-20J-V2-P1-S2-D1 | 117.779 | 117.719 |  |  |  | 117.719 |
|  | 5M-20J-V2-P1-S2-D2 | 109.932 | 109.932 |  |  |  | 109.932 |
|  | 5M-20J-V2-P1-S2-D3 | 135.985 | 133.95 | 133.433 |  |  | 133.433 |
|  | 5M-20J-V2-P1-S2-D4 | 101.435 | 101.435 |  |  |  | 101.435 |
|  | 5M-20J-V2-P1-S2-D5 | 106.122 | 106.122 |  |  |  | 106.122 |
|  | 5M-20J-V2-P1-S2-D6 | 105.984 | 105.984 |  |  |  | 105.984 |
|  | 5M-20J-V2-P1-S2-D7 | 99.24 | 99.24 |  |  |  | 99.240 |
|  | 5M-20J-V2-P1-S2-D8 | 102.796 | 102.796 |  |  |  | 102.796 |
|  | 5M-20J-V2-P1-S2-D9 | 124.207 | 124.207 |  |  |  | 124.207 |
|  | 5M-20J-V2-P1-S2-D10 | 109.607 | 109.607 |  |  |  | 109.607 |
|  | 5M-20J-V2-P2-S1-D1 | 110.27 | 107.833 | 107.833 |  |  | 107.833 |
|  | 5M-20J-V2-P2-S1-D2 | 108.423 | 107.381 |  |  |  | 107.381 |
|  | 5M-20J-V2-P2-S1-D3 | 122.874 | 122.874 |  |  |  | 122.874 |
|  | 5M-20J-V2-P2-S1-D4 | 107.75 | 107.689 |  |  |  | 107.689 |
|  | 5M-20J-V2-P2-S1-D5 | 119.121 | 119.121 |  |  |  | 119.121 |
|  | 5M-20J-V2-P2-S1-D6 | 105.828 | 102.968 | 102.968 |  |  | 102.968 |
|  | 5M-20J-V2-P2-S1-D7 | 103.719 | 102.431 | 101.016 | 101.016 |  | 101.016 |
|  | 5M-20J-V2-P2-S1-D8 | 120.088 | 120.088 |  |  |  | 120.088 |
|  | 5M-20J-V2-P2-S1-D9 | 121.139 | 118.777 | 118.777 |  |  | 118.777 |
|  | 5M-20J-V2-P2-S1-D10 | 117.481 | 117.481 |  |  |  | 117.481 |
|  | 5M-20J-V2-P2-S2-D1 | 114.301 | 113.212 |  |  |  | 113.212 |
|  | 5M-20J-V2-P2-S2-D2 | 108.007 | 108.007 |  |  |  | 108.007 |
|  | 5M-20J-V2-P2-S2-D3 | 122.477 | 122.477 |  |  |  | 122.477 |
|  | 5M-20J-V2-P2-S2-D4 | 107.689 | 107.689 |  |  |  | 107.689 |
|  | 5M-20J-V2-P2-S2-D5 | 117.793 | 117.793 |  |  |  | 117.793 |
|  | 5M-20J-V2-P2-S2-D6 | 107.453 | 105.828 | 103.868 | 103.868 |  | 103.868 |
|  | 5M-20J-V2-P2-S2-D7 | 103.719 | 103.719 |  |  |  | 103.719 |
|  | 5M-20J-V2-P2-S2-D8 | 121.496 | 121.496 |  |  |  | 121.496 |
|  | 5M-20J-V2-P2-S2-D9 | 119.383 | 117.212 | 117.212 |  |  | 117.212 |
|  | 5M-20J-V2-P2-S2-D10 | 117.765 | 115.522 | 115.522 |  |  | 115.522 |

* H is the reputation time


## APPENDIX 3 - COMPARISON FOR INITIAL HEURISTIC AND IMPROVED HEURISTIC SOLUTIONS

|  |  | Initial Heuristic C max | Improved Heuristic Cmax | \% Gap |
| :---: | :---: | :---: | :---: | :---: |
|  | 3M-6J-V1-P1-S1-D1 | 104.591 | 46.611 | 124.39\% |
|  | 3M-6J-V1-P1-S1-D2 | 108.263 | 52.265 | 107.14\% |
|  | 3M-6J-V1-P1-S1-D3 | 64.764 | 64.764 | 0.00\% |
|  | 3M-6J-V1-P1-S1-D4 | 67.331 | 67.331 | 0.00\% |
|  | 3M-6J-V1-P1-S1-D5 | 72.091 | 72.091 | 0.00\% |
|  | 3M-6J-V1-P1-S1-D6 | 40.941 | 40.941 | 0.00\% |
|  | 3M-6J-V1-P1-S1-D7 | 44.33 | 44.330 | 0.00\% |
|  | 3M-6J-V1-P1-S1-D8 | 92.278 | 44.693 | 106.47\% |
|  | 3M-6J-V1-P1-S1-D9 | 122.424 | 57.809 | 111.77\% |
|  | 3M-6J-V1-P1-S1-D10 | 188.359 | 56.346 | 234.29\% |
|  | 3M-6J-V1-P1-S2-D1 | 64.798 | 48.342 | 34.04\% |
|  | 3M-6J-V1-P1-S2-D2 | 94.072 | 51.890 | 81.29\% |
|  | 3M-6J-V1-P1-S2-D3 | 62.41 | 62.410 | 0.00\% |
|  | 3M-6J-V1-P1-S2-D4 | 67.331 | 67.331 | 0.00\% |
|  | 3M-6J-V1-P1-S2-D5 | 217.449 | 69.751 | 211.75\% |
|  | 3M-6J-V1-P1-S2-D6 | 71.647 | 44.353 | 61.54\% |
|  | 3M-6J-V1-P1-S2-D7 | 95.939 | 45.254 | 112.00\% |
|  | 3M-6J-V1-P1-S2-D8 | 85.443 | 47.848 | 78.57\% |
|  | 3M-6J-V1-P1-S2-D9 | 223.128 | 57.839 | 285.77\% |
|  | 3M-6J-V1-P1-S2-D10 | 127.461 | 56.664 | 124.94\% |
|  | 3M-6J-V1-P2-S1-D1 | 73.027 | 49.370 | 47.92\% |
|  | 3M-6J-V1-P2-S1-D2 | 158.661 | 65.991 | 140.43\% |
|  | 3M-6J-V1-P2-S1-D3 | 123.976 | 55.438 | 123.63\% |
|  | 3M-6J-V1-P2-S1-D4 | 93.387 | 72.422 | 28.95\% |
|  | 3M-6J-V1-P2-S1-D5 | 75.238 | 52.066 | 44.51\% |
|  | 3M-6J-V1-P2-S1-D6 | 46.47 | 46.470 | 0.00\% |
|  | 3M-6J-V1-P2-S1-D7 | 66.495 | 50.795 | 30.91\% |
|  | 3M-6J-V1-P2-S1-D8 | 48.695 | 48.695 | 0.00\% |
|  | 3M-6J-V1-P2-S1-D9 | 83.421 | 56.346 | 48.05\% |
|  | 3M-6J-V1-P2-S1-D10 | 99.729 | 49.493 | 101.50\% |
|  | 3M-6J-V1-P2-S2-D1 | 51.427 | 51.427 | 0.00\% |
|  | 3M-6J-V1-P2-S2-D2 | 94.072 | 65.331 | 43.99\% |
|  | 3M-6J-V1-P2-S2-D3 | 92.397 | 55.174 | 67.46\% |
|  | 3M-6J-V1-P2-S2-D4 | 72.422 | 72.422 | 0.00\% |
|  | 3M-6J-V1-P2-S2-D5 | 78.766 | 54.077 | 45.66\% |
|  | 3M-6J-V1-P2-S2-D6 | 92.96 | 46.400 | 100.34\% |
|  | 3M-6J-V1-P2-S2-D7 | 77.424 | 49.952 | 55.00\% |
|  | 3M-6J-V1-P2-S2-D8 | 50.84 | 50.840 | 0.00\% |
|  | 3M-6J-V1-P2-S2-D9 | 165.865 | 56.346 | 194.37\% |
|  | 3M-6J-V1-P2-S2-D10 | 62.708 | 49.109 | 27.69\% |


|  |  | $\begin{gathered} \text { Initial } \\ \text { Heuristic C }{ }_{\text {max }} \end{gathered}$ | Improvement Heuristic C ${ }_{\text {max }}$ | \% Gap |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { n } \\ & \text { 官 } \\ & 0 \\ & \text { y } \end{aligned}$ | 3M-6J-V2-P1-S1-D1 | 77.647 | 46.686 | 66.32\% |
|  | 3M-6J-V2-P1-S1-D2 | 40.664 | 40.664 | 0.00\% |
|  | 3M-6J-V2-P1-S1-D3 | 108.371 | 67.851 | 59.72\% |
|  | 3M-6J-V2-P1-S1-D4 | 94.638 | 53.590 | 76.60\% |
|  | 3M-6J-V2-P1-S1-D5 | 96.246 | 62.388 | 54.27\% |
|  | 3M-6J-V2-P1-S1-D6 | 80.901 | 42.995 | 88.16\% |
|  | 3M-6J-V2-P1-S1-D7 | 84.26 | 44.407 | 89.74\% |
|  | 3M-6J-V2-P1-S1-D8 | 78.984 | 41.749 | 89.19\% |
|  | 3M-6J-V2-P1-S1-D9 | 104.507 | 57.952 | 80.33\% |
|  | 3M-6J-V2-P1-S1-D10 | 113.939 | 64.717 | 76.06\% |
| $\begin{aligned} & 0 \\ & \text { b } \\ & 0 \\ & 0 \\ & \text { y } \end{aligned}$ | 3M-6J-V2-P1-S2-D1 | 82.997 | 48.225 | 72.10\% |
|  | 3M-6J-V2-P1-S2-D2 | 72.395 | 39.979 | 81.08\% |
|  | 3M-6J-V2-P1-S2-D3 | 97.761 | 66.881 | 46.17\% |
|  | 3M-6J-V2-P1-S2-D4 | 79.815 | 54.730 | 45.83\% |
|  | 3M-6J-V2-P1-S2-D5 | 103.979 | 62.388 | 66.67\% |
|  | 3M-6J-V2-P1-S2-D6 | 56.157 | 43.873 | 28.00\% |
|  | 3M-6J-V2-P1-S2-D7 | 92.698 | 44.885 | 106.52\% |
|  | 3M-6J-V2-P1-S2-D8 | 80.066 | 42.618 | 87.87\% |
|  | 3M-6J-V2-P1-S2-D9 | 104.507 | 57.952 | 80.33\% |
|  | 3M-6J-V2-P1-S2-D10 | 112.116 | 62.894 | 78.26\% |
| $\begin{aligned} & \text { N } \\ & \text { Be } \\ & 0 \\ & \text { 合 } \end{aligned}$ | 3M-6J-V2-P2-S1-D1 | 70.482 | 50.079 | 40.74\% |
|  | 3M-6J-V2-P2-S1-D2 | 48.624 | 48.624 | 0.00\% |
|  | 3M-6J-V2-P2-S1-D3 | 119.111 | 58.579 | 103.33\% |
|  | 3M-6J-V2-P2-S1-D4 | 91.127 | 54.910 | 65.96\% |
|  | 3M-6J-V2-P2-S1-D5 | 85.432 | 56.336 | 51.65\% |
|  | 3M-6J-V2-P2-S1-D6 | 46.505 | 46.505 | 0.00\% |
|  | 3M-6J-V2-P2-S1-D7 | 85.737 | 51.077 | 67.86\% |
|  | 3M-6J-V2-P2-S1-D8 | 82.234 | 46.967 | 75.09\% |
|  | 3M-6J-V2-P2-S1-D9 | 78.934 | 54.954 | 43.64\% |
|  | 3M-6J-V2-P2-S1-D10 | 55.759 | 55.759 | 0.00\% |
| $$ | 3M-6J-V2-P2-S2-D1 | 68.627 | 49.411 | 38.89\% |
|  | 3M-6J-V2-P2-S2-D2 | 70.048 | 48.624 | 44.06\% |
|  | 3M-6J-V2-P2-S2-D3 | 120.941 | 58.158 | 107.95\% |
|  | 3M-6J-V2-P2-S2-D4 | 100.51 | 55.182 | 82.14\% |
|  | 3M-6J-V2-P2-S2-D5 | 89.584 | 55.152 | 62.43\% |
|  | 3M-6J-V2-P2-S2-D6 | 47.383 | 47.383 | 0.00\% |
|  | 3M-6J-V2-P2-S2-D7 | 67.495 | 51.077 | 32.14\% |
|  | 3M-6J-V2-P2-S2-D8 | 75.381 | 47.970 | 57.14\% |
|  | 3M-6J-V2-P2-S2-D9 | 55.857 | 55.857 | 0.00\% |
|  | 3M-6J-V2-P2-S2-D10 | 108.573 | 55.932 | 94.12\% |


|  |  | Initial Heuristic C $_{\text {max }}$ | Improvement Heuristic Cmax | \% Gap |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { a } \\ & \stackrel{\rightharpoonup}{0} \\ & 0 \\ & \text { y } \end{aligned}$ | 3M-12J-V1-P1-S1-D1 | 317.973 | 116.857 | 172.10\% |
|  | 3M-12J-V1-P1-S1-D2 | 114.188 | 76.418 | 49.43\% |
|  | 3M-12J-V1-P1-S1-D3 | 139.285 | 115.152 | 20.96\% |
|  | 3M-12J-V1-P1-S1-D4 | 117.771 | 84.496 | 39.38\% |
|  | 3M-12J-V1-P1-S1-D5 | 250.841 | 110.132 | 127.76\% |
|  | 3M-12J-V1-P1-S1-D6 | 143.652 | 91.070 | 57.74\% |
|  | 3M-12J-V1-P1-S1-D7 | 145.666 | 145.666 | 0.00\% |
|  | 3M-12J-V1-P1-S1-D8 | 109.474 | 87.579 | 25.00\% |
|  | 3M-12J-V1-P1-S1-D9 | 199.035 | 96.074 | 107.17\% |
|  | 3M-12J-V1-P1-S1-D10 | 175.169 | 125.334 | 39.76\% |
| $\begin{aligned} & 9 \\ & \stackrel{y}{3} \\ & 0 \\ & \frac{y}{4} \end{aligned}$ | 3M-12J-V1-P1-S2-D1 | 193.055 | 117.347 | 64.52\% |
|  | 3M-12J-V1-P1-S2-D2 | 86.08 | 78.681 | 9.40\% |
|  | 3M-12J-V1-P1-S2-D3 | 161.784 | 114.990 | 40.69\% |
|  | 3M-12J-V1-P1-S2-D4 | 121.723 | 85.365 | 42.59\% |
|  | 3M-12J-V1-P1-S2-D5 | 147.613 | 111.300 | 32.63\% |
|  | 3M-12J-V1-P1-S2-D6 | 135.954 | 89.868 | 51.28\% |
|  | 3M-12J-V1-P1-S2-D7 | 303.258 | 145.117 | 108.97\% |
|  | 3M-12J-V1-P1-S2-D8 | 133.991 | 88.130 | 52.04\% |
|  | 3M-12J-V1-P1-S2-D9 | 151.075 | 98.163 | 53.90\% |
|  | 3M-12J-V1-P1-S2-D10 | 136.001 | 124.430 | 9.30\% |
|  | 3M-12J-V1-P2-S1-D1 | 114.834 | 100.480 | 14.29\% |
|  | 3M-12J-V1-P2-S1-D2 | 106.283 | 81.270 | 30.78\% |
|  | 3M-12J-V1-P2-S1-D3 | 170.238 | 105.238 | 61.76\% |
|  | 3M-12J-V1-P2-S1-D4 | 157.91 | 92.807 | 70.15\% |
|  | 3M-12J-V1-P2-S1-D5 | 157.113 | 105.229 | 49.31\% |
|  | 3M-12J-V1-P2-S1-D6 | 203.184 | 95.135 | 113.57\% |
|  | 3M-12J-V1-P2-S1-D7 | 261.116 | 145.516 | 79.44\% |
|  | 3M-12J-V1-P2-S1-D8 | 147.008 | 96.524 | 52.30\% |
|  | 3M-12J-V1-P2-S1-D9 | 107.91 | 94.682 | 13.97\% |
|  | 3M-12J-V1-P2-S1-D10 | 333.282 | 161.433 | 106.45\% |
| $\begin{aligned} & \text { IT } \\ & \text { Be } \\ & 0 \\ & \frac{8}{3} \end{aligned}$ | 3M-12J-V1-P2-S2-D1 | 101.145 | 101.145 | 0.00\% |
|  | 3M-12J-V1-P2-S2-D2 | 99.256 | 80.810 | 22.83\% |
|  | 3M-12J-V1-P2-S2-D3 | 132.026 | 105.053 | 25.68\% |
|  | 3M-12J-V1-P2-S2-D4 | 189.77 | 91.507 | 107.38\% |
|  | 3M-12J-V1-P2-S2-D5 | 205.324 | 106.726 | 92.38\% |
|  | 3M-12J-V1-P2-S2-D6 | 131.726 | 93.509 | 40.87\% |
|  | 3M-12J-V1-P2-S2-D7 | 173.5 | 145.516 | 19.23\% |
|  | 3M-12J-V1-P2-S2-D8 | 125.113 | 96.333 | 29.88\% |
|  | 3M-12J-V1-P2-S2-D9 | 131.891 | 96.074 | 37.28\% |
|  | 3M-12J-V1-P2-S2-D10 | 267.32 | 162.798 | 64.20\% |


|  |  | Initial Heuristic C $_{\text {max }}$ | Improvement Heuristic C ${ }_{\text {max }}$ | \% Gap |
| :---: | :---: | :---: | :---: | :---: |
| 2 <br> 6 <br> 0 <br> 0 <br>  | 3M-12J-V2-P1-S1-D1 | 158.077 | 111.744 | 41.46\% |
|  | 3M-12J-V2-P1-S1-D2 | 178.581 | 92.181 | 93.73\% |
|  | 3M-12J-V2-P1-S1-D3 | 241.227 | 124.146 | 94.31\% |
|  | 3M-12J-V2-P1-S1-D4 | 137.468 | 90.554 | 51.81\% |
|  | 3M-12J-V2-P1-S1-D5 | 161.788 | 105.784 | 52.94\% |
|  | 3M-12J-V2-P1-S1-D6 | 96.586 | 96.586 | 0.00\% |
|  | 3M-12J-V2-P1-S1-D7 | 189.26 | 110.194 | 71.75\% |
|  | 3M-12J-V2-P1-S1-D8 | 128.53 | 89.255 | 44.00\% |
|  | 3M-12J-V2-P1-S1-D9 | 130.867 | 106.993 | 22.31\% |
|  | 3M-12J-V2-P1-S1-D10 | 160 | 111.310 | 43.74\% |
| $\begin{aligned} & \pm \\ & \stackrel{\rightharpoonup}{3} \\ & \stackrel{0}{c} \\ & \underset{\sim}{3} \end{aligned}$ | 3M-12J-V2-P1-S2-D1 | 133.954 | 110.836 | 20.86\% |
|  | 3M-12J-V2-P1-S2-D2 | 91.998 | 91.998 | 0.00\% |
|  | 3M-12J-V2-P1-S2-D3 | 188.742 | 127.174 | 48.41\% |
|  | 3M-12J-V2-P1-S2-D4 | 177.835 | 91.732 | 93.86\% |
|  | 3M-12J-V2-P1-S2-D5 | 141.95 | 106.821 | 32.89\% |
|  | 3M-12J-V2-P1-S2-D6 | 142.733 | 97.196 | 46.85\% |
|  | 3M-12J-V2-P1-S2-D7 | 168.78 | 110.224 | 53.12\% |
|  | 3M-12J-V2-P1-S2-D8 | 155.911 | 88.241 | 76.69\% |
|  | 3M-12J-V2-P1-S2-D9 | 146.284 | 107.877 | 35.60\% |
|  | 3M-12J-V2-P1-S2-D10 | 231.564 | 110.316 | 109.91\% |
| $\begin{aligned} & \text { n } \\ & \text { Bै } \\ & 0 \\ & \text { en } \end{aligned}$ | 3M-12J-V2-P2-S1-D1 | 194.709 | 106.521 | 82.79\% |
|  | 3M-12J-V2-P2-S1-D2 | 139.141 | 96.529 | 44.14\% |
|  | 3M-12J-V2-P2-S1-D3 | 163.899 | 114.016 | 43.75\% |
|  | 3M-12J-V2-P2-S1-D4 | 170.442 | 97.100 | 75.53\% |
|  | 3M-12J-V2-P2-S1-D5 | 179.92 | 109.200 | 64.76\% |
|  | 3M-12J-V2-P2-S1-D6 | 191.777 | 101.969 | 88.07\% |
|  | 3M-12J-V2-P2-S1-D7 | 206.672 | 115.325 | $79.21 \%$ |
|  | 3M-12J-V2-P2-S1-D8 | 117.44 | 98.795 | 18.87\% |
|  | 3M-12J-V2-P2-S1-D9 | 161.816 | 106.109 | 52.50\% |
|  | 3M-12J-V2-P2-S1-D10 | 126.027 | 126.027 | 0.00\% |
| $\begin{aligned} & 0 \\ & \stackrel{0}{3} \\ & 0 \\ & \text { en } \end{aligned}$ | 3M-12J-V2-P2-S2-D1 | 203.735 | 107.391 | 89.71\% |
|  | 3M-12J-V2-P2-S2-D2 | 115.214 | 95.791 | 20.28\% |
|  | 3M-12J-V2-P2-S2-D3 | 151.689 | 116.229 | 30.51\% |
|  | 3M-12J-V2-P2-S2-D4 | 127.831 | 99.115 | 28.97\% |
|  | 3M-12J-V2-P2-S2-D5 | 217.36 | 108.160 | 100.96\% |
|  | 3M-12J-V2-P2-S2-D6 | 148.546 | 100.879 | 47.25\% |
|  | 3M-12J-V2-P2-S2-D7 | 182.693 | 116.467 | 56.86\% |
|  | 3M-12J-V2-P2-S2-D8 | 211.978 | 97.369 | 117.71\% |
|  | 3M-12J-V2-P2-S2-D9 | 165.09 | 104.714 | 57.66\% |
|  | 3M-12J-V2-P2-S2-D10 | 299.028 | 126.697 | 136.02\% |


|  |  | Initial Heuristic C $_{\text {max }}$ | Improvement Heuristic C ${ }_{\text {max }}$ | \% Gap |
| :---: | :---: | :---: | :---: | :---: |
| 令 | 5M-10J-V1-P1-S1-D1 | 174.128 | 58.964 | 195.31\% |
|  | 5M-10J-V1-P1-S1-D2 | 108.263 | 45.714 | 136.83\% |
|  | 5M-10J-V1-P1-S1-D3 | 124.323 | 68.520 | 81.44\% |
|  | 5M-10J-V1-P1-S1-D4 | 180.729 | 43.072 | 319.60\% |
|  | 5M-10J-V1-P1-S1-D5 | 98.779 | 57.905 | 70.59\% |
|  | 5M-10J-V1-P1-S1-D6 | 178.199 | 59.801 | 197.99\% |
|  | 5M-10J-V1-P1-S1-D7 | 212.677 | 55.545 | 282.89\% |
|  | 5M-10J-V1-P1-S1-D8 | 67.769 | 46.415 | 46.01\% |
|  | 5M-10J-V1-P1-S1-D9 | 100.543 | 62.859 | 59.95\% |
|  | 5M-10J-V1-P1-S1-D10 | 168.123 | 67.651 | 148.52\% |
| $\begin{aligned} & \infty \\ & \stackrel{\infty}{3} \\ & 0 \\ & \underset{\sim}{2} \end{aligned}$ | 5M-10J-V1-P1-S2-D1 | 58.936 | 58.936 | 0.00\% |
|  | 5M-10J-V1-P1-S2-D2 | 106.396 | 44.798 | 137.50\% |
|  | 5M-10J-V1-P1-S2-D3 | 126.347 | 65.303 | 93.48\% |
|  | 5M-10J-V1-P1-S2-D4 | 138.084 | 44.339 | 211.43\% |
|  | 5M-10J-V1-P1-S2-D5 | 98.647 | 60.175 | 63.93\% |
|  | 5M-10J-V1-P1-S2-D6 | 112.253 | 60.163 | 86.58\% |
|  | 5M-10J-V1-P1-S2-D7 | 57.459 | 57.459 | 0.00\% |
|  | 5M-10J-V1-P1-S2-D8 | 85.824 | 47.237 | 81.69\% |
|  | 5M-10J-V1-P1-S2-D9 | 117.315 | 61.792 | 89.85\% |
|  | 5M-10J-V1-P1-S2-D10 | 109.934 | 68.000 | 61.67\% |
| $\begin{aligned} & \stackrel{\rightharpoonup}{2} \\ & \stackrel{\rightharpoonup}{3} \\ & \stackrel{y}{c} \end{aligned}$ | 5M-10J-V1-P2-S1-D1 | 99.568 | 62.137 | 60.24\% |
|  | 5M-10J-V1-P2-S1-D2 | 169.86 | 44.021 | 285.86\% |
|  | 5M-10J-V1-P2-S1-D3 | 127.533 | 60.601 | 110.45\% |
|  | 5M-10J-V1-P2-S1-D4 | 116.311 | 49.664 | 134.20\% |
|  | 5M-10J-V1-P2-S1-D5 | 63.979 | 63.979 | 0.00\% |
|  | 5M-10J-V1-P2-S1-D6 | 329.571 | 63.232 | 421.21\% |
|  | 5M-10J-V1-P2-S1-D7 | 100.681 | 82.472 | 22.08\% |
|  | 5M-10J-V1-P2-S1-D8 | 76.191 | 55.173 | 38.09\% |
|  | 5M-10J-V1-P2-S1-D9 | 123.964 | 57.860 | 114.25\% |
|  | 5M-10J-V1-P2-S1-D10 | 154.632 | 69.334 | 123.02\% |
|  | 5M-10J-V1-P2-S2-D1 | 174.128 | 63.253 | 175.29\% |
|  | 5M-10J-V1-P2-S2-D2 | 76.53 | 46.554 | 64.39\% |
|  | 5M-10J-V1-P2-S2-D3 | 120.714 | 62.410 | 93.42\% |
|  | 5M-10J-V1-P2-S2-D4 | 108.947 | 49.983 | 117.97\% |
|  | 5M-10J-V1-P2-S2-D5 | 155.377 | 65.011 | 139.00\% |
|  | 5M-10J-V1-P2-S2-D6 | 148.974 | 63.462 | 134.75\% |
|  | 5M-10J-V1-P2-S2-D7 | 105.218 | 80.645 | 30.47\% |
|  | 5M-10J-V1-P2-S2-D8 | 73.442 | 54.557 | 34.62\% |
|  | 5M-10J-V1-P2-S2-D9 | 149.752 | 58.210 | 157.26\% |
|  | 5M-10J-V1-P2-S2-D10 | 110.667 | 66.443 | 66.56\% |


|  |  | Initial Heuristic $\mathbf{C}_{\text {max }}$ | Improvement Heuristic C ${ }_{\text {max }}$ | \% Gap |
| :---: | :---: | :---: | :---: | :---: |
|  | 5M-10J-V2-P1-S1-D1 | 76.019 | 56.132 | 35.43\% |
|  | 5M-10J-V2-P1-S1-D2 | 49.491 | 49.491 | 0.00\% |
|  | 5M-10J-V2-P1-S1-D3 | 150.24 | 70.920 | 111.84\% |
|  | 5M-10J-V2-P1-S1-D4 | 78.465 | 45.335 | 73.08\% |
|  | 5M-10J-V2-P1-S1-D5 | 112.457 | 52.984 | 112.25\% |
|  | 5M-10J-V2-P1-S1-D6 | 123.703 | 56.036 | 120.76\% |
|  | 5M-10J-V2-P1-S1-D7 | 94.315 | 52.283 | 80.39\% |
|  | 5M-10J-V2-P1-S1-D8 | 63.898 | 46.011 | 38.88\% |
|  | 5M-10J-V2-P1-S1-D9 | 96.258 | 60.624 | 58.78\% |
|  | 5M-10J-V2-P1-S1-D10 | 105.783 | 65.963 | 60.37\% |
| $\begin{aligned} & \text { Ñ } \\ & \text { eै } \\ & \text { ồ } \end{aligned}$ | 5M-10J-V2-P1-S2-D1 | 105.904 | 58.241 | 81.84\% |
|  | 5M-10J-V2-P1-S2-D2 | 94.107 | 47.830 | 96.75\% |
|  | 5M-10J-V2-P1-S2-D3 | 145.779 | 72.889 | 100.00\% |
|  | 5M-10J-V2-P1-S2-D4 | 92.203 | 43.765 | 110.68\% |
|  | 5M-10J-V2-P1-S2-D5 | 51.327 | 51.327 | 0.00\% |
|  | 5M-10J-V2-P1-S2-D6 | 93.546 | 57.567 | 62.50\% |
|  | 5M-10J-V2-P1-S2-D7 | 79.928 | 50.965 | 56.83\% |
|  | 5M-10J-V2-P1-S2-D8 | 105.509 | 45.081 | 134.04\% |
|  | 5M-10J-V2-P1-S2-D9 | 127.57 | 60.023 | 112.54\% |
|  | 5M-10J-V2-P1-S2-D10 | 152.9 | 67.581 | 126.25\% |
|  | 5M-10J-V2-P2-S1-D1 | 133.233 | 61.492 | 116.67\% |
|  | 5M-10J-V2-P2-S1-D2 | 119.139 | 48.370 | 146.31\% |
|  | 5M-10J-V2-P2-S1-D3 | 146.974 | 60.571 | 142.65\% |
|  | 5M-10J-V2-P2-S1-D4 | 73.654 | 48.284 | 52.54\% |
|  | 5M-10J-V2-P2-S1-D5 | 184.714 | 60.562 | 205.00\% |
|  | 5M-10J-V2-P2-S1-D6 | 135.424 | 56.038 | 141.66\% |
|  | 5M-10J-V2-P2-S1-D7 | 90.808 | 59.949 | 51.48\% |
|  | 5M-10J-V2-P2-S1-D8 | 71.881 | 49.608 | 44.90\% |
|  | 5M-10J-V2-P2-S1-D9 | 162.362 | 57.987 | 180.00\% |
|  | 5M-10J-V2-P2-S1-D10 | 126.217 | 58.636 | 115.26\% |
|  | 5M-10J-V2-P2-S2-D1 | 111.822 | 58.241 | 92.00\% |
|  | 5M-10J-V2-P2-S2-D2 | 75.153 | 51.308 | 46.47\% |
|  | 5M-10J-V2-P2-S2-D3 | 115.062 | 62.055 | 85.42\% |
|  | 5M-10J-V2-P2-S2-D4 | 113.309 | 47.299 | 139.56\% |
|  | 5M-10J-V2-P2-S2-D5 | 222.86 | 61.197 | 264.17\% |
|  | 5M-10J-V2-P2-S2-D6 | 55.768 | 55.768 | 0.00\% |
|  | 5M-10J-V2-P2-S2-D7 | 83.007 | 62.255 | 33.33\% |
|  | 5M-10J-V2-P2-S2-D8 | 80.127 | 50.713 | 58.00\% |
|  | 5M-10J-V2-P2-S2-D9 | 125.823 | 58.336 | 115.69\% |
|  | 5M-10J-V2-P2-S2-D10 | 103.246 | 57.902 | 78.31\% |


|  |  | Initial Heuristic C max $_{\text {max }}$ | Improvement Heuristic C ${ }_{\text {max }}$ | \% Gap |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { Na } \\ & \text { eै } \\ & 0 \\ & \text { eै } \end{aligned}$ | 5M-20J-V1-P1-S1-D1 | 187.637 | 127.859 | 46.75\% |
|  | 5M-20J-V1-P1-S1-D2 | 124.723 | 98.378 | 26.78\% |
|  | 5M-20J-V1-P1-S1-D3 | 267.439 | 127.571 | 109.64\% |
|  | 5M-20J-V1-P1-S1-D4 | 131.5 | 106.076 | 23.97\% |
|  | 5M-20J-V1-P1-S1-D5 | 211.12 | 103.507 | 103.97\% |
|  | 5M-20J-V1-P1-S1-D6 | 105.875 | 93.581 | 13.14\% |
|  | 5M-20J-V1-P1-S1-D7 | 147.483 | 104.200 | 41.54\% |
|  | 5M-20J-V1-P1-S1-D8 | 129.874 | 93.243 | 39.29\% |
|  | 5M-20J-V1-P1-S1-D9 | 228.256 | 130.184 | 75.33\% |
|  | 5M-20J-V1-P1-S1-D10 | 192.696 | 104.355 | 84.65\% |
| $\begin{aligned} & \text { Ǹ } \\ & \text { eै } \\ & 0 \\ & \underset{\sim}{c} \end{aligned}$ | 5M-20J-V1-P1-S2-D1 | 273.777 | 129.616 | 111.22\% |
|  | 5M-20J-V1-P1-S2-D2 | 181.71 | 97.221 | 86.90\% |
|  | 5M-20J-V1-P1-S2-D3 | 171.045 | 126.888 | 34.80\% |
|  | 5M-20J-V1-P1-S2-D4 | 164.102 | 110.277 | 48.81\% |
|  | 5M-20J-V1-P1-S2-D5 | 229.037 | 101.432 | 125.80\% |
|  | 5M-20J-V1-P1-S2-D6 | 114.369 | 93.731 | 22.02\% |
|  | 5M-20J-V1-P1-S2-D7 | 134.906 | 103.776 | 30.00\% |
|  | 5M-20J-V1-P1-S2-D8 | 138.835 | 95.181 | 45.86\% |
|  | 5M-20J-V1-P1-S2-D9 | 250.673 | 136.854 | 83.17\% |
|  | 5M-20J-V1-P1-S2-D10 | 146.755 | 104.399 | 40.57\% |
| $\begin{aligned} & \text { N } \\ & \text { Sै } \\ & 0 \\ & \text { env } \end{aligned}$ | 5M-20J-V1-P2-S1-D1 | 280.819 | 107.246 | 161.85\% |
|  | 5M-20J-V1-P2-S1-D2 | 113.839 | 91.810 | 23.99\% |
|  | 5M-20J-V1-P2-S1-D3 | 155.085 | 115.433 | 34.35\% |
|  | 5M-20J-V1-P2-S1-D4 | 207.366 | 113.120 | 83.32\% |
|  | 5M-20J-V1-P2-S1-D5 | 239.713 | 124.442 | 92.63\% |
|  | 5M-20J-V1-P2-S1-D6 | 140.889 | 94.036 | 49.82\% |
|  | 5M-20J-V1-P2-S1-D7 | 248.609 | 101.803 | 144.21\% |
|  | 5M-20J-V1-P2-S1-D8 | 231.55 | 143.016 | 61.90\% |
|  | 5M-20J-V1-P2-S1-D9 | 234.413 | 132.388 | 77.07\% |
|  | 5M-20J-V1-P2-S1-D10 | 191.222 | 119.514 | 60.00\% |
|  | 5M-20J-V1-P2-S2-D1 | 185.246 | 107.242 | 72.74\% |
|  | 5M-20J-V1-P2-S2-D2 | 210.645 | 94.204 | 123.61\% |
|  | 5M-20J-V1-P2-S2-D3 | 150.56 | 117.640 | 27.98\% |
|  | 5M-20J-V1-P2-S2-D4 | 334.83 | 114.215 | 193.16\% |
|  | 5M-20J-V1-P2-S2-D5 | 177.348 | 121.385 | 46.10\% |
|  | 5M-20J-V1-P2-S2-D6 | 171.735 | 94.977 | 80.82\% |
|  | 5M-20J-V1-P2-S2-D7 | 261.129 | 98.371 | 165.45\% |
|  | 5M-20J-V1-P2-S2-D8 | 195.059 | 143.553 | 35.88\% |
|  | 5M-20J-V1-P2-S2-D9 | 219.509 | 131.434 | 67.01\% |
|  | 5M-20J-V1-P2-S2-D10 | 206.673 | 121.626 | 69.93\% |


|  |  | Initial Heuristic C $_{\text {max }}$ | Improvement Heuristic C ${ }_{\text {max }}$ | \% Gap |
| :---: | :---: | :---: | :---: | :---: |
|  | 5M-20J-V2-P1-S1-D1 | 224.284 | 113.226 | 98.09\% |
|  | 5M-20J-V2-P1-S1-D2 | 189.455 | 109.780 | 72.58\% |
|  | 5M-20J-V2-P1-S1-D3 | 301.136 | 131.936 | 128.24\% |
|  | 5M-20J-V2-P1-S1-D4 | 192.872 | 101.510 | 90.00\% |
|  | 5M-20J-V2-P1-S1-D5 | 198.587 | 104.890 | 89.33\% |
|  | 5M-20J-V2-P1-S1-D6 | 132.876 | 104.804 | 26.79\% |
|  | 5M-20J-V2-P1-S1-D7 | 140.624 | 101.421 | 38.65\% |
|  | 5M-20J-V2-P1-S1-D8 | 176.79 | 101.858 | 73.57\% |
|  | 5M-20J-V2-P1-S1-D9 | 228.692 | 123.724 | 84.84\% |
|  | 5M-20J-V2-P1-S1-D10 | 192.23 | 108.637 | 76.95\% |
| $\begin{aligned} & \text { en } \\ & \text { eै } \\ & 0 \\ & \underset{\sim}{c} \end{aligned}$ | 5M-20J-V2-P1-S2-D1 | 171.387 | 117.719 | 45.59\% |
|  | 5M-20J-V2-P1-S2-D2 | 177.89 | 109.932 | 61.82\% |
|  | 5M-20J-V2-P1-S2-D3 | 180.279 | 133.433 | 35.11\% |
|  | 5M-20J-V2-P1-S2-D4 | 177.22 | 101.435 | 74.71\% |
|  | 5M-20J-V2-P1-S2-D5 | 203.045 | 106.122 | 91.33\% |
|  | 5M-20J-V2-P1-S2-D6 | 150.02 | 105.984 | 41.55\% |
|  | 5M-20J-V2-P1-S2-D7 | 127.498 | 99.240 | 28.47\% |
|  | 5M-20J-V2-P1-S2-D8 | 145.651 | 102.796 | 41.69\% |
|  | 5M-20J-V2-P1-S2-D9 | 221.583 | 124.207 | 78.40\% |
|  | 5M-20J-V2-P1-S2-D10 | 219.214 | 109.607 | 100.00\% |
| $\begin{aligned} & \text { en } \\ & \text { 尚 } \\ & 0 \\ & \end{aligned}$ | 5M-20J-V2-P2-S1-D1 | 148.98 | 107.833 | 38.16\% |
|  | 5M-20J-V2-P2-S1-D2 | 216.866 | 107.381 | 101.96\% |
|  | 5M-20J-V2-P2-S1-D3 | 206.465 | 122.874 | 68.03\% |
|  | 5M-20J-V2-P2-S1-D4 | 198.166 | 107.689 | 84.02\% |
|  | 5M-20J-V2-P2-S1-D5 | 155.272 | 119.121 | 30.35\% |
|  | 5M-20J-V2-P2-S1-D6 | 242.388 | 102.968 | 135.40\% |
|  | 5M-20J-V2-P2-S1-D7 | 152.526 | 101.016 | 50.99\% |
|  | 5M-20J-V2-P2-S1-D8 | 188.395 | 120.088 | 56.88\% |
|  | 5M-20J-V2-P2-S1-D9 | 195.063 | 118.777 | 64.23\% |
|  | 5M-20J-V2-P2-S1-D10 | 159.774 | 117.481 | 36.00\% |
| $$ | 5M-20J-V2-P2-S2-D1 | 211.831 | 113.212 | 87.11\% |
|  | 5M-20J-V2-P2-S2-D2 | 190.783 | 108.007 | 76.64\% |
|  | 5M-20J-V2-P2-S2-D3 | 253.579 | 122.477 | 107.04\% |
|  | 5M-20J-V2-P2-S2-D4 | 169.478 | 107.689 | 57.38\% |
|  | 5M-20J-V2-P2-S2-D5 | 194.394 | 117.793 | 65.03\% |
|  | 5M-20J-V2-P2-S2-D6 | 145.041 | 103.868 | 39.64\% |
|  | 5M-20J-V2-P2-S2-D7 | 157.816 | 103.719 | 52.16\% |
|  | 5M-20J-V2-P2-S2-D8 | 206.776 | 121.496 | 70.19\% |
|  | 5M-20J-V2-P2-S2-D9 | 176.904 | 117.212 | 50.93\% |
|  | 5M-20J-V2-P2-S2-D10 | 185.059 | 115.522 | 60.19\% |

